## Supplement to:

Apollo 16 Lunar Surface Procedures

(Final)

(March 16, 1972)

April 7, 1972

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#### SUPPLEMENT TO

APOLLO 16

LUNAR SURFACE PROCEDURES

April 7, 1972

APPROVED BY:

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# Supplement to Apollo 16 Lunar Surface Procedures (Final) (March 16, 1972)

## Make the following changes:

1. Page v add figure numbers and titles and page numbers.

4.2-1	Walking Traverse Map
4.2-2	EVA 1 - Walking Summary Timeline
4.2-3	EVA 1 - Walking Traverse Constraint Data
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2. Page vi add table numbers and titles and page numbers.

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4.6-7	EVA 3 - 55 Minute Late Calculated Data
4.6-8	EVA 3 - 55 Minute Late Input Data

3. Insert Sections: 4.0 through 4.6

- 4. Replace the following pages with new pages herein attached: 70/71, 89/90, 91/92, 111/112, 121/122, 126/127, 164/165, 204/205, 206/207
- 5. Make the following additions, deletions or corrections as shown below:

<u>Page</u>	Location	Category	Detail of Change
16	Foot note	Correction	Dociment should be document "CDR - LCRU covers open (100%)" "CDR - LCRU Power Sw - External" "(1) Cap Com - Advise LMP to change
86	0 + 23	Add	
86	0 + 24	Add	
90	1 + 15	Add	
90	1 + 20	Add	DAC to 12 fps" at Station 4, "if slope NG for NAV update Park Heading 180°"
96	2 + 22	Add	<pre> Gyro "(If Nav Update)" Station 8. "If update not required advise CDR Park Heading</pre>
106	3 + 52	Add	
128	0 + 21	Add	180°." UNPACK "(Either Crewman)" Gyro "(If Nav Update)"
147	3 + 34	Add	
153 153 155	4 + 38 4 + 42 4 + 58	Correction Add Correction	LMP should by LPM "(1) Cap Com - Advise CDR to lower visor" LMP should be LPM
155	5 + 02	Add	"(1) Cap Com - Advise CDR to lower visor" CMP should be LMP
155	5 + 08	Correction	
157	5 + 21	Correction	LMP should be LPM LMP should be LPM "(1) Cap Com - Advise CDR to lower visor"
157	5 + 27	Correction	
159	5 + 31	Add	

6. The sheets, with page letters, reflect changes to the crew cuff checklist. The changes are shown by a bar. The page numbers indicate the page in the document where the cuff checklist page is printed. The recipient should also insure that the change as indicated is reflected into the vertical time where appropriate.

7. In all vertical timelines, the column designated below shows times of DAC (Data Acquisition Camera) operation.

LMP	P ACTIVITIES	EVA TIME	CDR ACTIVITIES	·	C D R
-		+		PRE-EGRESS C	PRE-EGRESS (

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#### LUNAR SURFACE PROCEDURES

#### 4.0 CONTINGENT PLANS

#### 4.1 General Description

Contingency plans presented in this section apply to various situations where some degree of pre-mission planning, together with discussions and reviews with the responsible program elements serve to provide a set of plans and guidelines for use in real time where circumstances might not otherwise permit such planning. It is obvious that not all situations can be preplanned and it is understood that real time circumstances can modify even those situations which were preplanned. Such modifications, if made, will be with the concurrence of the responsible elements in the Mission Control Center.

Plans and guidelines for the following contingency situations are presented in this section:

- (a) Walking EVA's
- (b) One man EVA's
- (c) EVA's from off-nominal landing points
- (d) Shortened EVA's (with prior knowledge)
- (e) Behind time during EVA

The following science priorities were used in replanning EVA activities when circumstances dictate.

#### A. Surface Experiments Priorities

(Source: Mission Implementation Plan and Mission Requirements Document)

- 1. Documented Sample Collection at highest priority traverse station (Part of Lunar Geology Investigation)
- Heat Flow (S-037) (Part of Apollo 16 ALSEP)
- Lunar Surface Magnetometer (S-034) (Part of Apollo 16 (ALSEP)
- 4. Passive Seismic (S-031) (Part of Apollo 16 ALSEP)
- 5. Active Seismic (S-033) (Part of Apollo 16 ALSEP)

- 6. Drill Core Sample Collection (Part of Lunar Geology Investigation)
- 7. Lunar Geology Investigation (S-059) (Portions other than priority items 1 and 6 above)
- 8. Far UV Camera/Spectroscope (S-201)
- 9. Solar Wind Composition (S-080)
- 10. Soil Mechanics (S-200)
- 11. Portable Magnetometer (S-198)
- 12. Cosmic Ray Detector (Sheets) (S-152)
- 13. Lunar Rover Vehicle Evaluation
- B. Station Priorities within each Traverse

(Source: Science Working Panel Minutes of March 16-17, 1972)

PRIORITY	EVA I STATION	EVA II STATION	EVA III STATION
. ]	1-2	4-5	11-12
2	3	8	14
3		6	13
4		10	17
5		9	16
6		7	15

C. Priority of Major Science Activities at Stations

(Exclusive of standard tasks such as TV, photographic pans, etc.)

STATION:	PRIORITY OF ACTIVITIES:
1	Rake/Soil samples; other documented samples
2	Documented samples of Spook; LPM Site Measurement Documented samples of Buster; 500 mm photos
3	Retrieve core; arm MP
4	Rake/Soil Samples Documented Samples Double Core Penetrometer Measurement 500 mm photos
5	N/A
6	N/A

7	Documented Samples 500 mm photos
8	Rake/Soil Samples Boulder samples Other documented samples Double Core
9	CSVC Surface Samples
10	Double Core Penetrometer measurement Documented samples Trench samples
11	Documented Samples 500mm photos Near Field Polarimetry Far Field Polarimetry
12	Rake/Soil Samples Documented samples 500 mm photos
13	N/A
14 ,	Rake/Soil Samples Documented Samples Double Core 500 mm photos
15	LPM Measurement Soil Samples Rock Samples
16	LPM Measurement Soil Samples Rock Samples
17	Rake/Soil Sample Documented Samples LPM Measurements
	- ··· <del>- · · · - ·</del>

# D. Priority of "Special" Samples

(Source: SWP minutes of February 7-8, 1972)

PRIORITY:	SAMPLE:
1	Split Boulder
2	Giant Igneous Rock
3	Radial Sampling of Fresh Crater
4	CSVC

- 5 Surface Sampler Activities
- 6 Fillet Sample
- 7 Permanently Shadowed Soil
- 8 E-W Split

### 4.2 Walking EVA's

The major constraining factors on walking traverses are: radius of action is more limited than LRV traverses to accommodate the B-SLSS emergency return mode (approximately 3.75 km is the maximum distance), average metabolic rate is higher and therefore PLSS consumables margins are lower and the equipment which can be hand-carried precludes doing certain station tasks which were done on the LRV traverses (LMP measurements, for example). walking traverses presented herein are consistent with these limitations while trying to accommodate as many of the original science objectives as practical. It is assumed that the traverses originate from the nominal landing point and no attempt is made to preplan walking traverses from off-nominal landings. Such planning will be done after landing, if necessary. It should also be noted that the three walking traverses discussed herein will apply whether the LRV is inoperative for all three EVA's or whether it becomes inoperative later in the mission.

Table 4.2-1 lists the equipment that will be carried by the crewman on the walking traverses and how it will be carried. Basically, the only tools or experiments that will not be carried are the following:

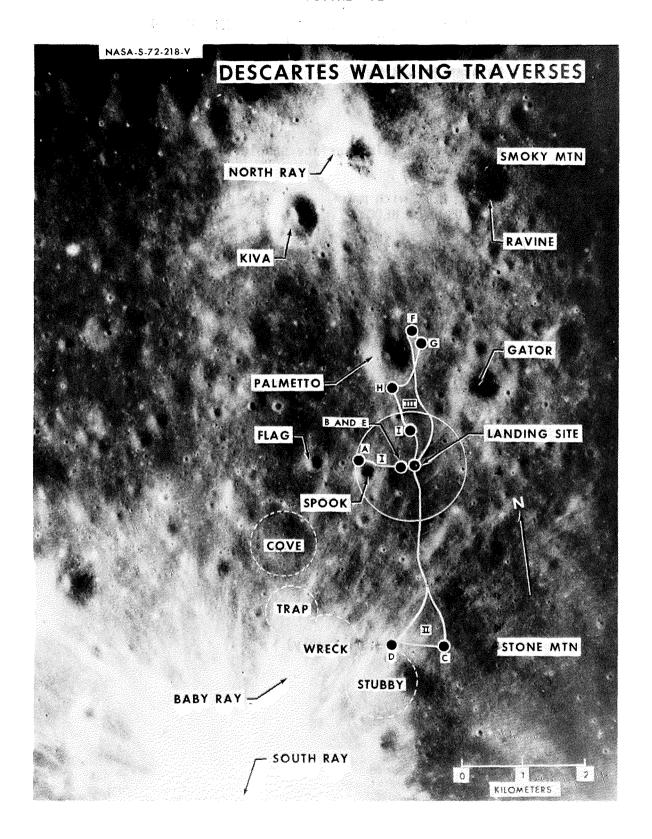
- (a) Lunar portable magnetometer
- (b) Penetrometer
- (c) Scoop (Lunar surface rake carried instead)
- (d) 500 mm camera (carried on EVA III only)
- (e) Padded bags, polarizing filter

Figure 4.2-1 shows the geometry of the three walking traverses, the details of which appear below.

#### TABLE 4.2-1 APOLLO 16 LUNAR GEOLOGY SAMPLING EQUIPMENT FOR A WALKING TRAVERSE

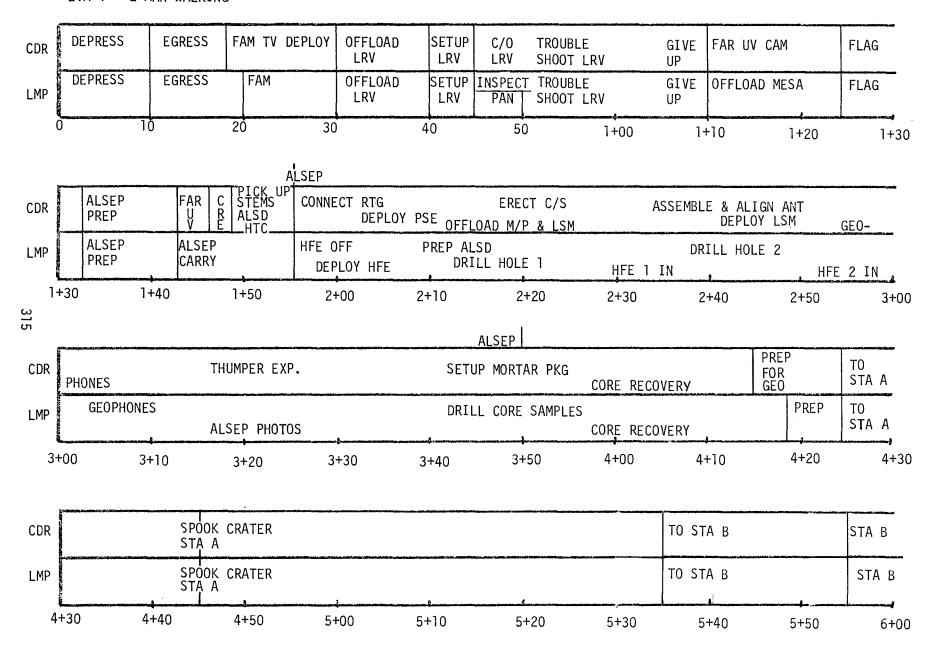
- 1. Mounted on CDR PLSS
  - B-SLSS
  - 2 SCB's
- 2. Tethered to CDR
  - UHT (when taking surface samplers)
- 3. On CDR RCU
  - 70mm HEDC with mag
  - 20 DSBD on HEDC
- 4. Hand-carried by CDR
  - Gnomon
  - Maps
- 5. Mounted on LMP PLSS
  - Core tube rammer
  - Hammer
  - 2 SCB's
- 6. Tethered to LMP
  - Tongs
- 7. On LMP RCU
  - 70mm HEDC with mag
  - 20 DSBD on HEDC
- 8. Hand-carried by LMP
  - Extension handle with rake
- 9. Stowed in SCB's (Depending on EVA requirements)
  - 2-70mm Mags
  - 2 surface samplersCSVC

  - SESC
  - Core tubes
  - 500mm camera (EVA 3 only)



#### 4.2.1 EVA 1

For planning purposes, it is assumed that only 5 minutes more overhead time is used on EVA 1 as in the LRV traverses (1 hour 43 minutes versus 1 hour 37 minutes). This allowance would probably accommodate most cases where an LRV problem was discovered during deployment or initial checkout and some time was subsequently devoted in attempting to troubleshoot and correct the problem before abandoning the vehicle.(the Mission Rule allows up to 30 minutes for this situation.) Figure 4.2-2 is a summary timeline for EVA 1, Walking EVA.



During this initial 1 hour 43 minutes it is assumed that the other science objectives are accomplished as nominally planned (SWC deployment, cosmic ray detector deployment, and UV camera targets).

Following the abandonment of the LRV, ALSEP deployment and obtaining the 2.6 m core take place as nominally planned. At the conclusion of these operations, 4 hours 25 minutes into the EVA, the geology traverse begins.

Although the LRV traverse for EVA 1 visits both Flag and Spook Craters (Stations 1 and 2), the walking traverse is limited to only sampling Spook Crater. (Continuing on to Flag Crater and back would necessitate the investment of an additional 33 minutes walking time and would result in marginal station time at both locations.) Spook Crater is designated station "a" and 49 minutes is allocated to the stop. The sampling rationale and observations at Spook are identical to those on the LRV traverse (see Section 3.6.1.1). The absence of the LPM site measurement at this station allows somewhat more time to be devoted to sampling than on the LRV traverse.

Completing the Spook Crater station, the crew return to the LM/ALSEP vicinity to station "b", where 28 minutes are available for sampling activities at station b. Alternately, this time (or any portion of it) can be spent sampling at locations enroute based upon crew discretion. If circumstances permit, consideration should be given to obtaining the surface sampler samples on EVA 1 (the prime consideration here is availability of boulders in the area to shield the sample area from the effects of LM descent engine contamination).

Arming the mortar package and retrieval of the 2.6 meter core are accomplished upon return to the ALSEP area at the end of the traverse. The final 35 minutes of the EVA are spent in LM closeout activities. The detailed procedures for the EVA 1, Walking EVA are shown in the following pages in a vertical timeline format. A summary of the EVA 1 walking traverse parameters is presented in the tables that follow the detailed procedures.

MISSION:

EVA:

APOLLO 16, J-2 DATE: APRIL 1972 1, TWO MAN WALKING TRAVERSE TASK FUNCTION EVA LMP ACTIVITIES CDR ACTIVITIES CDR TIME 0 + 30NOTE: FOR THE PURPOSE OF THIS TIMELINE PLAN, IT IS ASSUMED THAT THE EVA ACTIVITIES ARE NOMINAL UP TO LRV CHECKOUT AT 43 MINUTES. AT THIS POINT IT IS DISCOVERED THAT THE LRV HAS MALFUNCTIONED. 27 MINUTES ARE USED IN TRYING TO GET THE LRV OPERA-TIONAL. AT 1+10 IT IS DECIDED TO GO WITH A WALKING TRAVERSE. 0+40 LM INSPECTION AND PANS

Retrieve HEDC from ETB and mount on EMU

Take photo pan 20 ft. off SEQ Bay (Quad II)

Comment on:

DPS erosion Strut stroking Pad penetration Soil patterns Any LM anomalies

Photo Cosmic Ray panels (7 ft.) Remove HEDC; place on LRV floor pan

0+50

MISSION: APOLLO 16, J-2 EVA: 1, TWO MAN WALKING TRAVERSE DATE: APRIL 1972

LMP ACTIVITIES	EVA TIME CDR ACTIVITIES	S TAS E FUN C L A M M. P	
-	0+50	M	
Trouble shooting LRV	Trouble shooting LRV		
	+		
_	+		
	+		
•	1+00		
	+		
	+		
-	+		
	1+10		

MISSION: APOLLO 16, J-2

DATE: APRIL 1972 EVA: 1, TWO MAN WALKING TRAVERSE TASK FUNCTION EVA LMP ACTIVITIES CDR ACTIVITIES TIME C D R 1+10 OFFLOAD GEOLOGY PALLET OFFLOAD FAR UV CAMERA Remove thermal blanket Remove thermal blanket Pull lanyard to split bag Pull pip pins; Remove pallet and place on -Z foot pad Remove pallet from LM(optional) Remove pallet handrails (2) Pull 4 pip pins and remove camera from pallet Remove HTC from pallet and set it up Carry camera to deployment site in Quad I (in shadow) Deploy Cam. legs & set on surface Point cam. down sun Place cam. battery in sun OFFLOAD MESA (Temp Label up) Unstow rake, stow on MESA; Pull 2 elev. pins, azimuth Discard rake bracket pin and plate pin Unstow antenna canister and set aside; discard brackets Remove dust cover Level camera (Use 3 leveling knobs -Unstow HEDC from MESA, install and/or dig legs into surface mag B and bag shoe on HEDC and to level) place HEDC back in the ETB Caution: Stay away from camera front after protective cover removed 1+20 Release azimuth lock, point cam. down sun; lock Unstow DAC and place in middle MESA, Remove excess brackets Zero azimuth scale if req'd. from right side MESA Set in first target coord. Az 14° E1 48° Position cam. power Sw - ON FLAG DEPLOY FLAG DEPLOY Mount HEDC from ETB on EMU Unstow flag from MESA Walk to deploy site Assist CDR with flag deployment Push lower shaft into surface Extend flag; insert upper shaft Photo CDR by flag; hand HEDC to

1+30

into lower shaft

MISSION: APOLLO 16, J-2

EVA: 1. TWO MAN WALKING TRAVERSE

DATE: APRIL 1972

TASK FUNCTION **EVA** CDR ACTIVITIES LMP ACTIVITIES TIME 1+30 Photo LMP by flag ALSEP PREP ALSEP PREP Remove therm. cover - SEQ Bay door Pull lanyard - unlock PKG 1 Open SEQ Bay door (white lanyard) Pull PKG 1 from SEQ Bay, lower to surface Stow lanyard on strut Remove hockey stick & lanyard Switch BATT TEMP MON - ON Remove tool restraint pins-PKG 1 Pull lanvard - unlock PKG 2 Remove tool bracket & UHT's; Pull PKG 2 from SEQ Bay, insert UHT'S in ALSEP PKGS. lower to surface Join antenna mast sections to Remove hockey stick & lanyard form carry bar; attach to PKG 1 Unstow fuel cask lanyard; pull Hand DRT to LMP to rotate cask down Rotate PKG to surface Receive DRT from CDR Remove RTG dust cover Remove cask dome using DRT, Hand FTT to LMP discard under LM Set Far UV Cam to target #2 Receive FTT from CDR Push reset switch 1+40 Remove fuel element from cask • Check film advance Insert fuel element into RTG • Set in target: Az <u>54°</u>, El <u>77°</u> Rotate PKG 2 upright and attach to carry bar & PKG 1 ALSEP TO DEPLOY SITE Shift CRE plate-pull RED ring Carry ALSEP Pkgs to deploy site Report CRE dust condition Close SEQ Bay door Retrieve core/bore stems and drill from +Y foot pad and HTC from -Z foot pad and proceed to ALSEP area 1+50

MISSION: APOLLO 16, J-2

EVA: 1, TWO MAN WALKING TRAVERSE

DATE: APRIL 1972 TASK FUNCTION EVA LMP ACTIVITIES CDR ACTIVITIES TIME 1+50ALSEP PACKAGE PLACEMENT Place HTC, ALSD, and stems in the HFE area Place ALSEP Pkgs on surface Move Pkg 2 8' West of Pkg 1, orient UHT'S pointing North Tether UHT REMOVE HFE SUBPALLET Release pull rings (2); pull CONNECT RTG pip pins (3) Tether UHT Read RTG cable Temp Label Pull M/P base pin #1; unwrap Release RTG cable - 3 BB tape; remove cover; pull pin #2 Remove M/P; set on surface Remove RTG cable and pull Pull subpallet pip pin pin to release connector Rotate Pkg 2 to surface, align Verify shorting switch - OUT Remove HFE - 2 BB & connector Report amp reading Place HFE on surface Connect RTG cable to C/S, push down collar to lock Connect HFE to C/S - lock DEPLOY HFE 2+00 Remove subpallet & aim mech. from Pkg. 2 - 4 BB Carry HFE pallet 30' S of C/S. place on surface Place subpallet & aim mech. Remove probe box from pallet -NNE of C/S 4 BB Remove PSE stool from subpallet Split probe box (2 velcro straps) Position PSE stool on surface 8 ft ESE of C/S; dig out hole Carry half with rammer to HFE Hole #1 (~ 18' W) Stow ant. amst on subpallet Remove Pkg 1 dust cover Place HEDC on dust cover Rotate Pkg 1 to surface and align Hole #2 (~ 18 E), place DEPLOY PSE

Place box half on surface

Carry other box half to HFE box on surface

Configure ALSD hardware:

- Verify motor operates
- •Pull pin #2
- Rotate rack camloc 90°
- •Rotate batt camloc 90° pull pin lanyard

Remove PSE from Pkg 1 - 4 BB

Carry PSE to stool

Remove 4 Boyd Bolts from PSE

Remove girdle pull pin

Place PSE on stool; align

Remove girdle and discard Deploy PSE thermal shroud,

2+10 smooth down edge APOLLO 16, J-2 DATE: APRIL 1972

MISSION: APOLLO 16, J-2 EVA: 1, TWO MAN WALKING TRAVERSE

	LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	SECCAM	H	CTION C D R
	<ul><li>Remove handle and install on battery</li><li>Rotate rack bracket up</li></ul>	2+10	Level & <u>Report</u> compass reading Verify C/S sw #5 - CW			
-	<ul> <li>Lift rack off treadle, extend legs and set on surface</li> </ul>	+	Remove T/G from C/S - 1 BB Deploy T/G Verify T/G dial at "O"			
	<ul><li>Pull pin #5, move bracket &amp; lift drill</li></ul>	†	Lean T/G against subpallet			
	Carry drill, rack and bore/core stem bag to HFE Hole #1 site	+	OFFLOAD MORTAR PACKAGE Remove M/P from C/S Pull socket pin ring; deploy 1st leg			
	BORE HOLE 1 DRILLING Set drill on surface	+	Rotate M/P on swivel socket Deploy 2nd leg, position legs Place M/P NNE C/S; point NW  REMOVE LSM			
-	Lean bore/core stem bag against rack; open bag	+	Release LSM from C/S - 2 BB Lift LSM off C/S, ck. cable			
F	Insert 54" bore stem into drill Pick up drill & push bit into surface as far as possible	<del>-</del>	Set LSM on surface clear of C/S  ERECT CENTRAL STATION			
$\vdash$	Remove batt. thermal shield	2+20	Level and align Pkg î			
-	Energize drill until stem top approx. 16" above surface	+	Release C/S So. side - 5 BB			
-		+	Release E side & ant 4 BB			
-	Attach wrench to bore stem	†	Remove rear curtain cover; use UHT socket, pull pins, velcro			
	Remove drill from stem Screw 28" bore section to	†	Release ant. cable bracket			
	section in surface Screw drill onto bore section Energize drill until stem top approx. 16" above surface	+	Release C/S N side - 3 BB			
	Attach wrench to bore stem Remove drill from stem	+	Release W side & ant. 4 BB			
	Screw 28" bore section to section in surface		Verify sunshield released			
	Screw drill onto bore section Energize drill until stem top approx 11" above surface	2+30	Release 2 N interior BB  Release center BB and  control sunshield erection			

MISSION: APOLLO 16, J-2

EVA: 1, TWO MAN WALKING TRAVERSE

TASK FUNCTION EVA LMP ACTIVITIES CDR ACTIVITIES TIME M D 2+30 Attach wrench to bore stem Check side curtains deployed. Remove drill from stem. discard covers set on surface Attach rear and front of side curtains EMPLACE HFE PROBE 1 Remove HFE probe from box Deploy rammer, lean on rack Attach rear thermal curtain Insert probe and first thermal to side thermal curtain shield into bore hole, using rammer Report probe depth & stem height above surface Emplace second thermal shield ASSEMBLE & ALIGN ANTENNA to 21" depth Retrieve ant. mast from Place sunshield over top of stem subpallet; install on C/S Retrieve aiming mech. from DRILL BORE HOLE 2 subpallet, remove dust cover Install aiming mech. on mast Carry drill, rack, rammer Remove aiming mech. housing and bore/core stems to hole 2 and packing Set drill on surface Install antenna on aiming mech. Lean bore/core stem bag and rammer against rack Level and align aiming mech. Insert 54" bore stem into drill Pick up drill & push bit into surface as far as possible Set antenna offsets: Energize drill until stem top Az - 24.68 is approx. 16" above surface E1 - 16.59Push in shorting switch, report amps Turn Sw #1 CW; Sw #5 CCW, report to Hou. Attach wrench to bore stem Remove drill from stem Screw 28" bore section to DEPLOY LSM section in surface Carry LSM to deploy site (50'WSW) Screw drill onto bore section Energize drill until stem top Remove stowage bracket is approx. 16" above surface Deploy legs & verify locked Set LSM on surface(striped leg E) 2+50

DATE: APRIL 1972

MISSION: APOLLO 16, J-2 EVA: 1, TWO MAN WALKING TRAVERSE

	LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	SHO CAM	TASI FUNC L M P	C TION C D R
	Attach wrench to bore stem Remove drill from stem Screw 28" bore section Screw drill onto bore stem Energize drill until stem top is approx. 11" above surface	2+50	Remove foam packing  Deploy sensor arms (center one first)  Remove sensor dust covers  Clean debris from top of LSM  Raise legs so that PRA cover will clear bottom			
-	Attach wrench to bore stem Remove drill from stem, set on surface EMPLACE HFE PROBE 2 Remove HFE probe from box Insert probe and first thermal shield into bore hole, using rammer Report probe depth & stem	+	Pull striped ring to remove PRA cover; verify PRA deployed Level & align LSM			
-	height above surface Emplace second thermal shield to 21" depth	+	DEPLOY GEOPHONES  Pick up T/G from pallet			
<b>-</b>	Place shunshield over top of ste Remove HFE elec. box from pallet Remove dust cover (4BB)		Walk approx. 8' N with T/G			
  -  -	Level & align HFE elec box  Remove all debris at least 16' away from HFE area Place UHT on LRV left floorboard	+				
-	ASSIST IN GEOPHONE DEPLOY Retrieve hammer from HTC; place in leg pocket Retrieve HEDC from dust cover mount on EMU Remove T/G cable stakes from M/P pallet	+	Coordinate with LMP; LMP stake power and geophone cable loops just N of C/S Walk out (290°)			
_	Coordinate with CDR; stake power and geophone cable loops just N of C/S	+	until 1st geophone is reached  Remove geophone clip end geophone #1  Walk out 150' until 2nd			
	Emplace geophone #1 into surface (within 7° of vertical	) + 3+10	geophone is reached  Remove geophone clip and geophone #2			

MISSION: APOLLO 16, J-2

EVA: 1, TWO MAN WALKING TRAVERSE

TASK FUNCTION EVA LMP ACTIVITIES CDR ACTIVITIES TIME 3+10 Stake geophone cable at Walk out 150' until 3rd geophone #2 geophone is reached Emplace geophone #2 into surface (within 7° of vertical) Remove geophone clip and geophone #3 Photo CDR when he reaches Emplace geophone #3 into end of geophone cable surface (within 7° of vertical) TAKE ALSEP PHOTOS Remove flag and emplant by Coordinate photo activity geophone #3 with CDR thumping Unreel remaining power cable Photo: • HFE Bore stems THUMPER GEOPHONE EXP. - Down sun, 11 ft (ea.) Verify "GO" for thumping from MCC - Stereo pair, X Sun, 7 ft (ea) To fire thumper: • HFE Electronics Box - Select ASI - X Sun, 7 ft. - Rotate arm switch 3+20 - Wait 4 sec. - Depress switch to fire LSM - Sun compass; X Sun, 3 ft. - Deploy sunshade Note: - LSM with C/S in bkgnd, 7 ft. Each crewman must remain motionless 10 sec. before and 10 sec. RTG after each thumper firing. CDR will - With C/S in bkgnd; 7 ft. alert LMP preceeding each firing. CENTRAL STATION - X Sun, looking So., 7 ft. - X Sun, viewing switches, The first thumper firing 7 ft. will be at geophone #3; subsequent firing will be at each white mark on the geophone line. A total of 19 thumper firings will be performed. 3+30

DATE: APRIL 1972

MISSION: APOLLO 16, J-2 EVA: 1, TWO MAN WALKING TRAVERSE

	LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	SEG CAM	TAS FUN L	CTION
-	<ul><li>PSE</li><li>X Sun; Viewing bubble and suncompass; 3 ft.</li><li>With C/S in bkgnd.; 7 ft.</li></ul>	3+30				
_	• Panorama - 10 ft. So. of C/S	+				
- - -	Place HEDC on C/S	3+40				
- -	DRILL CORE SAMPLE  Take drill, rack and core stems to deep core site So. of C/S  Set drill on surface  Lean core stem bag against rack  Insert core stem with adapter into drill  Pick up drill and push stem into	+	SET UP MORTAR PACKAGE  Return to C/S  Turn astro sw #5 - CW  Deploy M/P base (pull pin #3)  Insert UHT in M/P base  Using UHT & M/P base as sun compass, estimate geophone line heading			
- - -	surface as far as possible Energize drill until stem top is approx. 12" above surface Attach wrench to core stem Remove drill from stem Screw another core stem section to section in surface Screw drill onto core section Energize drill until stem top is approx. 12" above surface	T	Carry M/P and base ~ 50 ft NNE of C/S Place M/P on surface Deploy M/P base legs(pull pin #4 Using UHT, orient base to same heading as geophone line			

MISSION: APOLLO 16, J-2

DATE: APRIL 1972 EVA: 1, TWO MAN WALKING TRAVERSE TASK FUNCTION EVA LMP ACTIVITIES CDR ACTIVITIES TIME DR 3+50 Place base on surface and Attach wrench to core stem emplant legs. Verify base Remove drill from stem is flat on surface Screw last core stem section to section in surface Place M/P on base; front Screw drill onto core section pins 1st, then lock on rear Energize drill until stem top is approx. 8" above surface Verify wires in front off base Check M/P bubble level reading Deploy M/P antenna Return to C/S Keep drill energized for Mount HEDC on EMU; leave UHT 15 sec. to clear flutes Check PSE shroud Photo M/P - Down sun; 7 ft. - Viewing NE; 7 ft. DRILL CORE RECOVERY - Viewing SE, 7 ft. - With C/S in bkgnd, 15 ft. Pull drill string up as far as possible ASSIST CORE RECOVERY Attach wrench to core stem Remove drill from stem Photo core stem X sun stereo & locator Retrieve stem caps from rack; cap top of core stem 4+00 Assist LMP in deep core Pull core string out of surface recovery by hand, or if difficult: - Assemble jack to treadle - Position jack/treadle over core stem in surface - Jack core out of surface Cap bit end of core Carry core stem back to LM Carry HTC, Core caps & wrench back to LM

4+10

MISSION: APOLLO 16, J-2 EVA: 1, TWO MAN WALKING TRAVERSE

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES		TASI FUNI L M	K CTION C D
BREAK CORE STEM	4+10	<u> </u>	Å.	Р	Ř
Place core string in vise Using wrench, break core string between 3rd & 4th section	+	Set HTC down  Remove vise from dust brush pocket and place on top of pallet  Cap ends of core section			
Unstow core stem bag from MESA & place core stems in it  Place core stem bag by ladder	+	CONFIGURE FOR GEOLOGY TRAV  Unstow SRC #1 & place on SRC table Open SRC, remove SCB & seal control sample in SRC			
CONFIGURE FOR GEOLOGY TRAV  Install mag G on LMP HEDC & place on EMU  Dlace SCR #1 on CRR	4+20	Remove from SCB #1  • 2 20-Bag disp and place them on HEDC'S • 1 core cap disp & place			
Place SCB #1 on CDR  Retrieve rake from MESA & take to -Z foot pad area  Remove extension handle from pallet & put rake on it & hand carry	4+20	on LMP Remove BSLSS from ETB & place on LMP Remove SCB #5,6,7 or 8 from geology pallet & hang on LMP Remove tongs from pallet & place on tether			
- Hand Carry	T +	Remove gnomon from pallet & hand carry			
TRAVERSE TO STA A	+	TRAVERSE TO STA A			
	†				
	4+30				

MISSION: APOLLO 16, J-2 EVA: 1, TWO-MAN WALKING TRAVERSE

	LMP ACTIVITIES	EVA TIME CDR ACTIVITIES  S TASK FUNCTION C L C A P R
		4+30
	-	
		† 1111
*		+
*		+ 1111
	<u> </u>	
		T
		†
A Continues		+
Manufacture.		4+40
	<b>-</b>	1 1 1
		†
	<b>-</b>	+
	SPOOK CRATER	SPOOK CRATER
	Geology sta A	Geology sta A
		†
Miller species -		+
Marketine		4+50

MISSION: APOLLO 16, J-2 EVA: 1, TWO-MAN WALKING TRAVERSE

LMP ACTIVITIES	EVA TIME	CDR	ACTIVITIES	SECO	TAS FUN L M	CTION C D R
	4+50					
	+					
	1					
	†					
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	1					
	<b> </b> 5+10					
<u></u>	2710			1	,	

MISSION: APOLLO 16, J-2

EVA: 1, TWO-MAN WALKING TRAVERSE

Marine Ma	LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	SEQ CAM	TASI FUNC L M P	
		5+10		M-		Ħ
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	<u></u>	+				
	-	+				
( minum	L	5+30				
Maritiman						

MISSION: APOLLO 16, J-2 DATE: APRIL 1972

EVA: 1, TWO-MAN WALKING TRAVERSE

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	S E Q C A	FUNC L M P	CTION C D R
	5+30	·	M.	Р	R
	Ţ				
<b>-</b>	†				
-	+				
· ·					
TRAVERSE TO STA B		TRAVERSE TO STA B			
11419 21102 10 0111					
	†				
-	+				
	1				
-	+				
	5+40				
-	Ţ				
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-	+				
	1				
_	†				
-	+				
	+				
-	1				
	T				
•	†				
_	5+50				

MISSION: APOLLO 16, J-2 EVA: 1, TWO-MAN WALKING TRAVERSE

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	S E G C A M	TAS FUN L M P	
	5+50		- iñ.	P	t
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CEOLOGY STA D		CEOLOCY STA D			
- GEOLOGY STA B	†	GEOLOGY STA B			
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MISSION: APOLLO 16, J-2 EVA: 1, TWO-MAN WALKING TRAVERSE

LMP ACTIVITIES	EVA TIME CDR ACTIVITIES	S TASK E FUNCTION C L C A M D M. P R
	6+10	M. F. A.
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	T	
	†	
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	T	
<b>-</b>	+	
-	+	
-	†	
-	+	
	1 6+20	
	†	
-	+	
TRAVERSE TO LM	TRAVERSE TO LM	
CLOSEOUT  Place rake/ext handle by MESA	CLOSEOUT  Place gnomon & tongs by MESA	
- Tace Takey ext manage by MES	Reset Far UV cam. target:	
Unstow SWC from MESA	Az <u>126°</u> E1 <u>33°</u>	
Deploy SWC 60' at 2:00	LI JJ	
Extend SWC staff sections	Photo Far UV Camera	
Press staff into surface	- X Sun; 20 ft; f5.6/60	
Deploy foil; hook on staff	- Dn Sun; 3 ft; f5.6/60 6+30	

MISSION: APOLLO 16, J-2 EVA: 1, TWO-MAN WALKING TRAVERSE

DATE: APRIL 1972

	LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	E Q. C	TAS FUN	CTIC
			<u> </u>	Â	M P	
	Photo SWC:	6+30				
	- X Sun; stereo pair of foil ans staff; 7 ft.	T	Remove HEDC & place in ETB			
	- X Sun; upper foil; 7 ft.	Ť				
	Remove HEDC & place in ETB	+				
	CDR remove SCB from LMP		Remove SCB from LMP and stow on +Z foot pad			
	Remove SCB #1 from CDR	1	LMP remove SCB #1 from CDR			
	Place SCB #1 in SRC #1 on MESA table	+				
	Remove seal protectors (2)	+	Remove sample containment bags (6) from MESA & place			
	Verify bag material is free of seal area	+	in ETB			
_	Close and seal SRC #1	6+40	Retrieve dust brush from pallet			
	Tidy MESA blankets	ł				
	Clean EMU'S & stow PLSS antennas	+	Clean EMU'S & stow PLSS antennas			
		+				
		ł				
-	INGRESS Ascend ladder with SCB from +Z	+	Place dust brush on ladder hook			
	foot pad Descend ladder	+				
	Ascend ladder with core/bore stems from +Z foot pad	+				
	Ingress IM with COD a	1	Attach ETB to LEC			
	Ingress LM with SCB & core/bore stems		Ascend ladder with SRC #1 Pass SRC #1 to LMP			
	Obtain SRC #1 from CDR	6+50				

MISSION: APOLLO 16, J-2

EVA: 1, TWO-MAN WALKING TRAVERSE

DATE:APRIL 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	SEQ CAM	TASE FUNC L M P	C D R
- Obtain ETB from CDR	† P	ull up ETB ass ETB to LMP escend ladder to surface eset Far UV cam. target:			
- Assist CDR ingress	ļ I	Az 230° E1 53°  CDR INGRESS  ngress LM			
- Close hatch	Ŧ				
FI PR	NAL EVA CL	CEDURES FOR OSEOUT ARE THE LUNAR KLIST			
	7+00 				
	1			•	
	-				
	+				
	+				
	1				

#### WALKING TRAVERSE

#### **ASSUMPTIONS**

- 30 MINUTES RESERVES MAINTAINED ON ALL PLSS CONSUMABLES AT STATION METABOLIC RATE
- 2. ALL DISTANCES AND SPEEDS ARE MAP DISTANCES AND MAP SPEEDS (MOBILITY RATES)
- 3. REQUIRED RATE = RETURN DISTANCE/AVAILABLE OP\$ TIME TOTAL OPS TIME 80.5 MINUTES
  5 MIN BSLSS HOOKUP
  13 MIN LM INGRESS
  62.5 MIN AVAILABLE FOR WALKBACK
- 4. TIME MARGIN AT STATION METABOLIC RATE

  STATION
  FINAL LM 0/H

  MARGIN = FOR WALKBACK, AND 13 MINUTES
  INGRESS
- 5. RESPIRATORY EXCHANGE QUOTIENT = .90
- 6. FEEDWATER HEAT OF VAPORIZATION 1038  $\frac{BTU}{LB}$ .

TABLE 4.2-2

# APOLLO 16 DESCARTES WALKING TRAVERSES

EVA I

CALCULATED DATA

APR 10 1972

STATION	SEGMENT DISTANCE (KM)	WALKING MOBILITY RATE (KM/HR)	WALK TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	1+43	1+43
WALK ALSEP	0.10	2.50	2	0.10	1+45	2+40	4+25
WALK	0.85	2.50	20		<del>-</del> <del></del>		
A WALK	0.90	2.50	22	0.95	4+46	0+49	5+35
В				1.85	0 5+56	0+28	6+24
WALK LM	0.05	2.50	1	1.90	6+26	0+35	7+ 1
TOTALS			45			6+15	7+ 1

		PLSS	FAILURE	TRAVERSE	CONTINGE	NCIES	
		CONT.	STA:	TION MARG	ИI	MIN	
	RETURN	WALKBACK	ABOVE	WALKBACK	REQT	WALKBACK	
	DISTANCE	TIME	(PRII	MARY CREW	MAN)	SPEED	AVG EVA
STAT	TO LM	TO LM	F₩	02	AMP-HRS	REQ	MET RATE
МП	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KM/HR)	(BTU/HR)
LM	0.00	0+ 0	****	****	****	0.00	1050.00
ALSEF	0.10	0+ 2	3+59	2+57	3+26	0.10	1049.55
A	0.95	0+16	2+12	1+24	2+2	0.91	1031.96
В	0.05	0+ 1	2+ 0	0+57	1+28	0.05	1024.19
∟M	0.00	0+ 0	1+35	0+32	1+ 5	0.00	1026.27

TABLE 4.2-3
APOLLO 16 DESCARTES WALKING TRAVERSES

INPUT DATA

APR 10 1972

	STATION NO	STOP TIME (HR+MIN)	SEGM DIST (KM)	RETURN DIST (KM)	HEAT LEAK (BTU/HR)	-MOBILIT NOMINAL (KM/HR)	Y RATE CONT/CY (KM/HR)	MET RAT NOMINAL (BTU/HR)	E WALK CONT1CY (BTU/HR)
	LM	1+43	0.00	0.00	-75.00	2.50	3.60	1000.0	1560.0
	ALSEP	2+40	0.10	0.10	-75.00	2.50	3.60	1000.0	1560.0
,	A	0+49	0.85	0.95	-75.00	2.50	3.60	1000.0	1560.0
	В	0+28	0.90	0.05	-75.00	2.50	3.60	1000.0	1560.0
	LM	0+35	0.05	0.00	-75.00	2.50	3.60	1000.0	1560.0

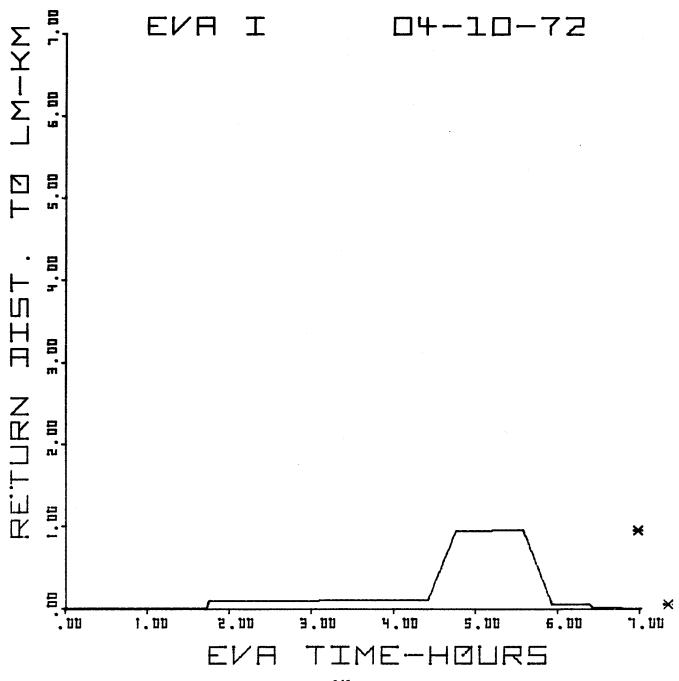
ALSEP	STATION	MET RATE LM D/H (BTU/HR)	RATE D2	EVA START (F/W-LB)	EVA START (O2-LB)	
1050.0	950.0	1050.0	0.020	11.21	1.403	62.5

NOTE: OPS TIME IS TOTAL WALKING TIME AVAILABLE.

EVA I

# PPOLLO 16-WLK TRAVERSE

- X 02 WALKBACK CONSTRAINT
- <sup>+</sup> FW WALKBACK CONSTRAINT
- M BATTERY WALKBACK CONSTRAINT



#### 4.2.2 EVA 2

The objectives for walking traverse on EVA 2 are the same as the LRV traverses; namely, to investigate the Stone Mt. region and the South Ray ray area. Limitations on walking radius and slope climbing ability on foot, however, will limit the Stone Mt. operations to areas near the base. Figure 4.2-4 is a summary timeline for EVA 2, Walking EVA.

The first station on the traverse (station "c") is in the region of the LRV traverse station 6. It is approximately 3 km away from the LM and is reached after an estimated 1 hour 10 minutes walk. The station time allotted is 1 hour 15 minutes which is spent in sampling along the base of Stone Mt. ranging over an area to the north of Stubby Crater.

Station "d" is located in the vicinity of the LRV traverse station 8 and 1 hour 11 minutes is allotted to the stop. Activities at station "d" are identical to the station 8 activities, being principally concerned with the sampling of material from South Ray Crater including boulder operations.

Leaving station "d", the traverse continues northeast to pick up the outbound tracks which are then followed back to the LM area where station "e" is located. Activities at "e" are identical to those of the nominal LRV traverse station 10; 30 minutes are alloted for these activities consisting of the trench, trench samples, double core, and penetrometer measurements. The final 35 minutes of EVA 2 are devoted to closeout activities.

A summary of the EVA 2 walking traverse parameters is presented in the following tables.

STA E

6+00

5+50

TO STA E

4+50

5+00

5+10

5+20

5+30

5+40

4+40

LMP

4+30

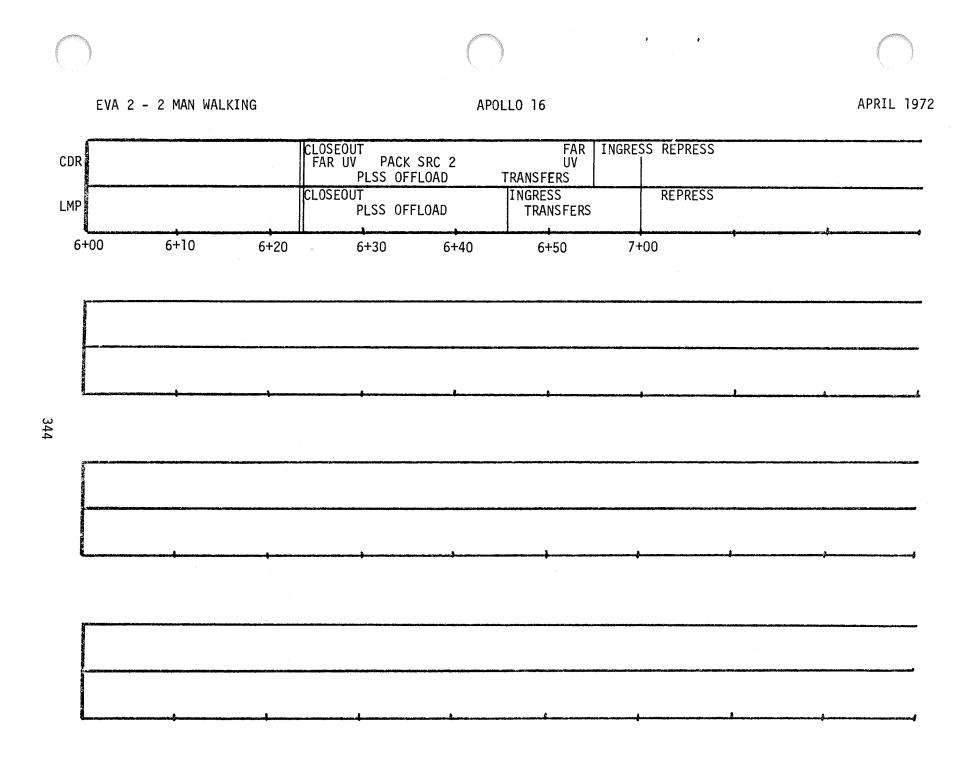


TABLE 4.2-4
APOLLO 16 DESCARTES WALKING TRAVERSES

EVA II

CALCULATED DATA

MAR 20 1972

STATION	SEGMENT DISTANCE (KM)	WALKING MOBILITY RATE (KM/HR)	WALK TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
∟M				0.00	0+ 0	0+45	0+45
WALK C	2.90	2.50	70	2.90	1+55	1+15	3+10
WALK	0.80	2.50	19				
D WALK	3.00	2.50	72	3.70	3+29	1+11	4+40
Ē				6.70	5+52	0+32	6+24
WALK LM	0.05	2.50	1	6.75	6+25	0+35	7+ 0
TOTALS			162			4+18	7+ 0

		PLSS	S FAILURE	TRAVERSE	CONTINGE	MCIES	
		CONT.	STA:	TION MARG	M	MIN	*
	RETURN	WALKBACK	ABOVE	WALKBACK	REQT	WALKBACK	
	DISTANCE	TIME	(PRI)	MARY CREW	MAN)	SPEED	AVG EVA
STAT	TO LM	TO LM	F₩	- 02	AMP-HRS	REQ	MET RATE
NO	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KMZHR)	(BTU/HR)
∟M	0.00	0+ 0	++++	****	****	0.00	1050.00
S	2.90	0+48	2+45	2+41	4+ 1	2.78	992.09
$\mathbf{D}$	3.10	0+52	1+ 6	1+ 4	2+28	2.98	981.95
Ē	0.05	0+ 1	1+22	0+36	1+34	0.05	982.67
∟M	0.00	0+ 0	0+58	0+11	1+12	0.00	988.33

TABLE 4.2-5

# APOLLO 16 DESCARTES WALKING TRAVERSES

EVA II

### INPUT DATA

MAR 20 1972

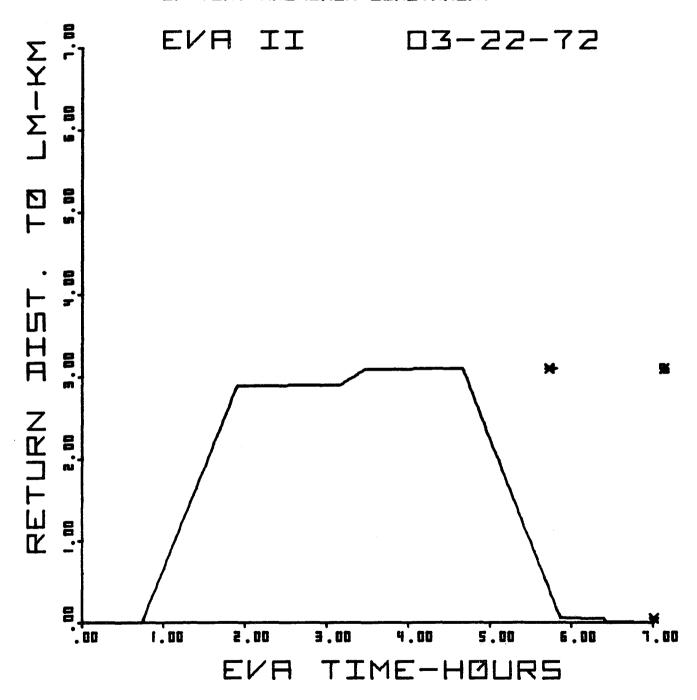
		STOP	SEGM	RETURN	HEAT	-MOBILIT	Y RATE	MET RAT	E WALK
	STATION	TIME	DIST	DIST	LEAK	NOMINAL	CONT/CY	MOMINAL	CONTICY
	HO	(HR+MIN)	(KM)	(KM)	(BTU/HR)	(KMZHR)	(KMZHR)	(BTU/HR)	(BTU/HR)
	LM	0+45	0.00	0.00	125.00	2.50	3.60	1000.0	1560.0
	C	1+15	2.90	2.90	125.00	2.50	3.60	1000.0	1560.0
	D	1+11	0.80	3.10	125.00	2.50	3.60	1000.0	1560.0
	Ε	0+32	3.00	0.05	125.00	2.50	3.60	1000.0	1560.0
<b>.</b>	LM	0+35	0.05	0.00	125.00	2.50	3.60	1000.0	1560.0

MET RATE	MET RATE	MET RATE	LEAK	EVA	EVA
ALSEP	STATION	LM D/H	RATE 02	START	START
(BTUZHR)	(BTUZHR)	(BTUZHR)	(LB/HR)	(F∠W−LB)	(02-LB)
1050.0	950.0	1050.0	0 028	11.64	1.353

FIGURE 4.2-5

# APOLLO 16-WLK TRAVERSE

- X 02 WALKBACK CONSTRAINT
- + FW WALKBACK CONSTRAINT
- \* BATTERY WALKBACK CONSTRAINT



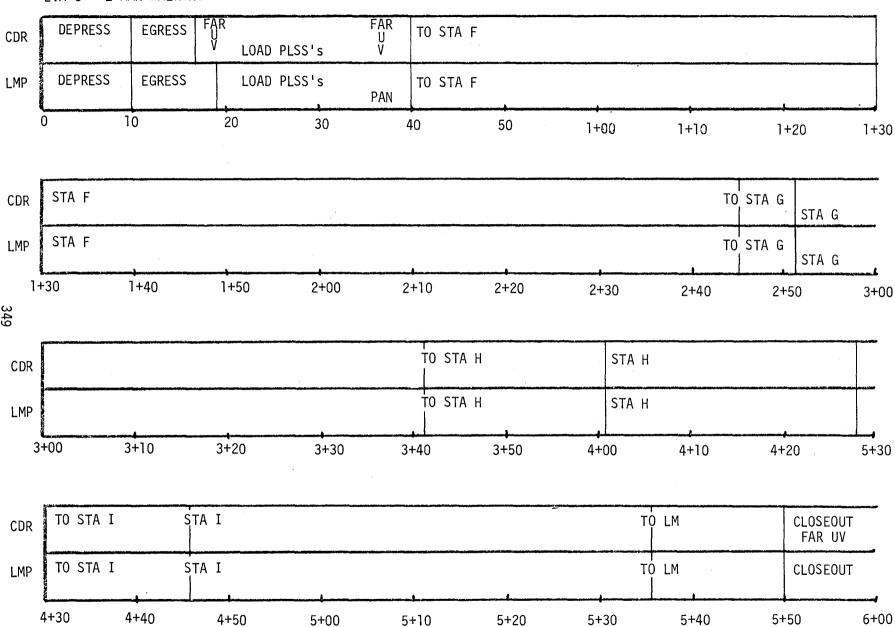
#### 4.2.3 EVA 3

Although the prime objectives of the EVA 3 LRV traverses were North Ray Crater and Smoky Mt., both of these points are beyond the range of the walking traverse (5.5 km and 4.4 km, respectively). A substitute for the Descartes Formation sampling (Smoky Mt.) is not available within walking range, but Palmetto Crater can serve as a substitute for the Cayley sampling originally planned for North Ray. Figure 4.2-6 is a summary timeline for EVA 3, Walking EVA.

The EVA 3 walking traverse, therefore, ranges northward from the LM to Palmetto Crater where three stations are planned (f, g and h) for a total station time of about 2-1/2 hours. After departing the Palmetto vicinity, the traverse continues to station "i" where 50 minutes are spent sampling at an intermediate size crater in the Cayley plains.

Returning to the LM, the final hour of the EVA is spent in closeout activities. The total duration of the EVA is slightly under the usual 7 hours (6 hours 55 minutes) due to limitations on PLSS oxygen.

Details of the EVA 3 traverse parameters are presented in the following tables.



EVA 3 - 2 MAN WALKING APOLLO 16 APRIL 1972 FAR UV TRANS-FERS INGRESS REPRESS PLSS OFFLOAD PACK SCB's CDR COLLECT CRE DAC SHOW CASSETTE INGRESS PLSS OFFLOAD PACK SCS's **REPRESS** LMP TRANSFERS COLLECT SWC DAC SHOW 6+00 6+10 6+20 6+30 6+40 6+50 7+00 350

TABLE 4.2-6 APOLLO 16 DESCARTES WALKING TRAVERSES

EVA III CALCULATED DATA

MAR 22 1972

STATION	SEGMENT DISTANCE (KM)	WALKING MOBILITY RATE (KM/HR)	WALK TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
_M			\ 	0.00	0+ 0	0+40	0+40
WALK F	2.10	2.50	50	2.10	1+30	1+15	2+45
WALK S	0.25	2.50	6	2.35	2+51	0+50	3+41
WALK	0.80	2.50	19				
H WALK	0.80	2.50	19	3.15	4+ 1	0+26	4+27
I		0 50		3.95	4+46	0+50	5+36
WALK LM	0.60	2.50	14	4.55	5+50	1+ 5	6+55
TOTALS			108			5+ 6	6+55

		PLSS	FAILURE	TRAVERSE	CONTINGE	MCIES	
		CONT.	STA:	TION MARG	M	MIN	
	RETURN	WALKBACK	ABOVE	WALKBACK	REQT	WALKBACK	
	DISTANCE	TIME	(PRI)	MARY CREW	MAN)	SPEED	AVG EVA
STAT	TO LM	TO LM	F₩	02	AMP-HRS	REQ	MET RATE
NΠ	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KMZHR)	(BTU/HR)
				•			
11 ا	0.00	0+ 0	****	****	****	0.00	1050.00
F	2.10	0+35	3+26	3+11	4+39	2.02	989.42
5	2.00	0+33	2+34	2+17	3+44	1.92	980.80
Н	1.40	0+23	2+12	1+47	3+ 9	1.34	979.18
1	0.60	0+10	1+34	0+57	2+13	0.58	976.03
Mے	0.00	0+ 0	0+45	0+ 0	1+17	0.00	988.44

TABLE 4.2-7

## APOLLO 16 DESCARTES WALKING TRAVERSES

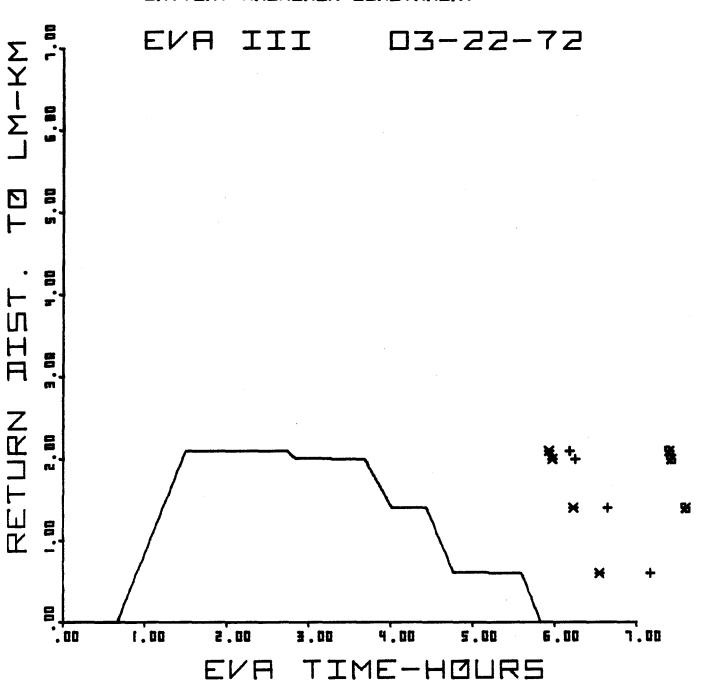
EVA III INPUT DATA MAR 22 1972

STATION ON	STOP TIME (HR+MIN)	SEGM DIST (KM)	RETURN DIST (KM)	HEAT LEAK (BTU/HR)	-MOBILIT NOMINAL (KM/HR)	Y RATE CONT/CY (KM/HR)	MET RAT NOMINAL (BTU/HR)	E WALK CONT/CY (BTU/HR)
LM	0+40	0.00	0.00	180.00	2.50	3.60	1000.0	1560.0
F	1+15	2.10	2.10	180.00	2.50	3.60	1000.0	1560.0
G	0+50	0.25	2.00	180.00	2.50	3.60	1000.0	1560.0
Н	0+26	0.80	1.40	180.00	2.50	3.60	1000.0	1560.0
I	0+50	0.80	0.60	180.00	2.50	3.60	1000.0	1560.0
LM	1+ 5	0.60	0.00	180.00	2.50	3.60	1000.0	1560.0

MET RATE	MET RATE	MET RATE	LEAK	EVA	EVA
ALSEP	STATION	LM D/H	RATE 02	START	START
(BTUZHR)	(BTU/HR)	(BTUZHR)	(LB/HR)	(F/W-LB)	(02-LB)
1050.0	950.0	1050.0	0.035	11.64	1.353

# PPOLLO 16-WLK TRAVERSE

- × 02 WALKBACK CONSTRAINT
- + FW WALKBACK CONSTRAINT
- BATTERY WALKBACK CONSTRAINT



#### 4.3 One man EVA's

Certain hardware problems, principally associated with the EMU, could result in the situation where one crewman would have to remain in the LM cabin while the other crewman performed the EVA alone. For example, a problem in the PLSS electrical system could result in the loss of fan and/or pump operation which would preclude EVA operations with that EMU. If such a problem developed it would most likely be discovered during the EVA preparation period and only a short time would be available for the ground to prepare contingency EVA plans. Thus, although such a situation is very unlikely to occur, it will be desirable to establish constraints and outline traverse objectives within these constraints.

Although it is possible to perform all the planned EVA tasks with one man (including ALSEP deployment and LRV deployment), it will obviously be more difficult and more time consuming. Timelines are provided in this section to show how the major tasks would be accomplished in this mode. Insofar as the traverse is concerned, the constraints remain the same in that the consumables margins must be retained to walk back from a failed LRV, or to drive back with a failed PLSS. The absence of the Buddy-SLSS, however, for cooling with the failed PLSS case results in a different radius of action for the one man case compared to the nominal two man case.

With the PLSS failure on the one man EVA, the crewman becomes completely dependent on the OPS for both oxygen, cooling, and CO<sub>2</sub> removal. To accomplish this, the OPS is operated in the purge mode with either of two flow rates, the selection of which depends upon the amount of cooling required. The necessity for the high flow rate (and hence early depletion) can be avoided if the crewman's activity after the PLSS failure can be minimized. Hence, the first constraint on the one man EVA is that traverse operations be restricted to the near vicinity of the LRV, on the order of 100 m. Allowing for the high metabolic rate in returning to the LRV over this distance and for a later period of high metabolic rate ingressing the LM, leaves the portion of the OPS capability which remains for use on the LRV return to the LM. This remainder is equivalent to a certain number of minutes driving time and dictates how far (in terms of driving time) the single crewman can range on the traverse. Figure 4.3-1 presents curves which can be used to estimate this maximum radius under various conditions. These curves represent the maximum capability available; the actual values to be used in real time situations will be determined by the Flight Director based on an overall assessment of the situation.

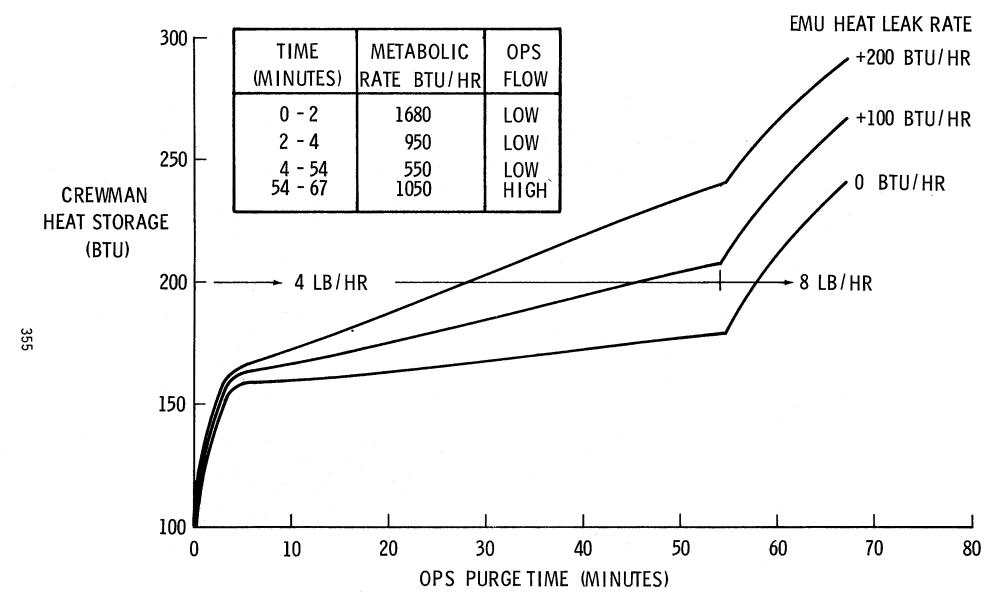


Figure 4.3-1 - Crewman heat storage for contingency LRV Traverse with OPS cooling only (Low- and high-flow mode).

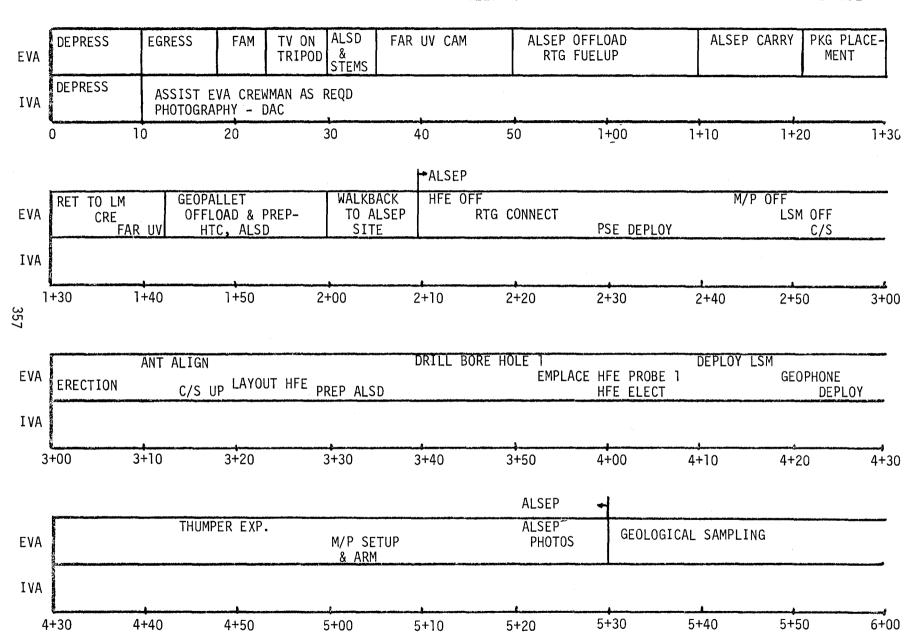
The other consideration on one man traverse design is the fact that the LRV navigation tasks should be simplified by providing a return route where it will be possible to simply follow the outbound LRV tracks back to the LM. The reason for this consideration is that absence of the second crewman (who does much of the visual navigation) could compromise a time-critical emergency return.

The following is a brief discussion on one man EVA's which were constructed within the framework of the above constraints.

#### 4.3.1 EVA 1

EVA 1 is largely occupied with ALSEP deployment as shown in the summary timeline in figure 4.3-2. Other activities in the LM vicinity are also accomplished such as UV camera photography and cosmic ray detector deployment. About 6 minutes are provided for sampling activities which must be restricted to the vicinity of the LM since the LRV has not been deployed. Other nominal EVA 1 activities which are not performed under this contingency case are the emplacement of the second Heat Flow Experiment probe and part of the Thumper operations associated with the Active Seismic Experiment. The 2.6 m core operation is postponed to EVA 2.

The detailed procedures for EVA 1, One Man EVA are shown in the following pages in a vertical timeline format. A summary of the EVA 1 walking traverse parameter is presented in the tables that follow the detailed procedures.

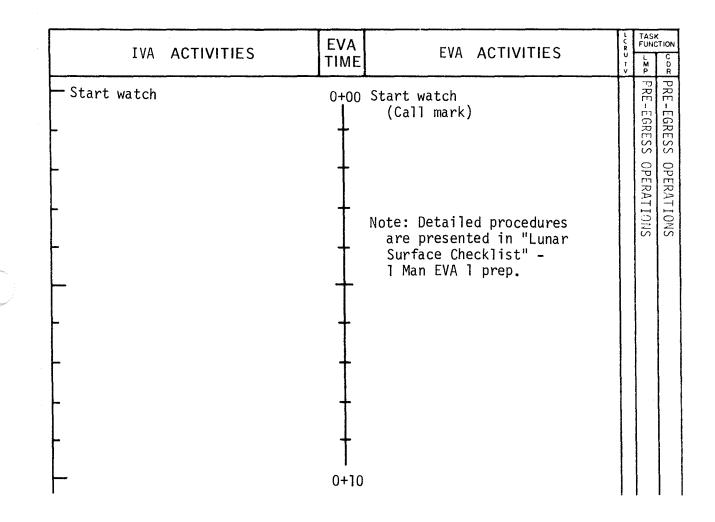


EVA 1 - 1 MAN APOLLO 16 **APRIL 1972** FAR UV PACK ETB SRC, SCB TRANSFER IN-ETB,SRC,GRESS SCB REPRESS EVA ASSIST TRANSF. **REPRESS** IVA 6+10 6+20 6+30 6+00 6+40 6+50 7+00 358

APOLLO 16 APRIL 1972

#### ONE-MAN TIMELINE

# LUNAR SURFACE EVA 1



MISSION: EVA: 1

APOLLO 16 -1 MAN

DATE:

**APRIL 1972** 

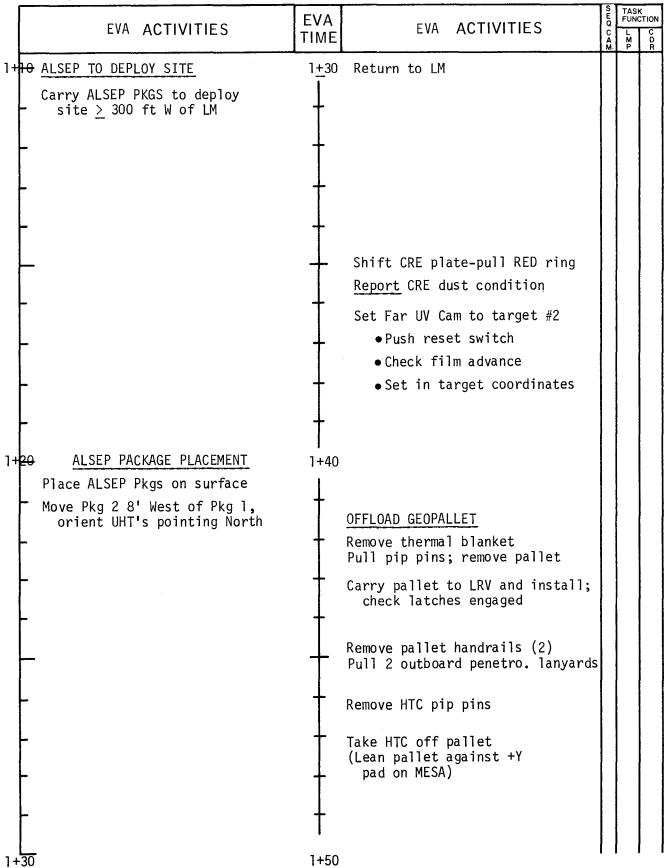
TASK FUNCTION EVA EVA ACTIVITIES IVA **ACTIVITIES** M C D R TIME Assist 0+10 Move through hatch Deploy PLSS ant (EVA) Deploy PLSS antenna Place jettison bag in hatch - Comm check Attach LEC to ETB Descend ladder Pass ETB/LEC to CDR Toss jett bag to Quad I Deploy MESA Deploy LEC/ETB to gnd Descend to footpad Note: IVA crewman assists Step to surface EVA crewman as required with procedures and information. He also photos FAMILIARIZATION EVA crewman where possible with DAC. - Check mobility & stability (This IVA column will be dropped until end of the 0+20 EVA to conserve space) Comment on surroundings Kick jett bag under LM DEPLOY TV CAMERA Adjust MESA height Loosen blanket around lens Open MESA blankets Unstow & deploy TV tripod Unstow TV camera Mount TV camera on tripod Pull TV cable slack from MESA Position TV 12:00/50 ft (f:16,20mm,PK) Check reception with MCC Remove & discard MESA
TV Stowage bracket 0 + 30

DATE: APRIL 1972

	EVA TIME EVA ACTIVITIES	ō [	L M P	Tic
Offload ALSD from MESA place on +Y pad  Offload bore/core stem pkg from MESA; place on +Y pad  Hang ETB on SRC table  Unstow antenna canister and set aside; discard brackets  OFFLOAD FAR UV CAMERA Remove thermal blanket  Pull lanyard to split bag Remove pallet from LM(optional)  Pull 4 pip pins and remove camera from pallet  Carry camera to deployment site in Quad I (in shadow) Deploy Cam. legs & set on surface	ALSEP PREP  Remove therm. cover - SEQ Bay door Open SEQ Bay door (white lanyard) Stow lanyard on strut Switch BATT TEMP MON - ON Pull lanyard - unlock PKG 2 Pull PKG 2 from SEQ Bay, lower to surface Remove hockey stick & lanyard  Pull lanyard - unlock PKG 1  Pull PKG 1 from SEQ Bay, lower to surface Remove hockey stick & lanyard Remove tool restraint pins-PKG 2  Remove tool bracket & UHT's;	, and	Ρ	
Point cam. down sun Place cam. battery in sun (Temp Lable up)	insert UHT's in ALSEP PKGŚ.  Join antenna mast sections to form carry bar; attach to PKG 1			
+10 Pull 2 elev. pins, azimuth pin and plate pin  Remove dust cover	1+00 Put DRT & FTT in SEQ Bay Rotate PKG to surface Remove RTG dust cover			
Level camera (Use 3 leveling knobs - and/or dig legs into surface to level)	Unstow fuel cask lanyard; pull to rotate cask down  Get DRT from SEQ Bay  Remove cask dome using DRT,			
- Caution: Stay away from camera front after protective cover removed	discard under LM Get FTT from SEQ Bay  Remove fuel element from cask Insert fuel element into RTG			
Release azimuth lock, point cam. down sun; lock	Rotate PKG 2 upright and attach to carry bar & PKG 1			
- Zero azimuth scale if req'd.  Set in first target coord.  AZ. 14 ° El. 48 °	Close SEQ Bay door			
Position cam. power Sw - ON +50	Pick up ALSEP Pkgs 1+10			

MISSION: APOLLO 16 DATE: APRIL 1972

EVA: 1 -1 MAN



	EVA ACTIVITIES	EVA TIME EVA ACTIVITIES	SEG	TAS FUN L M	C D
•	1+50-Assemble XT handle to scoop  - Place tongs on HTC Place SCB on HTC Offload SRC 1  Open SRC 1	2+10Release pull rings (2); pull pip pins (3) Pull M/P base pin #1; unwrap tape; remove cover; pull pin #8 Remove M/P; set on surface Pull subpallet pip pin Rotate Pkg 2 to surface, align Remove HFE - 2 BB & connector Place HFE on surface Connect HFE to C/S - lock	2		
	Place SCB 1 on HTC  - Hang ETB on HTC  Turn TV to cover ALSEP  - Pick up ALSD, HTC, and stems	Carry HFE pallet 10' S of C/S, place on surface  CONNECT RTG Tether UHT			
	Walk back to ALSEP area	Read RTG cable Temp Lable  Release RTG cable - 3 BB  Remove RTB cable and pull  pin to release connector 2+20  Verify shorting switch - OUT			
	-	Report amp reading Connect RTG cable to C/S, push down collar to lock  Remove subpallet & aim mech. from Pkg 2 - 4 BB			
	-	Place subpallet & aim mech.  NNE of C/S  Remove PSE stool from subpallet Position PSE stool on surface 8 ft ESE of C/S; dig out hole Stow ant. mast on subpallet Remove Pkg 1 dust cover			
	Deposit HTC, ALSD & stems 30' S C/S HFE OFFLOAD	Rotate Pkg 1 to surface and align  2+30			

MISSION: APOLLO 16 EVA: 1 -1 MAN

DATE: APRIL 1972

EVA ACTIVITIES	EVA TIME EVA ACTIVITIES	TAS FUNI L M	C C D R
2+30	2+50  Release LSM from C/S - 2 BB Lift LSM off C/S, ck. cable Set LSM on surface clear of C/S  ERECT CENTRAL STATION Level and align Pkg 1 Release C/S So. side - 5 BB	4. P.	R
Verify C/S sw #5 - CW  Remove T/G from C/S - 1 BB Deploy T/G  Verify T/G dial at "0"  Lean T/G against subpallet	Release E side & ant 4 BB  Remove rear curtain cover; use UHT socket, pull pins, velcro  3+00Release ant. cable bracket  Release C/S N side - 3 Bb  Release W side & ant. 4 BB		
OFFLOAD MORTAR PACKAGE Remove M/P from C/S  Pull socket pin ring; deploy 1st leg Rotate M/P on swivel socket  Deploy 2nd leg, position legs Place M/P NNE C/S; point NW	Release 2 N interior BB Release center BB and control sunshield erection  Check side curtains deployed discard covers Attach rear and front of side curtains		

DATE: APRIL 1972 MISSION: APOLLO 16 EVA: 1 -1 MAN TASK FUNCTION EVA EVA ACTIVITIES EVA ACTIVITIES TIME M 3+10 Attach rear thermal curtain 3 + 30to side thermal curtain Configure ALSD hardware: ASSEMBLE & ALIGN ANTENNA Verify motor operates Retrieve ant. mast from •Pull pin #2 subpallet; install on C/S •Rotate rack camloc 90° Retrieve aiming mech. from subpallet, remove dust cover •Rotate batt camloc 90° Install aiming mech. on mast pull pin lanyard Remove aiming mech. housing • Remove handle and and packing install on battery Install antenna on aiming mech. Rotate rack bracket up Level and align aiming mech. Lift rack off treadle, extend legs and set on surface ● Pull pin #5, move Set antenna offsets: bracket & lift drill Az - 24.68E1 - 16.59Carry drill, rack and Push in shorting switch, bore/core stem bag to HFE report amps Hole #1 site Turn Sw #1 CW; 3+40 BORE HOLE 1 DRILLING report to Hou. Set drill on surface LAYOUT HFE Lean bore/core stem bag Remove probe box from pallet against rack; open bag 4 BB Insert 54" bore stem into drill Split probe box (2 velcro straps) Pick up drill & push bit Carry half with rammer to into surface as far as possible HFE Hole #1 (~ 18' W) Remove batt. thermal shield Place box half on surface Energize drill until stem Carry other box half 10' away top approx. 16" above surface place box on surface

Set up HTC/Drill support Place ALSD on HTC

3+30

Attach wrench to bore stem Remove drill from stem Screw 28" bore section to section in surface

3+50

MISSION: APOLLO 16 EVA: 1 -1MAN

TASK FUNCTION EVA EVA ACTIVITIES EVA ACTIVITIES TIME 3+50 Screw drill onto bore section 4+10 DEPLOY LSM Energize drill until stem top Carry LSM to deploy site (50'WSW) approx 16" above surface Remove stowage bracket Deploy legs & verify locked Attach wrench to bore stem Remove drill from stem Set LSM on surface(striped leg E) Screw 28" bore section to section in surface Remove foam packing Energize drill until stem top Deploy sensor arms (center approx 11" above surface one first) Remove sensor dust covers Clean debris from top of LSM Attach wrench to bore stem Raise legs so that PRA Remove drill from stem, cover will clear bottom set on surface Pull striped ring to remove EMPLACE HFE PROBE 1 PRA cover; verify PRA deployed Remove HFE probe from box Level & align LSM Deploy rammer, lean on rack Insert probe and first thermal shield into bore hole, using 4+00 4+20 DEPLOY GEOPHONES Turn Sw 5 - CCW Report probe depth & stem height Pick up T/G from above surface pallet Emplace second thermal shield to 30" depth Walk approx. 8'N with Place sunshield over top of T/G stem, place probe wire N DEPLOY HFE ELECTRONICS Remove HFE elec. box from pallet Remove dust cover (4BB) Get stakes from M/P base. Deploy 1. put 1 in pocket Level & align HFE elec box stake power and geophone cable loops just N of C/S Remove all debris at least 16' away from HFE area Walk out (290°) until 1st geophone is reached Remove geophone clip end geophone #1 Emplace geophone #1 into surface (within 7° of vertical) Walk out 150' until 2nd geophone is reached 4+10 4+30

DATE: APRIL 1972

4+50

MISSION: APOLLO 16 DATE: APRIL 1972 EVA: 1 - 1 MAN TASK FUNCTION EVA EVA **ACTIVITIES** EVA **ACTIVITIES** TIME 4+30 4+50 Do thumper positions 1,6,11,16,21 only Remove geophone clip and geophone #2 Put down T/G Stake geophone cable at geophone #2 Emplace geophone #2 into surface (within 7° of vertical) Walk out 150' until 3rd geophone is reached Remove geophone clip and geophone #3 Emplace geophone #3 into surface (within 7° of vertical) 5+00 SET UP MORTAR PACKAGE Remove flag and emplant by Return to C/S geophone #3 Turn astro sw #5 - CW Unreel remaining power cable Deploy M/P base (pull pin #3) THUMPER GEOPHONE EXP. Insert UHT in M/P base Verify "GO" for thumping Using UHT & M/P base as from MCC sun compass, estimate geophone line heading To fire thumper: Carry M/P and base ~ 50 ft - Select ASI NNE of C/S - Rotate arm switch Place M/P on surface - Wait 4 sec. Deploy M/P base legs(pull pin #4) - Depress switch to fire Using UHT, orient base to same heading as geophone Remain motionless 10 sec. line before and 10 sec. after each thumper firing

5+10

MISSION: APOLLO 16

EVA: 1 - 1 MAN

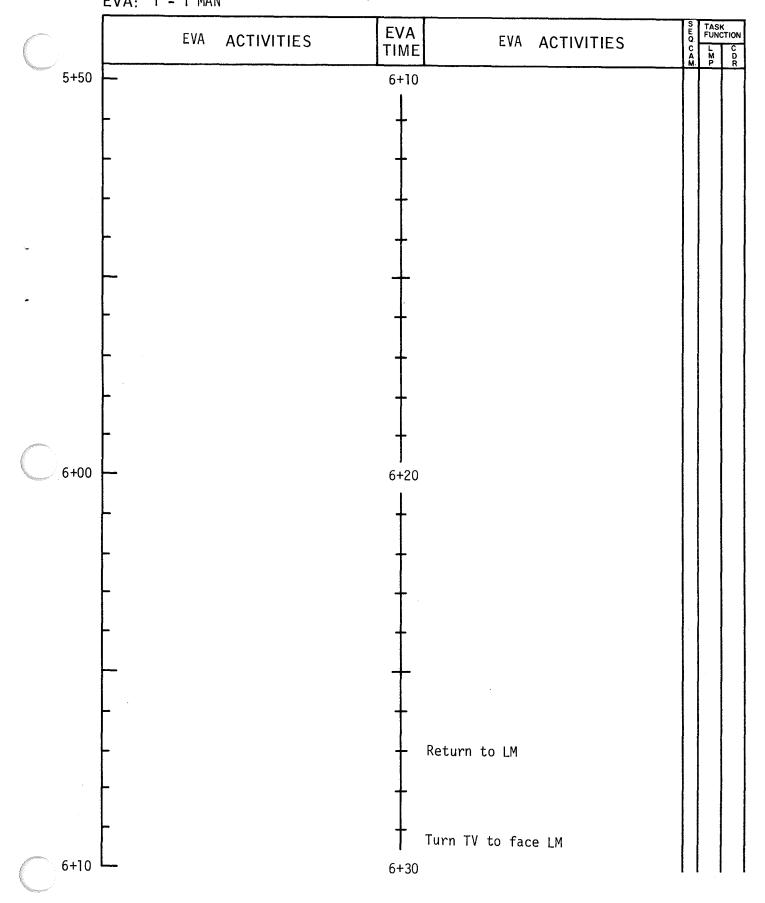
TASK FUNCTION EVA EVA **ACTIVITIES ACTIVITIES** EVA TIME Place base on surface and 5+30 Pick up HTC - move to West 5+10 emplant legs. Verify base for sampling is flat on surface Place M/P on base; front pins 1st, then lock on rear (Note: extent of traverse and posts locale TBD in real time Verify wires in front off base for a 1-man contingency.) Check M/P bubble level reading Deploy M/P antenna Return to C/S Mount HEDC on EMU; leave UHT Check PSE shroud Photo M/P - Down sun; 7 ft. - Viewing NE; 7 ft. - Viewing SE; 7 ft. - With C/S in bkgnd; 15 ft. Arm Mortar package: • Rotate latch with UHT • Remove safety pin (lanyard) • Rotate 2 Safe/Arm switches with UHT Verify alignment and level Position C/S Sw #5 - CCW 5+20 5+40 TAKE ALSEP PHOTOS Coordinate photo activity with CDR thumping Photo: • HFE Bore stems - Down sun, 11 ft (ea.) - Stereo pair, X Sun, 7 ft (ea) • HFE Electronics Box - X Sun, 7 ft. • Panorama S of C/S Xsun photo of C/S taken from North 5+50 5+30

DATE:

**APRIL 1972** 

MISSION: APOLLO 16 EVA: 1 - 1 MAN

DATE: APRIL 1972



MISSION: APOLLO 16

Receive Pallet 1

DATE: APRIL 1972 EVA: 1 - 1 MAN EVA IVA EVA ACTIVITIES **ACTIVITIES** TIME 6+30 Reset Far UV camera Enter azimuth & elevation (verify with MCC) Photo Far UV camera - Xsun; 20 ft, f5.6/60 - Dnsun; 3 ft, f5.6/60 Pack (or Prep) ETB HEDC • Extra mag Map(s) (attach to LEC) Photo CDR; 6+40 Prepare to assist in transfers Prep SCB for transfer Pack SRC 1 (Note: MCC may advise holding SRC 1 over to EVA 2) Deploy SWC 60' at 2:00 | Extend SWC staff sections Press staff into surface Deploy foil; hook on staff Offload Pallet 1 Tidy MESA blankets **TRANSFERS** Ascend ladder with pallet Open hatch

6+50

Pass pallet thru hatch

MISSION: APOLLO 16 EVA: 1 - 1 MAN

SION: APOLLO 16 DATE: APRIL 1972

	IVA ACTIVITIES	EVA TIME	EVA ACTIVITIES	SEQCAM	· 1	CTION C D
	Strip pallet 1 of expendables	6+50	Ascend ladder with SCB			
+		+	Place on platform			
		1	Descend ladder			
			Ascend ladder with			
-	•	+	SRC (if any)			
-	Receive SCB and SRC	<u> </u>	Pass SCB and SRC into cabin			
-	Pass pallet 1 out	+	Jettison Pallet l (watch out for Far UV Camera)			
-	Detach ETB, pass out LEC end	†	Pull up ETB & pass into cabin			
F		+	Drop LEC			
-	Fold EVA PLSS antenna Close hatch	+	Move through hatch			
ŀ			PROCEDURES FOR 1 CLOSEOUT ARE			
		7+00				
		PRESENTED SURFACE C	IN THE "LUNAR HECKLIST"			
-		+				
		T				
-		+				
		T				
-		+				
						•
Γ		T				
F		+				
m <sub>b.i.</sub>		T				
L				}	1	1

# TABLE 4.3-1 CALCULATED DATA EVA 1 ONE MAN EVA

TABLE 4.3-2 INPUT DATA EVA 1 ONE MAN EVA

For a one man EVA 1, geology sampling will be conducted near the LM hence there is no data in the above two tables for a walking traverse.

#### 4.3.2 EVA 2

The LRV is deployed at the beginning of EVA 2 and configured for the traverse which begins about 2 hours into the EVA (See figure 4.3-3).

Approximately 3-3/4 hours are available for the traverse and the crewman returns to the LM with sufficient time to obtain the 2.6 m core which was deferred from EVA 1. Closeout activities occupy the last 45 minutes of EVA 2.

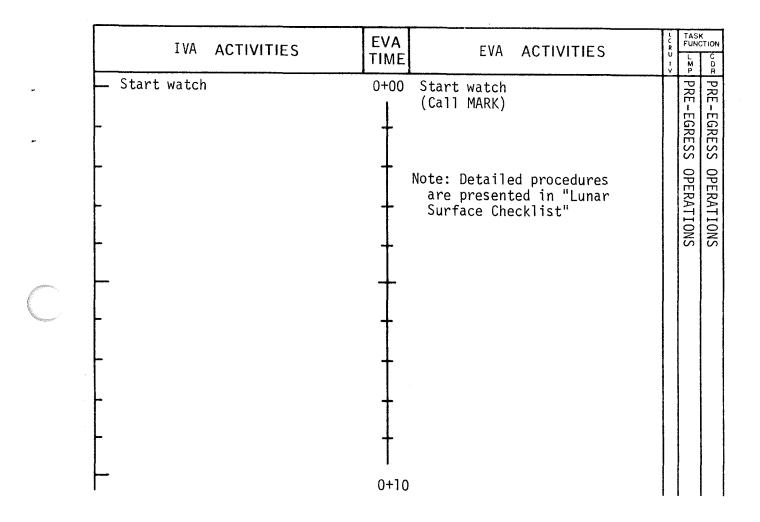
The traverse proceeds first towards the base of Stone Mountain along the same route as the normal LRV traverse. The allotted time for emergency drive-back on the OPS will represent the maximum distance the traverse will be permitted to extend, the distance being a function of LRV speed and will be determined in realtime. If possible, it will be desirable to reach the vicinity of station 5 so that the Descartes Formation can be sampled. (If this is not possible, the first sampling station will be as near to station 5 as the drive-back constraints permit.) Approximately 1 hour will be spent at this station. The traverse will then range over to the vicinity of station 8 where the sampling activities have also been allotted 1 hour. Proceeding northward, 28 minutes will be spent at station 9, at which point the traverse swings over to the outbound LRV tracks and the crewman proceeds back to the LM.

The detailed procedures for EVA 2, One Man EVA are shown in the following pages in a vertical timeline format. A summary of the EVA 2 traverse parameter is presented in the tables that follow the detailed procedures.

APOLLO 16 APRIL 1972

# ONE-MAN TIMELINE

# LUNAR SURFACE EVA 2



MISSION: APOLLO 16 EVA: 2 - 1 MAN

IVA ACTIVITIES	EVA TIME EVA ACTIVITIES	SEQ CAM	TASI FUNC L M P	C D
— Assist	0+10 Move thru hatch	M.	-	R
- Deploy PLSS Antenna (EVA) Place jettison bag in hatch Attach ETB to LEC pass back out	Deploy PLSS Antenna Comm check  Pass LEC into cabin Toss jettison bag to quad I Lower ETB to surface			
	Descend ladder to footpad			
Note; IVA crewman assists EVA crewman as required with procedures & information. He also photos EVA crewman where possible with DAC  (This IVA column will be dropped until end of the EVA to conserve space)	Step to surface  Kick jettison bag under LM  RESET FAR UV CAMERA Punch reset  Enter new azimuth & elevation (Check with MCC for updates)			
	0+20			
	OFFLOAD LRV  Remove LRV thermal blankets Unstow deploy cable; stow on +Z strut Unstow left side deploy tape Verify: • Walking hinges engaged • Chassis parallel alignment • Outrigger cables taut Unstow right side deploy tape			
	Ascend ladder  Pull LRV deploy D-handle verify LRV rotates outboard Descend ladder, pick up deploy cable Pull right side tape until aft wheels on surface & cables slack  0+30			

		EVA TIME		SEG CA	TASI FUNC L M	C D
0+30	— While pulling tape, maintain tension on deploy cable until LRV in walling hinges	0+50	Report: AMP-HR; AMPS VOLTS; TEMPS Verify: PWM SEL sw - BOTH Position: • DR EN LF & RF - PWM 1	3		K
	Pull pin - rt. side outrig. cable	+	● DR EN LR & RR - PWM 2 ● 15 V DC - SEC ● STEER FWD - BUS A			
	Pull pin - left side outrig. cable Pull left side tape until fwd. wheels on surface & cables slack	T	• STEER FWD - BUS A • STEER REAR - BUS D • DR PWR LF & RF - BUS A • DR PWR LR & RR - BUS D			
•	Tug LRV away from LM	+	Drive LRV to MESA area 15 VDC sw - OFF; AUX CB - close			
	Pull pin & discard deploy cable Raise geopallet post	+	,			
	SET UP LRV Deploy left rear fender Verify rear hinge pin - o.k.	+	RETARGET FAR UV CAM Punch reset			
and an investment of the contract of the contr	Erect left seat; unstow seat belt Lower & lock console Pull att. indicator, C&W pins	+	Check film advance Enter new azimuth & elevation (verify with			
0+40	Remove tripod & install toehold Erect left footrest Ver. front hinge pin & steering seal - o.k.	1+00	MCC)  LOAD LRV  Lift LCRU posts on frt. of LRV			
	Deploy left front fender  Deploy right rear fender  Verify rear hinge pin & steer  seal - o.k.  Erect right seat; unstow seat	+	Disconnect Y-cable connectors Discard cable adapters Unstow LCRU from MESA and install on LRV Connect Y-cable conn. to LCRU			
	belt - Lower & lock console Remove tripod & install toehold	+	Unstow TCU from MESA and install on LRV			
	Erect right footrest Verify front hinge pin - o.k. Deploy right front fender - Verify batt. covers closed Place LRV conting. tool on floor	+	Unstow rake, stow on MESA; discard rake bracket Unstow LGA and install on LRV; point ant. straight up			
	CHECKOUT LRV Verify parking brake on Mount LRV Close all CB's except AUX, NAV.	+	Connect LGA cable to LCRU Unstow HGA and install on LRV Remove HGA yellow bracket			
0+50	*Pull on deploy cable during this operation as reg'd	1+10				

MISSION: APOLLO 16 EVA: 2 - 1 MAN

	EVA ACTIVITIES	EVA TIME	EVA ACTIVITIES	L TAS FUN U L T M	K CTION C D B
1+10	Erect ant. mast; lock Connect HGA cable to LCRU; velcro cable to ant. mast Deploy and lock HGA dish Point HGA to earth	1+30	Re-install HTC on pallet		
-	Go to TV camera location  Position TV cam pwr sw - OFF Disconnect TV pwr. cable  Remove TV cam. from tripod and install on LRV (stow TV pwr. cable conn. on LM)  Connect TCU/TV cable to TV  Connect Y-cable conn. to TCU Deploy LCRU VHF antenna  Configure LCRU:  • CB - closed • Mode sw - PM1/NB • Power sw - INT • Report - AGC, TEMP, POWER	+ + + + + + + + + + + + + + + + + + + +	Place SCB on HTC (any 1 of NO's 5-8)  Unstow SRC 2 Place SRC 2 on MESA table*  Open SRC 2  Take out SCB 2 and install on HTC  Close organic Control sample  Unstow DAC; install mag; place on LRV		
1+20	<ul> <li>LCRU Blkts - (MCC)</li> <li>Power sw - EXT</li> <li>Mode sw - FM/TV (2)</li> <li>Verify - AGC &amp; POWER &gt; 2</li> <li>Discard ant. container bracke</li> <li>PALLET ON LRV</li> <li>Carry pallet to LRV and instacheck latches engaged</li> <li>Remove pallet handrails (2)</li> <li>Pull 2 outboard penetro. lanyards</li> <li>Place LPM tripod in bag</li> <li>Place penetro. in pallet hole</li> </ul>	11;	Unstow HEDC from MESA, stow in Take ETB to LRV Install bag shoe on HEDC; Stow under CDR seat: 500mm Cam 3 HEDC mags; 2 DAC mags 2 lens brushes; sun compass I Stow padded bags under LMP seat Install maps/holder on LRV (L s Don HEDC Place ETB on SRC table Tidy MESA Blankets  RETARGET FAR UV CAM Punch reset Check film advance		
1+30	Remove penetro. In parter hote Install vise on pallet top Place gnomon in bag on CDR Se Stow dust brush on LCRU Stow rake in pallet hole	+	Enter new azimuth & elevation (verify with MCC) LRV NAV INITIALIZATION LCRU mode sw - 1 Mount LRV Align LRV NAV system (Ref. LRV Decal) * if SRC 1 held over, put SRC 1 on +Y pad		

Water Comment		EVA ACTIVITIES	EVA TIME	EVA ACTIVITIES		C D R
	1+50	Leave for Station 4 (Stone Mountain)	5+20		/ P	R
•		- Note: number of Stations visited, activities at Stations, and time at Stations TBD in real time between EVA's in the event of a 1 - man EVA. See foregoing discussion for general guidelines	+ + + + + + + + + + + + + + + + + + + +	Return to ALSEP Site		
		-	1	Davies davis LDV		
Marian III				Power down LRV Sw LCRU - Mode 3		
		<b>.</b> 5.	<b>T</b>	Align HGA		
Agglessivitimen.		7	5+30	Dust TV, TCU, & LCRU		
			+	Walk over to HFE area		
		<b>-</b>	+	Activate ALSD momentarily to check operability		
			+	DRILL CORE SAMPLE  Take drill, rack and core stems to deep core site So. of C/S		
			†	Set drill on surface		
		-	+	Lean core stem bag against rack		
			+	Insert core stem with adapter into drill		
		<del>-</del>	+	Pick up drill and push stem into surface as far as possib	 1e	
Comment.	5+20	L	5+40			

MISSION: APOLLO 16 EVA: 2 - 1 MAN

		EVA ACTIVITIES	EVA TIME	EVA ACTIVITIES	ال
5+40		Energize drill until stem top is approx. 12" above surface Attach wrench to core stem Remove drill from stem	6+00	Take core string to LRV; install string in vise on pallet Using wrench, break core string between 3rd & 4th section	
	-	Screw another core stem section to section in surface Screw drill onto core section Energize drill until stem top is approx. 12" above surface	+	Cap ends of core sections  Place stems on floor   of LRV  Mount LRV + 15 VDC Sw - ON	
	- -	Attach wrench to core stem Remove drill from stem Screw last core stem section to section in surface Screw drill onto core section Energize drill until stem top is approx. 8" above surface  Keep drill energized for 15 sec. to clear flutes	e -	Return to LM  EVA CLOSEOUT  Park LRV at MESA; in sun; Heading = 351° + 15 VDC Sw - OFF Dismount LRV LCRU mode Sw - 3 Align HGA  Dust LCRU & GCTA	
5+50	-	15 Sec. to clear fintes	1 6+10		
	-	DRILL CORE RECOVERY  Pull drill string up as far as possible  Attach wrench to core stem	+	Reset Far UV cam.  Punch reset Check film advance Enter new azimuth & elevation	
	-	Remove drill from stem  Retrieve stem caps from rack; cap top  Pull core string out of surface by hand or if difficult:  -assemble jack to treadle -position jack/treadle over core stem in surface -jack core out of surface		PACK SAMPLES  Take SCB(s) off HTC and place on +Z pad  Place SCB 1 in SRC 1  (if still out)  Place SCB 2 in SRC 2*  Note: MCC may advise holding SRC 2	
6+00	L		6+20	over to EVA 3	ŀ

IVA ACTIVITIES	EVA TIME	EVA ACTIVITIES	RUTY	TASK FUNCT L M P
<del>-</del>	TIME  6+20  Place SRC(s) on +Z pad  Bag two core stem strings  Photo pan (20 ft off +Z pad)  Pack ETB: 2 - HEDC w/Mags 2 - 70 MM Mags			
	+	Photo pan (20 ft off +Z pad)		
Photo EVA crew man (tgts of opportunity)	+	2 – HEDC w/Mags		
(tgts of opportunity)	+	3 - DAC Mags		
	+	DAC Batt to		
	+	1 <b>-</b> 500 MM Mag		
<b>-</b>	6+30	Maps		
	+	2 - padded bags		
	1	Take ETB to LM, attach to LEC		
	I	Offload pallet 2		
		Place on +Z pad		
<del>-</del>	<u>†</u>	Punch reset		
•	T			
	7	Enter new azimuth & elevation		
	1	CLOSEOUT TV & LRV		
	<b> </b> 6+40	LCRU pwr. Sw - OFF		

MISSION: APOLLO 16 EVA: 2 - 1 MAN

	IVA ACTIVITIES	EVA TIME	EVA ACTIVITIES	C RU T V	TASH FUNC U L T M V P			
_		6+40	Open LRV batt covers; dust if dirty Dust LCRU			C D F		
_		+	LCRU covers (ask MCC)					
		+	Configure LRV CB's - A, B, C, D - OPEN					
-	TRANSFERS	+	TRANSFERS					
	Open hatch	+	Take pallet 2 up ladder to platform					
-		+	Hand pallet 2 to IVA					
<b>-</b>	Receive pallet 2, Strip & stow expendables	+	Return to surface, pick up stems & SCB's	·				
-	Receive stems & SCB's - Stow Hand out Pallet 2	6+50	Take stems & SCB's up ladder to A/S pass thru hatch Take pallet 2 back to surface, jettison under LM					
-	Receive & Stow SRC(s)	+	Take SRC(s) to A/S pass thru hatch					
-	Receive ETB, detach from LEC, pass LEC	+	Pull up ETB, pass thru hatch					
•	back	+	Drop LEC to surface					
	Fold EVA PLSS antenna	+	INGRESS					
•		+	Move thru hatch					
•	Close hatch	+						
-	NOTE: Detailed final EVA presented surface C	2 clos I in the	eout are : lunar					

TABLE 4.3-3

APOLIO 16 DESCARTES TRAVERSES

EVA II

# CALCULATED DATA

MAR 14 1972

STATION	SEGMENT DISTANCE (KM)	LRV MDBILITY RATE (KM/HR)	RIDE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	1+53	1+53
RIDE 5	4.10	7.30	34	4.10	2+27	1+ 0	3+27
RIDE	2.50	7.30	21				4.47
8 RIDE	0.45	7.30	4	6.60	3+47	1+ 0	4+47
9				7.05	4+51	0+28	5+19
RIDE LM	2.60	7.30	21	9.65	5+40	1+20	7+ 0
TOTALS			80			5+41	7+ 0

# ONE MAN EVA

- STATIONS 4, 6, 7 AND 10 DELETED
- STATION 5 INCREASED FROM 40 MIN TO 1 HR
- STATION 9 INCREASED FROM 25 TO 28 MINUTES

			TF	RAVERSE CI	ONTINGENCI	ES		
			LRV FAIL	.URE		PLSS F	AILURE	
	RETURN	WALKBACK	STATIO	IN MARGIN	ABOVE	MIN LRV	RIDEBACK	
	DISTANCE	TIME	WALKBAC	CK REQUIR	EMENTS	SPEED R	EQUIRED	AVG EVA
STAT	TO LM	TO LM	F₩	20	AMP HRS	0 MIN	10 MIH	MET RATE
NO	CKMD	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KM/HR)	(KM/HR)	(BTU/HR)
LM	0.00	0+ 0	****	****	****	0.00	0.00	1050.00
5	4.10	1+31	2+26	1+38	2+51	3.94	4.69	939.46
_					2+ 9	3.02	3.60	913.80
3	3.15	0+52	1+50	1+ 3				
9	2.60	0+43	1+34	0+47	1+47	2.50	2.97	912.76
LM .	0.00	0+ 0	1+22	0+36	1+12	0.00	0.00	920.44
							33	

TABLE 4.3-4

APDULD 16 DESCARTES TRAVERSES

EVA II

IMPUT DATA

MAR 14 1972

STATION NO	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HERT LEAK (BTU/HR)	-MOBILIT WALK (KM/HR)	Y RATES- RIDE (KM/HR)	MET RATE WALK (BTU/HR)
LM	1+53	0.00	0.00	125.00	3.60	7.30	1560 <b>.</b> p
5	1+ 0	4.10	4.10	125.00	2.70	7.30	1290.0
8	1+ 0	2.50	3.15	125.00	3.60	7.30	1560.0
9	0+28	0.45	2.60	125.00	3.60	7.30	1560.0
LM	1+20	2.60	0.00	125.00	3.60	7.30	1560.0

# ONE MAN EVA

- STATIONS 4, 6, 7 AND 10 DELETED
- STATION 5 INCREASED FROM 40 MIN TO 1 HR
- STATION 9 INCREASED FROM 25 TO 28 MINUTES

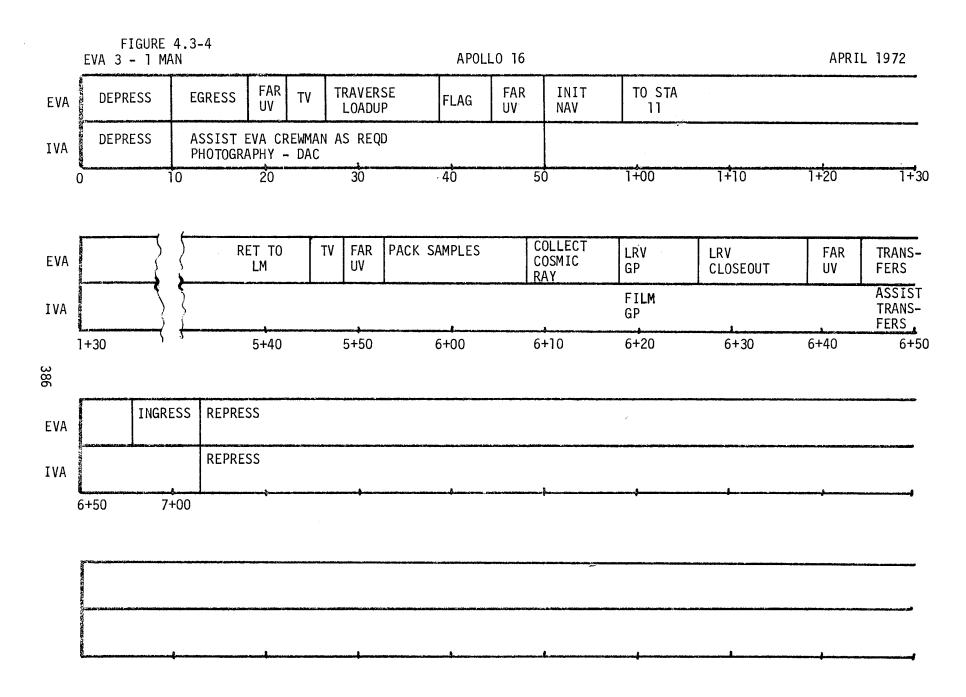
ALSEP	MET RATE RIDING (BTU/HR)	STATION	LM D/H	RATE 02	EVA START (F/W-LB)	EVA START (02-LB)
1050.00	550.00	950.00	1050.00	0.028	11.64	1.353

#### 4.3.3 EVA 3

The traverse gets underway about 1 hour into EVA 3 and approximately 5 hours are available for traverse activities. (See figure 4.3-4.)

Proceeding northward along the nominal route, the traverse objective is to reach the visible ejecta blanket from North Ray crater. Again, the distance reached will be a function of the actual LRV speed over the time allowed for emergency return. At the northernmost limit, a sampling station of 41 minutes duration has been provided. At the completion of this station, the traverse will return to Palmetto Crater where 1-1/2 hours has been allotted to two stations coincident with the nominal stations 16 and 17. Following these stations, the traverse returns to Spook Crater (station 2 on the nominal traverse) for an additional sampling point in the Cayley. Approximately 1 hour is available for this station. Finally, the traverse returns to the LM/ALSEP vicinity where a portion of the nominal station 10 activities are performed. The final hour of the EVA is spent in closeout activities at the LM.

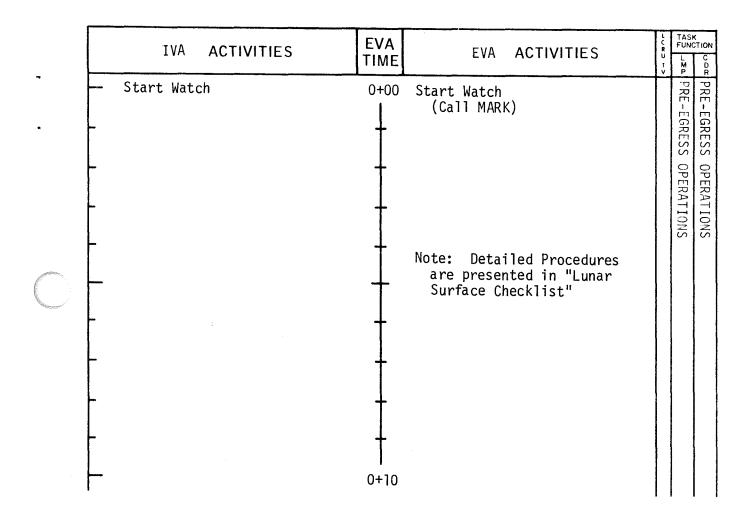
The detailed procedures for EVA 3 shown in the following pages is a vertical timeline format. A summary of the EVA 3 traverse parameters is presented in the tables that follow the detailed procedures.



APOLLO 16 APRIL 1972

# ONE-MAN TIMELINE

# LUNAR SURFACE EVA 3



DATE: APRIL 1972

IVA ACTIVITIE	S EVA	EVA ACTIVITIES	C R U T V	TAS FUN L M P	C D R
Deploy EVA crewman's antenna	0+10	Move thru hatch			
Pass jettison bag out		Toss jettison bag to Quad I area			
Attach ETB to LEC, pass out to EVA Cre	wman	Pass LEC inside cabin Lower ETB to surface			
_ Assist EVA Crewman as required with procedures	+	Descend ladder to surface			
Photo EVA Crewman with DAC	+				
	+	RETARGET FAR UV CAM			
	+	Punch reset Check film advance			
Note: this column wi be dropped until th		Enter new azimuth & elevation Check Batt temp & report BRING UP TV Configure LRV CB's			
end of this EVA to conserve space	†	A, B, C, D. Verify NAV in.			
	†	Close batt covers (verify closure mated)			
	†	LCRU Sw - INT			
-	+	Align HGA			
	. 1	LCRU Covers - 100%			
	T	TRAVERSE LOADUP			
	<del>†</del> .	Take ETB to LRV			
	+	Offload • 2 HEDC's • 2 DAC Mags • 4 70 MM Mags			
	1				

No.		EVA ACTIVITIES	EVA TIME	EVA ACTIVITIES	L C R U	TASH FUNC L M P	C D R
	0+30	Polarizing filter (on HEDC)  Maps Place Mag L on 500 Cam Place I DAC Mag (R) on R seat & (CDR) H Everything else under L seat. Maps in holder  Place mag R on DAC  Take ETB back to MESA	+	Turn TV CCW against stop & horizontal  Mount LRV Power up LRV  Maneuver to nav initialization area and perform initialization per LRV decal	V	P	R
		- Offload LCRU battery from MESA - Stow LCRU battery under CDR seat	+	Leave for Sta. 11			
		- Get flag kit out of MESA	†	Note: duration of time at stations, number of stations, and tasks at			
	0+40	Deploy flag	1+00	stations is TBD in real time for a one-man EVA. Refer to foregoing discussion for pre- mission general guidelines for this			
			+	contingency.			
		Punch reset Check film advance Enter new azimuth & elevation	+				
		Don HEDC  INITIALIZE NAV SYSTEM  SW LCRU Mode - 1	†				
Maritime of the Company of the Compa	0+50	<b>-</b>	1+10		1		İ

MISSION: APOLLO 16 EVA: 3 - 1 MAN

	EVA ACTIVITIES	EVA TIME	EVA ACTIVITIES		TAS FUN L M	CTION C D
1+10		5+50	Check film advance	ľ	P	R
-		+	Enter new azimuth and elevation			
-		+	C101401011			
_		1	PACK SAMPLES			
<i>م</i> لہ		+	Take SCB's off HTC and place on +Z pad			
<del>-</del>		+	(if SRC 2 is held over from EVA 2, place SCB 2 - also held over - in SRC 2 Close SRC 2 & place on +Z pad)			
-		+				
5+40	Return to LM	6+00	Place any large rocks collected (any EVA) in Big Rock Bag (from MESA)			
-	(homeward leg)	+	Place Big Rock Bag on +Z pad			
L			Bring ETB to LRV			
		+	Load: • 5 HEDC mags • 2 DAC mags • Maps			
	ARRIVE AT LM	+	Return ETB to LM SWC			
-	Park LRV near MESA in Sun	+	Photo SWC, 7' upper part Collect foil from mast			
-	Power down & dismount LRV	+	Bag SWC and place in ETB COLLECT COSMIC RAY			
-	LCRU Mode Sw - 3 Align HGA	+	Pull White ring, pin, & remove CRE from			
-	RETARGET FAR UV CAM	+	SEQ Bay			
5+50	Punch reset	<b>1</b> 6+10		ļ		

IVA ACTIVITIES	EVA TIME	EVA ACTIVITIES	C R U	TASK FUNC L M P	CTIO
	6+10	Bring CRE to MESA			T <sup>n</sup>
-	+	Pull blue ring, slide CRE out of frame			
<b>.</b>	+	Report temp labels as they appear - fold CRE			
	+	Bag CRE (Bag in MESA) and place in ETB			
•	+				
_	+	Take drum off penetro- meter			
•	4	Bag in DSB, place in ETB			
		LRV GRAN PRIX			
<ul> <li>Get ready for GP out A/S window</li> </ul>	†	Notify IVA crewman LCRU Mode Sw - 1			
DAC - f8/250/24	+	Mount LRV Power up LRV			
•	+	Drive W in front of LM at distance of			
_	6+20	50 ft			
-	+	Perform GP maneuvers			
Film GP	-	refrorm ar maneuvers			
•	†				
•	+				
	Ī				
- DAC <u>off</u>	+	LRV CLOSEOUT			
		Return to LM and			
-	T	initialize NAV system			
•	+	•			
	$\perp$	Drive on heading of			
	T	085° - 0.1 km (Bearing to LM 265°)			
•	+	CO LIM 200 )			
	6+30				

	IVA ACTIVITIES	EVA TIME	EVA ACTIVITIES	TAC FU	ISK INCTION C I D R
-		6+30	Park LRV on heading of 165°. Closeout per Decal: open all CB xcept AUX, BUS A&C AUX Bypass Sw - ON Align HGA  Dust GCTA & TV Lens  Open LRV Battery Covers Dust batteries if dirty Dust LCRU & tear off 65% cover  Cover LCRU panel with 65% cover  Return to LM with HEDC		
	DOCKING LIGHT TEST CB(T6) LTG Track - CLOSE EXT LTG Sw - TRACK (Report from EVA)  EXT LTG Sw - OFF CB(16) LTG Track - OPEN Receive & stow SCB's	6+40	Place HEDC mag in ETB  FAR UV CAMERA  Punch reset Sw 3 times  Power Sw - OFF  Pull pin on cassette  Twist cassette CW and remove from camera  Place cassette in ETB  Hang ETB from LEC  DOCKING LIGHT TEST  (Observe docking light during transfers)  TRANSFERS  Take SCB's to A/S pass thru hatch  Descend to surface Take SRC 2 (if on		

	IVA ACTIVITIES	EVA TIME	EVA ACTIVITIES	L C R U	TAS FUNI L M P	CTION
_		6+50 	this EVA) & Big Rock Bag to A/S	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	P	R
	Receive SRC 2 & Big Rock Bag - Stow	†	Pass thru hatch			
•		†	Pull up ETB			
•	Receive ETB, detach from LEC. Pass LEC	+	Pass thru hatch			
•	back	+	Drop LEC			
-	Fold EVA PLSS antenna	+	INGRESS Move thru hatch			
, -	Close hatch	Ī				
	NOTE: DETAILED FOR FINAL CLOSEOUT IN THE "L	EVA 3 ARE PRE	ESENTED			
•	CHECKLIST		IN ACE			
		7+00				
•	•	+				
•		+				
•		+				
•		+				
_		+				
•		+				
•		+				
		+				
•		+				
		i '				

TABLE 4.3-5

APOLLO 16 DESCARTES TRAVERSES

EVA III CALCULATED DATA

MAR 14 1972

CTATION	SEGMENT DISTANCE (KM)	LRV MOBILITY RATE (KM/HR)	RIDE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIM)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	0+55	0+55
RIDE 13	3.65	7.30	30	3.65	1+25	0+41	2+ 6
RIDE	0.95	7.30	8	4.60	2+14	0+30	2+44
16 RIDE	0.70	7.30	6				,
17 RIDE	2.25	7.30	18	5.30	2+50	1+ 0	3+50
2	0.90	7.30	7	7.55	4+ 8	1+ 0	5+ 8
RIDE 10		<del>-</del>		8.45	5+15	0+34	5+49
RIDE LM	0.05	7.30	0	8.50	5+50	1+10	7 <b>÷</b> 0
TOTALS			69			5+50	7+ 0
TUTTIES				NE MAN EVA		J.30	0

## ONE MAN EVA

- STATIONS 11, 12, 14 AND 15 DELETED
- STATIONS 2 AND 10 ADDED
- STATION 13 REPOSITIONED AND INCREASED FROM 10 TO 41 MINUTES
- STATION 16 INCREASED FROM 10 TO 30 MINUTES
- STATION 17 INCREASED FROM 38 MIN TO 1 HR

	TRAVERSE CONTINGENCIES										
			LRV FAI:	LURE		PLSS F	AILURE				
	RETURN	WALKBACK	STATI	ON MARCIN	ABOVE	MIN LRV	RIDEBACK				
	DISTANCE	TIME	WALKBA	CK REQUIR	EMENTS	SPEED R	EQUIRED	AVG EVA			
STAT	TO LM	TO LM	FW	88	AMP HRS	NIM 0	10 MIN	MET RATE			
ИΠ	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KMZHR)	(KM/HR)	(BTU/HR)			
LM	0.00	0+ 0	****	++++	****	0.00	0.00	1050.00			
13	3.65	1+21	3+46	3+ 0	4+22	3.50	4.17	898.41			
16	2.70	0+45	3+47	3+ 1	4+20	2.59	3.09	891.25			
17	2.00	0+33	3+ 1	2+15	3+26	1.92	2.29	898.05			
2	0.95	0+16	2+15	1+30	2+25	0.91	1.09	887.28			
1.0	0.05	0+1.1	1+58	1+14	1+59	0.05	0.06	886.24			
LM	0.00	0+ 0	1+ 7	0+22	1+12	0.00	0.00	913.21			

# TABLE 4.3-6

APOLLO 16

DESCARTES TRAVERSES

EVA III

INPUT DATA

MAR 14 1972

STATION ON	STOP TIME (HR+MIM)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTUZHR)	-MOBILITY WALK (KM/HR)	/ RATES- RIDE (KM/HR)	MET RATE WALK (BTU/HR)
LM	0+55	0.00	0.00	180.00	3.60	7.30	1560.0
13	0+41	3.65	3.65	180.00	2.70	7.30	1290.0
16	0+30	0.95	2.70	180.00	3.60	7.30	1560.0
17	1+ 0	0.70	2.00	180.00	3.60	7.30	1560.0
2	1+ 0	2.25	0.95	180.00	3.60	7.30	1560.0
1.0	0+34	0.90	0.05	180.00	3.60	7.30	1560.0
LM	1+10	0.05	0.00	180.00	3.60	7.30	1560.0

# ONE MAN EVA

- STATIONS 11, 12, 14 AND 15 DELETED
- STATIONS 2 AND 10 ADDED
- STATION 13 REPOSITIONED AND INCREASED FROM 10 TO 41 MINUTES
- STATION 16 INCREASED FROM 10 TO 30 MINUTES
- STATION 17 INCREASED FROM 38 MIN TO 1 HR

MET RATE	MET RATE	MET RATE	MET RATE	LEAK	EVA	EVA
ALSEP	RIDING	STATION	LM D/H	RATE 02	START	START
(BTU/HR)	(BTUZHR)	(BTU/HR)	(BTU/HR)	(LB/HR)	(F/W-LB)	(02-LB)
1050.00	550.00	950.00	1050.00	0.035	11.64	1.353

## 4.3.4 One man EVA 1 & 2 after nominal EVA 1

For the case where EVA 1 was the nominal 2 man case, LRV & ALSEP deployment will have been completed, and the one man EVA 2 & 3 cases will take on a somewhat different form than above.

EVA 2 can be performed essentially the same as the nominal LRV EVA 2 with the exception that the radius of action constraint will probably not permit ranging any further than station 5.

Similarly, the one man EVA 3 will take on the same form as the nominal EVA 3 except that the range limit will probably be around station 13. For this case, additional station time will be allocated to doing a more thorough investigation of Palmetto Crater in lieu of North Ray.

# 4.4 Traverses From Off-Nominal Landing Point

Under nominal conditions, the  $3\sigma$  landing dispersion ellipse is approximately  $\pm 1$  km down-range and  $\pm 1.4$  km cross-range. Any landing point within this ellipse is considered nominal and the planned traverse will remain essentially the same. Station times will be adjusted to compensate for the small difference in driving time over those traverses originating from the center of the ellipse.

Certain non-nominal conditions could result in landings outside the above dispersion ellipse. A low thrust descent engine, for example, could result in landing far downrange. The absence of landmark tracking from lunar orbit can result in greater cross-range dispersions and the failure to achieve an update of the position of the landing site relative to the LM just prior to descent initiation can cause large uprange and downrange uncertainties. The magnitude of these latter two effects is shown in Figure 4.4-1.

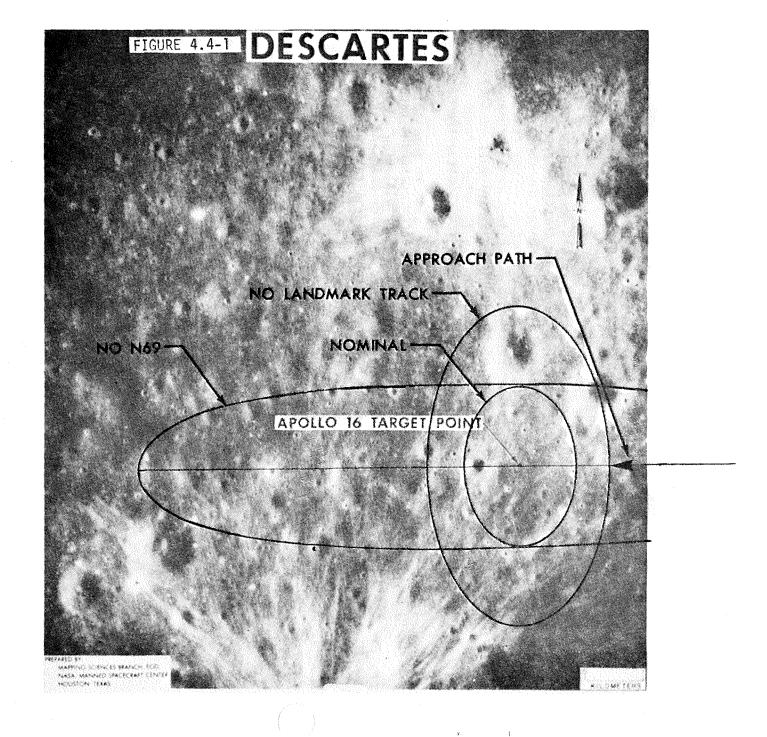
Pre-mission planning of new traverses to accommodate the range of these off-nominal landing points is a prohibitive job. However, certain guidelines can be agreed to beforehand and traverse planning tools can be constructed to facilitate planning when the actual landing point is determined. This section discusses such guidelines and sample traverses are presented to illustrate the effects of off-nominal landing points in attaining the original objectives on EVA's 2 and 3.

### 4.4.1 EVA 1

Rationale for replanning the traverse on EVA 1 must consider the following points:

- (a) Relatively little time will be available for replanning before egress.
- (b) The LM location may be imprecise and uncertain.
- (c) Traverse station time is more limited on EVA 1, therefore, little or no additional driving time should be spent on trying to find or reach the original stations.

Fortunately, the traverse objectives of EVA 1 are sufficiently flexible to accommodate the above considerations. Sampling the Cayley plains in two locations at craters of sufficient size to reveal any stratigraphy is the prime objective of the first traverse. Flag and Spook craters on the nominal traverse are particularly good locations to accomplish this objective, but a multitude of other craters in the Cayley plain also satisfy the criterion.



If the landing point is known, the new traverse will be designed to visit such sampling areas within approximately the same radius as the nominal traverse, with the station times and station activities the same as nominal.\* If the landing point is not known, the crew will seek out such sampling areas that meet the original objectives, within the time limitations available. Finally, if the LM location is still uncertain (after successive attempts by the CMP to locate the LM from orbit), time will be allotted during the traverse to take sun compass sightings (from some nearby promontory) on distant features such as Stone Mountain and Smoky Mountain. Using this information along with the LRV navigational data will allow the ground to determine the LM position prior to EVA 2.

\*The rationale for the LPM site measurement at one of these stations and how it fits in with the other scheduled LPM measurements will be re-evaluated for the new landing point.

### 4.4.2 EVA 2 and 3

The objectives for EVA's 2 and 3 remain the same as for the nominal: Stone Mountain/South Ray ray on EVA 2 and North Ray/Smoky Mountain on EVA 3. The ability to reach these locations and spend sufficient time at them to make it worthwhile, depend of course, on the actual landing point and how much extra driving time is required.

For preliminary planning purposes, it is assumed that the minimum acceptable station times at these primary objectives are 2 hours in the Stone Mountain/South Ray ray region (nominal time for stations 4-8 is 3 hours 13 minutes), and 1-1/2 hours in the North Ray/Smoky Mountain region (nominal time for stations 11-14 is 2 hours 40 minutes).

Considerations will be given to reconfiguring the entire traverse if these minimum times cannot be met.

Figure 4.4-2 can be used as a quick reference to determine new distances to the primary traverse objectives from a wide range of landing points. Subtracting the distances from the nominal landing point and applying the 7.3 km/hr LRV rate used for pre-mission planning will yield the difference in driving time to the objectives from off-nominal landing points. For a more detailed analysis, actual traverse routes must be generated and the new traverse tested against emergency walk-back and drive-back constraints. Two such traverses are included in the following tables for illustrative purposes: EVA 2 traverse from the northerly limit of the no landmark tracking ellipse (see Figure 4.4-1) and EVA 3 from the southerly limit.

FIGURE 4.4-2



Examination of these two cases indicate that EVA 2 from the northerly point meets the criterion of at least 2 hours in the Stone Mountain/South Ray ray vicinity, but the EVA 3 traverse from the southerly point only marginally provides the desired time in the North Ray/Smoky Mountain area. Furthermore, the EVA 3 traverse requires an emergency LRV drive-back speed of 9 km/hr from North Ray for the case where the crewmen had a 10 minute walk-back to the LRV from their sampling location. Unless better than expected trafficability conditions were encountered, this traverse would not be acceptable and considerations would be given by the traverse planning team to reconfiguring EVA 3 to the southwest with South Ray/Baby Ray as the prime objective.

TABLE 4.4-1

APOLLO 16 DESCRITES TRAVERSES

EVA II CALCULATED DATA MAR 14 1972

STATION	SEGMENT DISTANCE (KM)	LRV MOBILITY RATE (KM/HR)	RIDE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIH)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	0+50	0+50
RIDE 4	6.80	7.30	56	6.80	1+46	0+58	2+44
RIDE	0.80	7.30	7	7.60	2+50	0+40	3+30
RIDE	1.40	7.30	12		3+42	0+59	4+41
3 RIDE	2.45	7.30	20	9.00			
9 RIDE	0.55	7.30	5	11.45	5+ 1	0+25	5+26
10 RIDE	2.65	7.30	. 22	12.00	5+31	0+27	5+58
LM	E .00	1.50		14.65	6+19	0+40	6+59
TOTALS			122			4+59	6+59

# 2.6 KM NORTH OFF-NOMINAL LANDING

- STATIONS 6 AND 7 DELETED
- STATION 8 DECREASED 1 MINUTE
- STATION 10 DECREASED FROM 34 TO 27 MINUTES

			TI	RAVERSE CI	ONTINGENCI	ES		
			LRV FAIL	_URE		PLSS F	AILURE	
	RETURN	WALKBACK	STATIO	ON MARGIN	ABOVE	MIN LRV	RIDEBACK	
	DISTANCE	TIME	WALKBAG	CK REQUIR	EMENTS	SPEED R	EQUIRED	AVG EVA
STAT	TO LM	TO LM	FW	02	AMP HRS	O MIN	10 MIN	MET RATE
ПN	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KMZHR)	(KMZHR)	(BTU/HR)
LM	0.00	0+ 0	***	****	****	0.00	0.00	1050.00
4	6.80	2+31	2+ 4	1+17	2+34	6.53	7.77	844.10
5	6.00	2+13	1+43	0+56	2+ 5	5.76	6.86	855.04
3	5.65	2+ 6	0+46	0+ 0	1+ 2	5.42	6.46	862.49
Ģ	3.20	0+53	1+29	0+43	1+30	3.07	3.66	849.90
1.0	2.65	0+44	1+13	0+27	1+ 7	2.54	3.03	853.67
∟M	0.00	0+ 0	1+46	1+ 0	1+13	0.00	0.00	856.62

TABLE 4.4-2

APOLLO 16 DESCARTES TRAVERSES

EVA II

IMPUT DATA

MAR 14 1972

HOITATS ON	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTU/HR)	-MOBILIT WALK (KM/HR)	Y RATES- RIDE (KM/HR)	MET RATE WALK (BTU/HR)
LM	0+50	0.00	0.00	125.00	3.60	7.30	1560.0
4	0+58	6.80	6.80	125.00	2.70	7.30	1290.0
5	0+40	0.80	6.00	125.00	2.70	7.30	1290.0
8	0+59	1.40	5.65	125.00	2.70	7.30	1290.0
9	0+25	2.45	3.20	125.00	3.60	7.30	1560.0
10	0+27	0.55	2.65	125.00	3.60	7.30	1560.0
LM	0+40	2.65	0.00	125.00	3.60	7.30	1560.0

# 2.6 KM NORTH OFF-NOMINAL LANDING

- STATIONS 6 AND 7 DELETED
- STATION 8 DECREASED 1 MINUTE
- STATION 10 DECREASED FROM 34 TO 27 MINUTES

MET RATE	MET RATE	MET RATE	MET RATE	LEAK	EVA	EVA
ALSEP	RIDING	STATION	LM D/H	RATE 02	START	START
(BTU/HR)	(BTU/HR)	(BTU/HR)	(BTU/HR)	(LB/HR)	(F/W-LB)	(02-LB)
1050.00	550.00	950.00	1050.00	0.028	11.64	1.353

TABLE 4.4-3
APOLLO 16 DESCARTES TRAVERSES

EVA III

CALCULATED DATA

MAR 14 1972

MOLTATO	SEGMENT DISTANCE (KM)	LRV MOBILITY RATE (KM/HR)	RIDE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	0+45	0+45
RIDE 11	7.90	7.30	65	7.90	1+50	0+44	2+34
RIDE 12	0.35	7.30	3	8.25	2+37	0+30	3+ 7
RIDE	1.50	7.30	12				
14 RIDE	2.45	7.30	20	9.75	3+19	0+30	3+49
16 RIDE	0.55	7.30	5	12.20	4+ 9	0+10	4+19
17 RIDE	4.85	7.30	40	12.75	4+24	0+36	5+ 0
LM	4.00	1.00	70	17.60	5+40	1+11	6+51
TOTALS			145			4+26	6+51

# 2.6 KM SOUTH OFF-NOMINAL LANDING

- STATIONS 13 AND 15 DELETED
- STATION 11 DECREASED FROM 55 TO 44 MIN
- STATION 12 DECREASED FROM 55 TO 30 MIN
- STATION 14 DECREASED FROM 40 TO 30 MIN
- STATION 17 DECREASED FROM 38 TO 36 MIN

		TRAVERSE CONTINGENCIES							
			LRV FAIL	_URE		PLSS F	AILURE		
	RETURN	WALKBACK	STATIO	ON MARGIN	ABOVE	MIN LRV	RIDEBACK		
	DISTANCE	TIME	WALKBA(	CK REQUIR	EMENTS	SPEED R	EQUIRED	AVG EVA	
STAT	TO LM	TO LM	F₩	02	AMP HRS	O MIN	10 MIN	MET RATE	
ΝП	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KMZHR)	(KM/HR)	(BTU/HR)	
					•				
LM	0.00	0+ 0	****	****	****	0.00	0.00	1050.00	
11	7.90	2+56	1+30	0+43	2+20	7.58	9.03	810.51	
12	7.80	2+53	1+ 1	0+14	1+49	7.49	8.91	828.90	
14	7.00	2+36	0+45	0+ 0	1+24	6.72	8.00	829.75	
16	5.40	2+ 0	1+ 7	0+22	1+30	5.18	6.17	812.66	
17	4.85	1+48	0+44	0+ 0	1+ 1	4.66	5.54	825.19	
LM	0.00	0+ 0	1+41	0+58	1+21	0.00	0.00	837.34	

# TABLE 4.4-4

### APOLLO 16 DESCARTES TRAVERSES

EVA III

INPUT DATA

MAR 14 1973

STATION ON	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTU/HR)	-MOBILITY WALK (KM/HR)	/ RATES- RIDE (KM/HR)	MET RATE WALK (BTU/HR)
LM	0+45	0.00	0.00	180.00	3.60	7.30	1560.0
11	0+44	7.90	7.90	180.00	2.70	7.30	1290.0
12	0+30	0.35	7.80	180.00	2.70	7.30	1290.0
14	0+30	1.50	7.00	180.00	2.70	7.30	1290.0
16	0+10	2.45	5.40	180.00	2.70	7.30	1290.0
17	0+36	0.55	4.85	180.00	2.70	7.30	1290.0
LM	1+11	4.85	0.00	180.00	3.60	7.30	1560.0

# 2.6 KM SOUTH OFF-NOMINAL LANDING

- STATIONS 13 AND 15 DELETED
- STATION 11 DECREASED FROM 55 TO 44 MIN
- STATION 12 DECREASED FROM 55 TO 30 MIN
- STATION 14 DECREASED FROM 40 TO 30 MIN
- STATION 17 DECREASED FROM 38 TO 36 MIN

MET RATE	MET RATE	MET RATE	MET RATE	LEAK	EVA	EVA
ALSEP	RIDING	STATION	LM D/H	RATE 02	START	START
(BTU/HR)	(BTU/HR)	(BTU/HR)	(BTU/HR)	(LB/HR)	(FZW-LB)	(02-LB)
1050.00	550.00	950.00	1050.00	0.035	11.64	1.353

4.5 Shortened EVA's (with prior knowledge before EVA begins)

Under certain circumstances, it may be necessary to shorten the EVA's (duration and number) and replan the traverses accordingly. These circumstances could range from having relatively minor effects such as replanning EVA 2 and 3 based on slightly higher than predicted PLSS consumables usage on EVA 1, to circumstances which could have drastic effects such as a leak in the descent water tank which reduced the lunar surface staytime to only a few hours or less. Figure 4.5-1 provides a chart from which the EVA configurations can be estimated dependent upon the predicted staytime capability.

As in the previous section dealing with off-nominal landing points, there are too many of these situations to permit preplanning. Therefore, this section is limited to discussing general guidelines, providing some planning tools (See Figure 4.5-2) and detailing three cases of specific interest.

In general, with prior knowledge of the situation in terms of EVA time and number of EVA's, the traverses (and other EVA activities) will be replanned in accordance with the priorities previously listed (Experiment, traverse station and station task priorities). In attempting to accomplish as many of these objectives as possible under the circumstances, the traverse planning team must exercise careful judgment in abridging the objectives of a given experiment before proceeding on to embrace the next lower priority experiment. The final product to fit the particular circumstances will receive thorough review by the cognizant elements (science, operations, and management) before implementation.

Three cases are of sufficient interest to warrant a more detailed discussion:

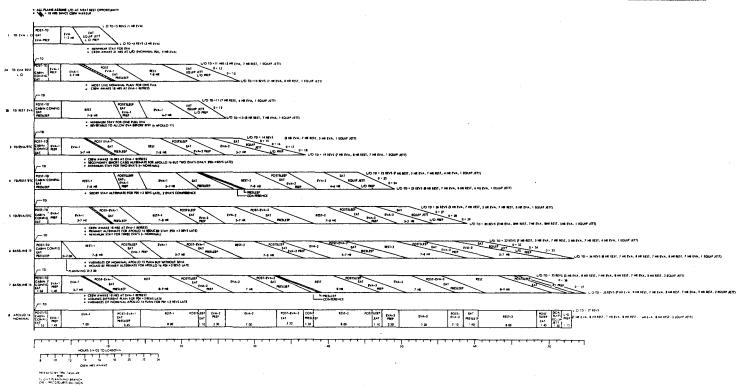
- (a) EVA 1 is shortened by 2 hours as a result of a one rev delay in landing. (Rest requirements on the landing day preclude maintaining the 7 hour EVA 1 for this case.)
- (b) Staytime limitations dictate a single EVA of only "x" hours duration.
- (c) Staytime limitations dictate an absolute minimum lunar staytime resulting in a one man 45 minute EVA. Detailed procedures for this case are shown in the following pages in vertical timeline format.

The first case is accommodated by shortening the LRV traverse from the nominal 2 hour 17 minute to the minimum of 55 minutes and deferring certain activities at the ALSEP site (notably, the 2.6 m core operations) until the end of EVA 2. Thus, in

# FIGURE 4.5-1

#### LUNAR SURFACE EVA CONTINGENCIES

ROMINALLY PLANNED REST PERIODS ARE 6 HOURS DURATION, HOMEYER IN EVENT OF CREW WAKEUP AT 7 HOURS, EVA'S WILL BE SHITLATED WITH 7 HOURS REST

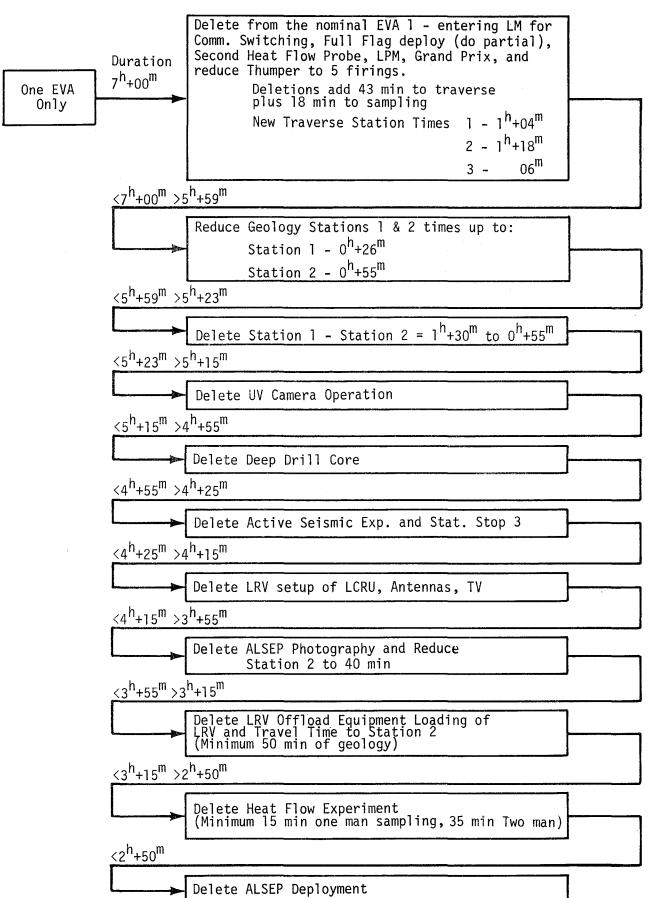


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Guidelines for Alternate Surface Stay Situations the 5 hour EVA 1, the LRV off-loading and outfitting is completed, ALSEP deployment is accomplished, and the minimum EVA 1 geology objectives are obtained. EVA 2 is impacted by about 30 minutes and this is accommodated by the elimination of an equal amount of traverse time.

The second case considered, a single EVA, is diagrammed on figure 4.5-2. In addition to dropping the traverse activities which had been scheduled for EVA 2 & 3, certain other activities (listed on the figure) are dropped at the outset in order to allow additional sampling time in the 7 hr. EVA case. As the EVA time is progressively shortened from 7 hr., this sampling time is reduced to a minimum value, and subsequently ALSEP experiments (and other activities) are dropped in order to maintain this minimum sampling time. Finally, with only a 2 hr. 50 min. EVA time available, ALSEP deployment must be dropped entirely and the available time will be spent in sampling activity.

FIGURE 4.5-2 ONE EVA ONLY CONTINGENCY PLANNING



MISSION: Apollo 16 EVA: ONE MAN - MINIMUM TIME

DATE: March 1972

LMF	ACTIVITIES	EVA TIME	CDR ACTIVITIES	C R U	<b>—</b>	K CTION C D R
				Ť		
•		1				
•		T				
•		†				
-		+.				
		1				
_						
•		Ť				
-		†				
		+				
-		1				
•		0.00.01				
-		0+00 Cr Fe	neck cabin pressure "ZERO" - eedwater - ON			
-		+ Or	pen Hatch			
-		+				
-		⊥ NO	OTE: Detailed procedures are	ŀ		
			presented in "Lunar Surface Checklist", "Equipment Prep EVA 1" section.			
•		†	EVA 1" section.			
_		+				
•		+				
_						
-						
,		†				
-		+				
·		0+10 Mc	ove thru hatch			

DATE: March 1972

MISSION: Apollo 16 EVA: ONE MAN - MINIMUM TIME

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	C R U T V	TASI FUNC L M P	CTION C D D
<del>-</del>	0+10	Move thru hatch			
Pass LEC & ETB to EVA Crewman	+	Deploy LEC with ETB			
	+	Descend to top of ladder Deploy MESA			
•	+	Descend to footpad			
- LM 16mm Seq Cam - ON (12 FPS)	+	Check ascent capability to lower ladder rung			<u>;</u>
NOTE: Monitor & photograph EVA crewman using LM 16mm Seq. Cam.	+	Step to surface			
Read procedures to EVA crewman	+	Check and discuss mobility and stability Report LM status			
	0+20 	Describe LM landing site			
16mm Cam - OFF Change Mag 16mm Cam - ON		Remove HEDC from ETB & obtain +Z panorama			
	†	,			
<del>-</del>	+	Get a containment bag from left side of MESA and fill with rocks & soil			
	+				
	+				
	0+30				

MISSION: Apollo 16 EVA: ONE MAN - MINIMUM TIME

DATE: March 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	C RU	TAS FUN L M P	K CTI
•	0+30		1	Ĺ	T
16mm cam - OFF Change mag 16mm Cam - ON (12 FPS)	+				
·	‡ ‡				
	+	Stow HEDC in ETB			
16mm Cam - OFF	T	Clean EMU			
	0+40	Climb ladder, haul up ETB & containment bag & pass to LMP in the cabin			
Remove 70mm Cam and contingency sample from ETB	+				
Pass ETB to CDR	+	Discard LEC Receive & discard ETB			
	+	Ingress - Go to Post EVA Procedures			
	+				
	†				
_	0+50			İ	

### 4.6 Behind time during EVA

During an EVA, the ground operations team must be prepared to make revisions to the planned EVA to accommodate "lost" time. This could happen as a result of several circumstances: activities could simply take longer than estimated, an unscheduled traverse stop may have occurred because of some unanticipated item of scientific interest, or EMU consumables may be depleting faster than predicted so that the EVA duration will have to be reduced. In general, the priorities discussed previously will be the guidelines for dealing with these cases. However, since there is a high likelihood of encountering the "behind time" situation, several cases have been preplanned in detail. These cases are presented in this section for each EVA.

### 4.6.1 EVA 1

Since EVA 2 and 3 both represent ambitious traverse objectives with little room for accommodating spillover tasks from EVA 1, it will be important to try to accommodate behind time situations on EVA 1 without impacting subsequent EVA's. This is accomplished insofar as possible by allowing the traverse time on EVA 1 to be reduced down to a minimum acceptable value while attempting to complete the planned ALSEP deployment. Beyond this point, portions of the ALSEP area operations are deferred to the end of EVA 2.

Figure 4.6-1 illustrates the logic flow which will be used for the behind time situations on EVA 1. Significant branch points shown in the figure are as follows:

- (a) Station 1 is dropped if EVA is more than 32 minutes behind.
- (b) Gran Prix is dropped from station 3 when EVA is 1 hour behind time.
- (c) LPM site measurement is dropped from station 2 when EVA is 1 hour 08 minutes behind (will be accomplished on EVA 3).
- (d) When the EVA is 1 hour 24 minutes behind, the minimum 55 minutes of traverse activities will be maintained and further delays will impact ALSEP area activities in the order shown.
- (e) For more than 2 hours 29 minutes behind time ALSEP area activities will not be attempted on EVA 1 and the available time will be spent on the traverse which will be essentially the same as the nominal EVA 1 traverse. ALSEP deployment will be rescheduled for the beginning of EVA 2 and about 3 hours will be available for a traverse. Figures 4.6-2 and 4.6-3 illustrate the impact on EVA's 2 and 3 of behind time situations on EVA 1.

FIGURE 4.6-1
EVA 1 OFF NOMINAL PLANNING GUIDE

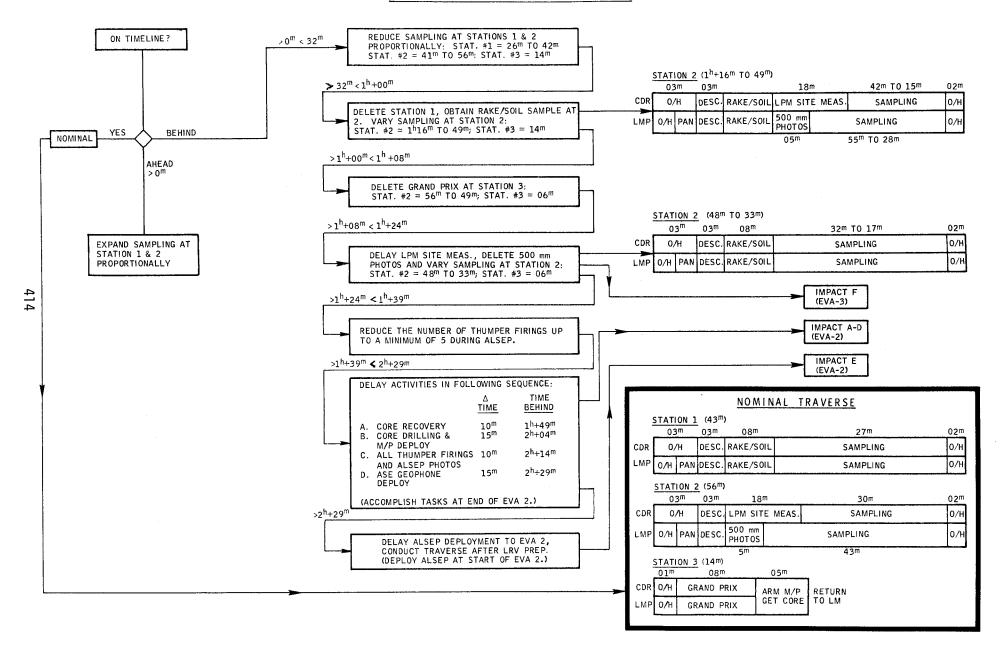
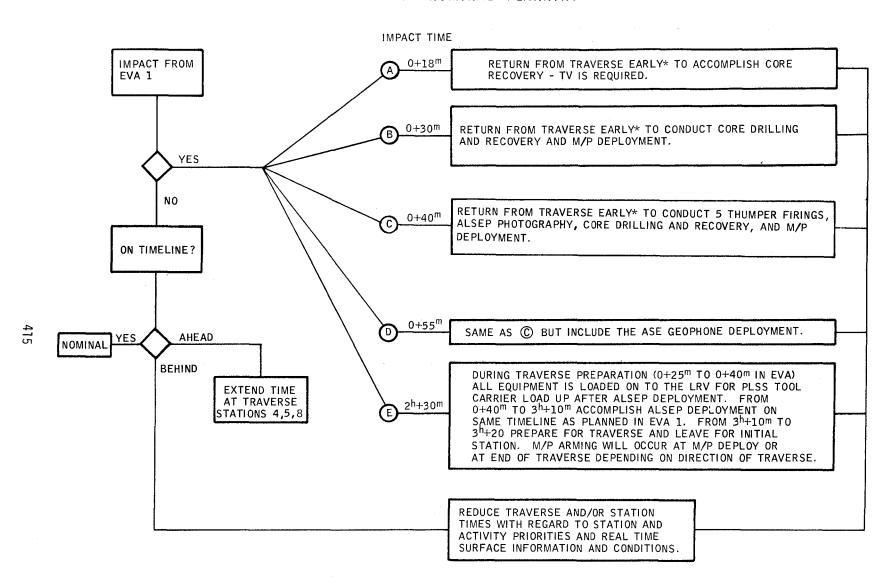
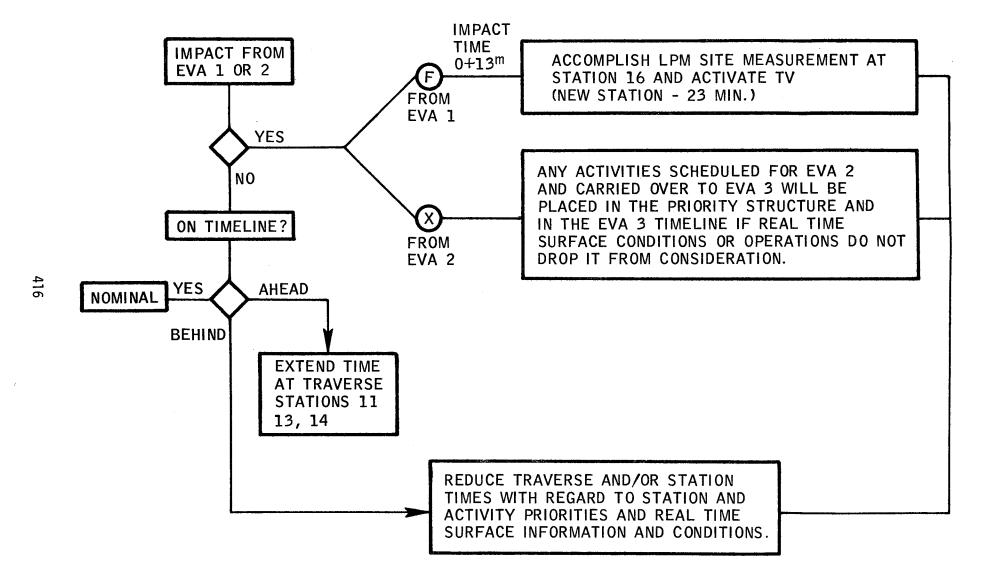


FIGURE 4.6-2
EVA 2 OFF NOMINAL PLANNING



\*NOTE: ANY UNPLANNED EVA 2 CREW ACTIVITIES IN THE LM/ALSEP AREA WILL BE ACCOMPLISHED AFTER THE TRAVERSE SO NOT TO AFFECT THE PLSS CONSUMABLE WALK BACK CONSTRAINTS ON THE TRAVERSE EXCEPT FOR A FULL ALSEP DEPLOYMENT.



### 4.6.2 EVA 2

In general, behind time situations on EVA 2 and 3 will be accommodated by eliminating the lower priority stations from the traverse entirely. However, in cases where these lower priority stations contain activities essential to the success of a given experiment, consideration will be given to reducing the station time at a higher priority station. Traverse replanning which involves reshuffling tasks from one station to another should be avoided as much as possible since this approach unduly complicates crew procedures. As in the previous discussions on contingency traverses, the replanned traverse must be tested against the same emergency walk-back and driveback situations as the nominal traverses. In some cases, this will result in having to depart a high priority station at the extremity of the traverse and subsequently to include a lower priority station nearer the LM.

The following cases are discussed briefly as examples of EVA 2 traverse changes for various behind time situations leaving the LM vicinity:

- (a) 30 minutes behind: delete station 7, delete station 9, move CSVC sample from 9 to 8 (increasing station 8 time to provide for CSVC task) and perform surface sampler activity on EVA 3.
- (b) 60 minutes behind: same as above plus delete station 10.
- (c) 90 minutes behind: same as above, plus delete station 6 and reduce stations 4 5 by 10 minutes.
- (d) >90 minutes behind: consider reorienting entire traverse since Stone Mountain/South Ray ray station times are near minimum.

### 4.6.3 EVA 3

EVA 3 replanning is not as straightforward an application of station priorities as EVA 2 since the nominal margins at the distant stations are not as great.

The following cases are discussed briefly to illustrate various behind time situations on EVA 3:

- (a) 30 minutes behind time: delete station 15; reduce 11-12 station time by 20 minutes (see following tables for new traverse tabulations)
- (b) 55 minutes behind time: since previous case showed only a 19 minute 0<sub>2</sub> margin at station 14, 6 minutes must be reduced from 11-14 area to maintain walk-back; therefore, the new traverse will show deletion of station 15, reduction in 11-12 time by 20 minutes, reduction in station 14 time to 30 minutes and reduction of station 17 time by 15 min. (See following table for new traverse tabulations.)
- (c) 70 minutes behind time: same as case "b" plus deletion of station 13
- (d) >70 minutes behind time: further reductions in station 11-12 time below 1-1/2 hours and station 14 time below 30 minutes make achieving the original objectives of EVA 3 questionable. Consideration should be given to reorienting the EVA to concentrate on only one of the two objectives depending on how well the Cayley and Descartes materials were investigated on EVA's 1 and 2.

TABLE 4.6-la

### APOLLO 16 DESCARTES TRAVERSES

EVA II CALCULATED DATA APR 4 1972

STATION	SEGMENT DISTANCE (KM)	LRV MOBILITY RATE (KM/HR)	RIDE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	1+20	1+20
RIDE 4	4.20	7.30	35	4.20	1+55	0+58	2+53
₽IDE 3	0.80	7.30	7	5.00	2+59	0+40	3+39
RIDE	0.40	7.30	3			•	-
6 RIDE	1.00	7.30	8	5.40	3+42	0+20	4+ 2
8 RIDE	3.05	7.30	25	6.40	4+11	1+10	5+21
1 0				9.45	5+46	0+34	6+20
RIDE LM	0.05	7.30	0	9.50	6+20	0+40	7+ 0
TOTALS			78			5+42	7+ 0

### 30 MINUTE BEHIND TIME CONTINGENCY

### NOTES:

- STATIONS 7 AND 9 DELETED
- STATION 8 INCREASED FROM 1 HOUR TO 1 HOUR + 10 MINUTES

			TI	RAVERSE C	ONTINGENCI	ES				
	RETURN	WALKBACK	STATI	ON MARGIN	ABOVE	MIN LRV	RIDEBACK			
	DISTANCE	TIME	WALKBA	CK REQUIR	EMENTS	SPEED R	EQUIRED	AVG EVA		
STAT	TO LM	TO LM	F₩	<b>0</b> 2	AMP HRS	0 MIN	10 MIN	MET RATE		
	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KMZHR)	(KMZHR)	(BTU/HR)		
LM	0.00	0+ 0	****	****	****	0.00	0.00	1050.00		
4	4.20	1+33	3+ 0	2+13	3+23	4.03	4.80	916.33		
5	3.40	0+57	2+50	2+ 3	3+13	3.26	3.89	911.49		
6	3.00	0+50	2+38	1+51	2+57	2.88	3.43	909.76		
8	3.05	0+51	1+22	0+34	1+38	2.93	3.49	909.32		
10	0.05	0+ 1	1+47	1+ 1	1+28	0.05	0.06	889.24		
LM	0.00	0+ 0	1+28	0+42	1+12	0.00	0.00	904.22		

### TABLE 4.6-1b

### APOLLO 16 DESCARTES TRAVERSES

EVA II

INPUT DATA

APR 4 1972

STATION NO	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTU/HR)	-MOBILIT' WALK (KM/HR)	Y RATES- RIDE (KM/HR)	MET RATE WALK (BTU/HR)
LM	1+20	0.00	0.00	125.00	3.60	7.30	1560.0
4	0+58	4.20	4.20	125.00	2.70	7.30	1290.0
5	0+40	0.80	3.40	125.00	3.60	7.30	1560.0
6	0+20	0.40	3.00	125.00	3.60	7.30	1560.0
8	1+10	1.00	3.05	125.00	3.60	7.30	1560.0
10	0+34	3.05	0.05	125.00	3.60	7.30	1560.0
LM	0+40	0.05	0.00	125.00	3.60	7.30	1560.0

# 30 MINUTE BEHIND TIME CONTINGENCY

### NOTES:

- STATIONS 7 AND 9 DELETED
- STATION 8 INCREASED FROM 1 HOUR TO 1 HOUR + 10 MINUTES

MET KHIE	MET RHIE	MET RHIE	MET RHIE	LEHK	EVA	EVA	OPS
ALSEP	RIDING	STATION	LM D/H	RATE 02	START	START	TIME
(BTU/HR)	(BTU/HR)	(BTU/HR)	(BTUZHR)	(LB/HR)	(F/W-LB)	(02-LB)	(MIN)
1050.00	550.00	950.00	1050.00	0.028	11.64	1.353	62.5

MOTE: OPS TIME IS TOTAL DRIVING TIME AVAILABLE!



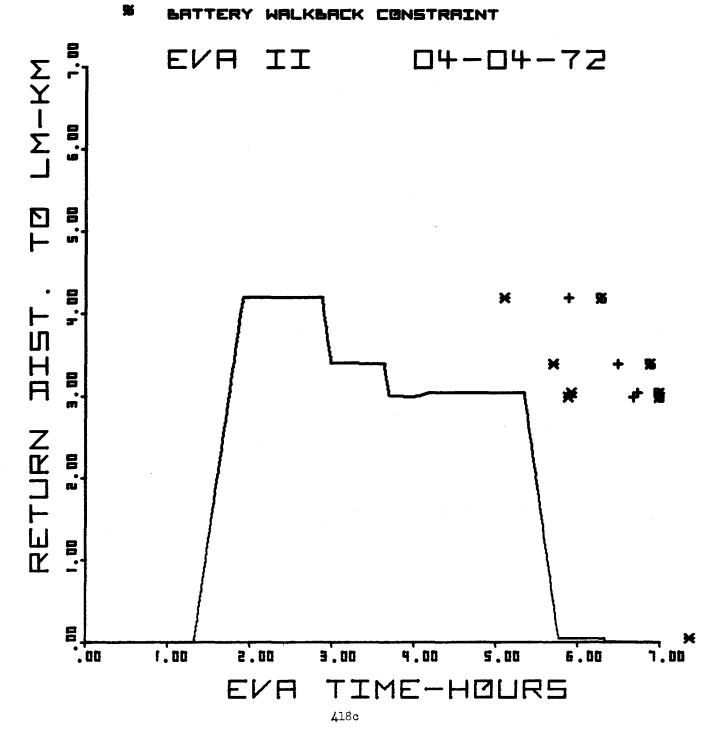


TABLE 4.6-2a

## APOLLO 16 DESCARTES TRAVERSES

EVA II

### CALCULATED DATA

APR 4 1972

STATION	SEGMENT DISTANCE (KM)	LRV MOBILITY RATE (KM/HR)	RIDE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	1+50	1+50
RIDE 4	4.20	7.30	35	4.20	2+25	0+58	3+23
RIDE	0.80	7.30	7	4.60	CTCJ	UTJO	STES
5	0.40	7.30	3	5.00	3+29	0+40	4+ 9
RIDE 6	0.40	7.30	3	5.40	4+12	0+20	4+32
RIDE	1.00	7.30	8				
8 RIDE	3.05	7.30	25	6.40	4+41	1+13	5+54
LM	J.05	1.50		9.45	6+19	0+40	6+59
TOTALS			78			5+41	6+59

### 60 MINUTE BEHIND TIME CONTINGENCY

## NOTES:

- STATIONS 7, 9 AND 10 DELETED
- STATION 8 INCREASED FROM 1 HOUR TO 1 HOUR + 13 MINUTES

			TI	RAVERSE CI	ONTINGENCI	ES		
			LRV FAIL	LURE		PLSS F	AILURE	
	RETURN	WALKBACK	STATI	ON MARGIN	ABOVE	MIN LRV	RIDEBACK	
	DISTANCE	TIME	WALKBA	CK REQUIR	EMENTS	SPEED R	EQUIRED	AVG EVA
STAT	TO LM	TO LM	F₩	02	AMP HRS	0 MIN	10 MIN	MET RATE
ΝO	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KMZHR)	(KMZHR)	(BTU/HR)
LM	0.00	0+ 0	****	****	****	0.00	0.00	1050.00
4	4.20	1+33	2+28	1+40	2+53	4.03	4.80	936.13
5	3.40	0+57	2+18	1+30	2+43	3.26	3.89	928.17
6	3.00	0+50	2+ 6	1+18	2+27	2.88	3.43	925.21
S	3.05	0+51	0+46	0+ 0	1+ 5	2.93	3.49	921.60
LM	0.00	0+ 0	1+27	0+41	1+13	0.00	0.00	911.62

### TABLE 4.6-2b

APOLLO 16 DESCARTES TRAVERSES

EVA II

INPUT DATA

APR 4 1972

STATION NO	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTU/HR)	-MOBILIT WALK (KM/HR)	Y RATES- RIDE (KM/HR)	MET RATE WALK (BTU/HR)
LM	1+50	0.00	0.00	125.00	3.60	7.30	1560.0
4	0+58	4.20	4.20	125.00	2.70	7.30	1290.0
5	0+40	0.80	3.40	125.00	3.60	7.30	1560.0
6	0+20	0.40	3.00	125.00	3.60	7.30	1560.0
8	1+13	1.00	3.05	125.00	3.60	7.30	1560.0
LM	0+40	3.05	0.00	125.00	3.60	7.30	1560.0

# 60 MINUTE BEHIND FIME CONTINGENCY

# NOTES:

- STATIONS 7, 9 AND 10 DELETED
- STATION 8 INCREASED FROM 1 HOUR TO 1 HOUR + 13 MINUTES

MET RATE	MET RATE	MET RATE	MET RATE	LEAK	EVA	EVA	OPS
ALSEP	RIDING	STATION	LM D/H	RATE 02	START	START	TIME
(BTUZHR)	(BTU/HR)	(BTU/HR)	(BTUZHR)	(LB/HR)	(F/W-LB)	(02-LB)	(MIN)
1050.00	550.00	950.00	1050.00	0.028	11.64	1.353	62.5

NOTE: OPS TIME IS TOTAL DRIVING TIME AVAILABLE!

# APOLLO 16-LRV TRAVERSE

- X 02 WALKBACK CONSTRAINT
- + FW WALKBACK CONSTRAINT
- S BATTERY WALKBACK CONSTRAINT

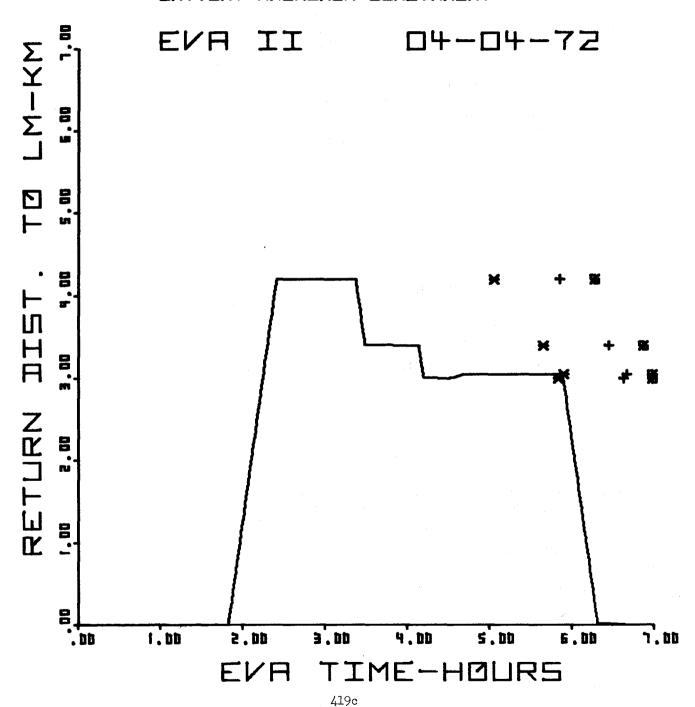


TABLE 4.6-3

### APOLLO 16 DESCARTES TRAVERSES

EVA II CALCULÁTED DATA APR 4 1972

STATION	SEGMENT DISTANCE (KM)	LRV MOBILITY RATE (KM/HR)	RIDE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	2+20	2+20
RIDE 4	4.20	7.30	35	4.20	2+55	0+53	3+48
RIDE	0.80	7.30	7				
5 RIDE	1.40	7.30	12	5.00	3+54	0+35	4+29
3				6.40	4+41	1+10	5+51
RIDE LM	3.05	7.30	25	9.45	6+16	0+40	6+56
TOTALS			79			5+38	6+56

### 90 MINUTE BEHIND TIME CONTINGENCY

### NOTES:

- STATIONS 6, 7, 9 AND 10 DELETED
- STATIONS 4 AND 5 EACH DECREASED BY 5 MINUTES
- STATION 8 INCREASED FROM 1 HOUR TO 1 HOUR + 10 MINUTES

			TF	RAVERSE CI	ONTINGENCI	ES		
			LRV FAIL	URE		PLSS F	AILURE	
	RETURN	WALKBACK	STATIO	IN MARGIN	ABOVE	MIN LRV	RIDEBACK	
	DISTANCE	TIME	WALKBAO	CK REQUIR	EMENTS	SPEED R	EQUIRED	AVG EVA
STAT	TO LM	TO LM	₽₩	02	AMP HRS	0 MIN	10 MIN	MET RATE
МП	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KMZHR)	(KM/HR)	(BTU/HR)
LM	0.00	0+ 0	****	****	****	0.00	0.00	1050.00
4	4.20	1+33	2+ 0	1+13	2+28	4.03	4.80	950.84
5	3.40	0+57	1+55	1+8	2+23	3.26	3.89	940.94
8	3.05	0+51	0+47	0+ 0	1+8	2.93	3.49	929.92
∟M	0.00	0+ 0	1+27	0+41	1+16	0.00	0.00	918.56

### TABLE 4.6-4

### APOLLO 16 DESCARTES TRAVERSES

EVA II

INPUT DATA

APR 4 1972

STATION NO	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTU/HR)	-MOBILITY WALK (KM/HR)	/ RATES- RIDE (KM/HR)	MET RATE WALK (BTU/HR)
LM	2+20	0.00	0.00	125.00	3.60	7.30	1560.0
4	0+53	4.20	4.20	125.00	2.70	7.30	1290.0
5	0+35	0.80	3.40	125.00	3.60	7.30	1560.0
8	1+10	1.40	3.05	125.00	3.60	7.30	1560.0
LM	0+40	3.05	0.00	125.00	3.60	7.30	1560.0

### 90 MINUTE BEHIND TIME CONTINGENCY

### NOTES:

- STATIONS 6, 7 AND 10 DELETED
- STATIONS 4 AND 5 EACH DECREASED BY 5 MINUTES
- STATION 8 INCREASED FROM 1 HOUR TO 1 HOUR + 10 MINUTES

ALSEP	RIDING	STATION	MET RATE LM O/H (BTU/HR)	RATE 02	START		
1050.00	550.00	950.00	1050.00	0.028	11.64	1.353	62.5

MOTE: OPS TIME IS TOTAL DRIVING TIME AVAILABLE!

# APOLLO 16-LRV TRAVERSE

- × 02 WALKBACK CONSTRAINT
- + FW WALKBACK CONSTRAINT
- BATTERY WALKBACK CONSTRAINT

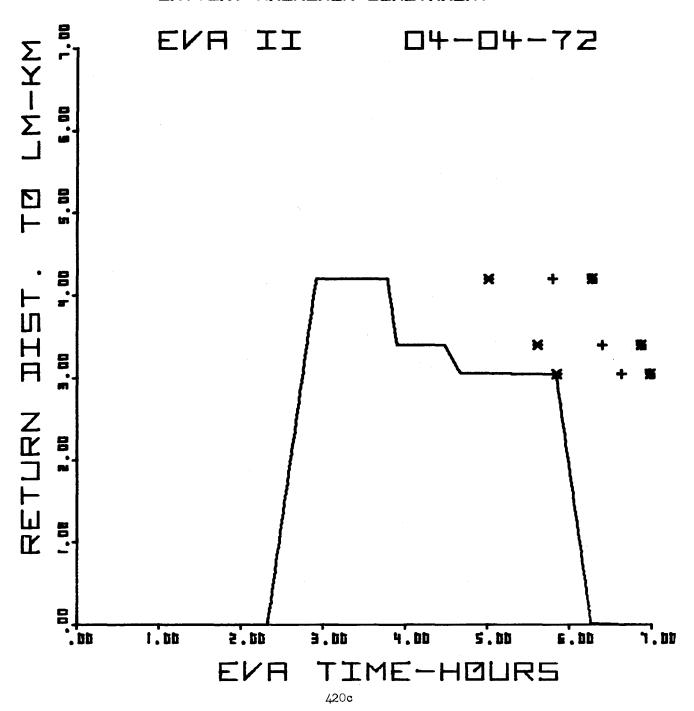


TABLE 4.6-5 APOLLO 16 DESCARTES TRAVERSES

EVA III

CALCULATED DATA

MAR 7 1972

### 30 MINUTES BEHIND TIME CONTINGENCY

	SEGMENT	LRV MOBILITY	RIDE	TOTAL TRAVEL	ARRIVE STATION	STOP	DEPART STATION
	DISTANCE	RATE	TIME	DISTANCE	EVA TIME	TIME	EVA TIME
STATION	(KM)	(KM/HR)	(MIN)	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)
LM RIDE	5.30	7.30	44	0.00	0+ 0	1+15	1+15
11				5.30	1+59	0+45	2+44
RIDE 12	0.35	7.30	3	5.65	2+46	0+45	3+31
RIDE 13	0.65	7.30	5	6.30	3+37	0+10	3+47
RIDE	0.85	7.30	7			" <del></del>	
14 RIDE	1.35	7.30	11	7.15	3 <b>+54</b>	0+40	4+34
15 RIDE	1.65	7.30	14	8.50	4+45	0+10	4+55
17		-		10.15	5+ 8	0+38	5+46
RIDE LM	2.25	7.30	18	12.40	6+ 5	0+55	7+ 0
TOTALS			102			5+18	7+ 0

NOTE:

STATION 16 DELETED
STATIONS 11 AND 12 EACH DECREASED BY 10 MINUTES

	TRAVERSE CONTINGENCIES									
			LRV FAIL	LURE		PLSS F	AILURE			
	RETURN	WALKBACK	STATIO	ON MARGIN	ABOYE	MIN LRV	RIDEBACK			
	DISTANCE	TIME	WALKBAG	CK REQUIR	EMENTS	SPEED R	EQUIRED	AVG EVA		
STAT	TO LM	TO LM	FW	02	AMP HRS	O MIN	10 MIN	MET RATE		
ND	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KM/HR)	(KMZHR)	(BTU/HR)		
LM	0.00	0+ 0	****	****	****	0.00	0.00	1050.00		
11	5.30	1+58	2+25	1+38	3+ 8	5.09	6.06	88 <del>9</del> .32		
12	5.20	1+56	1+41	0+54	2+22	4.99	5.94	897.62		
13	4.70	1+44	1+41	0+55	2+18	4.51	5.37	891.74		
14	4.40	1+38	1+ 5	0+19	1+37	4.22	5.03	891.53		
15	3.40	0+57	1+28	0+42	1+57	3.26	3.89	880.66		
17	2.25	0+37	1+ 9	0+24	1+25	2.16	2.57	875.32		
LM	0.00	0+ 0	1+17	0+32	1+12	0.00	0.00	883.87		

TABLE 4.6-6
APOLLO 16 DESCARTES TRAVERSES

EVA III

INPUT DATA

MAR 7 1972

STATION ON	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTU/HR)	-MOBILIT WALK (KM/HR)	Y RATES- RIDE (KM/HR)	MET RATE WALK (BTU/HF)
LM	1+15	0.00	0.00	180.00	3.60	7.30	1560.0
11	0+45·	5.30	5.30	180.00	2.70	7.30	1290.0
12	0+45	0.35	5.20	180.00	2.70	7.30	1290.0
13	0+10	0.65	4.70	180.00	2.70	7.30	1290.0
14	0+40	0.85	4.40	180.00	2.70	7.30	1290.0
15	0+10	1.35	3.40	180.00	3.60	7.30	1560.0
17	0+38	1.65	2.25	180.00	3.60	7.30	1560.0
LM	0+55	2.25	0.00	180.00	3.60	7.30	1560.0

MET RATE	MET RATE	MET RATE	MET RATE	LEAK	EVA	EVA
	•		LM D/H			START
(BTU/HR)	(BTU/HR)	(BTU/HR)	(BTU/HR)	(LB/HR)	(F/W-LB)	(05-FB)
1050.00	550.00	950.00	1050.00	0.035	11.64	1.353

TABLE 4.6-7 APOLLO 16 DESCARTES TRAVERSES

EVA III

### CALCULATED DATA

MAR 7 1972

55 MINUTES BEHIND TIME CONTINGENCY

STATION	SEGMENT DISTANCE (KM)	LRV MOBILITY RATE (KM/HR)	RIDE TIME (MIN)	TOTAL TRAVEL DISTANCE (KM)	ARRIVE STATION EVA TIME (HR+MIN)	STOP TIME (HR+MIN)	DEPART STATION EVA TIME (HR+MIN)
LM				0.00	0+ 0	1+40	1+40
RIDE 11	5.30	7.30	44	5.30	2+24	0+45	3+ 9
RIDE 12	0.35	7.30	3	5.65	3+11	0+45	3+56
RIDE	0.65	7.30	5.				
13 RIDE	0.85	7.30	7	6.30	4+ 2	0+10	4+12
14 RIDE	1.35	7.30	11	7.15	4+19	0+30	4+49
15				8.50	5+ 0	0+10	5+10
RIDE 17	1.65	7.30	14	10.15	5+23	0+23	5+46
RIDE LM	2.25	7.30	18	12.40	6+ 5	0+55	7+ 0
				16.70	0. 5	0+33	1 + 0
TOTALS			102			5+18	7+ 0

NOTES:

STATION 16 DELETED

STATIONS 11, 12, and 14 EACH DECREASED BY 10 MINUTES STATION 17 DECREASED BY 15 MINUTES

			TF	RAVERSE CI	ONTINGENCI	ES		
			LRV FAIL	_URE		PLSS/F	AILURE	
	RETURN	WALKBACK	STATIO	ON MARGIN	ABOVE	MIN LRV	RIDEBACK	
	DISTANCE	TIME	WALKBAC	CK REQUIR	EMENTS	SPEED R	EQUIRED	AVG EVA
STAT	TO LM	TO LM	FW	02	AMP HRS	NIM 0	10 MIN	MET RATE
NΠ	(KM)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(HR+MIN)	(KMZHR)	(KMZHR)	(BTU/HR)
								* 4
LM	0.00	0+ 0	****	****	****	0.00	0.00	1050.00
11	5.30	1+58	1+58	1+11	2+43	5.09	6.06	910.62
12	5.20	1+56	1+14	0+27	1+57	4.99	5.94	913.73
13	4.70	1+44	1+14	0+28	1+53	4.51	5.37	907.45
14	4.40	1+38	0+48	0+ 2	1+22	4.22	5.03	903.23
15	3.40	0+57	1+11	0+25	1+42	3.26	3.89	892.09
17	2.25	0+37	1+ 7	0+22	1+25	2.16	2.57	882.54
LM	0.00	0+ 0	1+15	0+30	1+12	0.00	0.00	889.83

# TABLE 4.6-8

APOLLO 16 DESCARTES TRAVERSES

EVA III

INPUT DATA

MAR 7 1972

STATION MQ	STOP TIME (HR+MIN)	SEGMENT DISTANCE (KM)	RETURN DISTANCE (KM)	HEAT LEAK (BTU/HR)	-MOBILIT WALK (KMZHR)	Y RATES- RIDE (KM/HR)	MET RATE WALK (BTU/HR)
LM	1+40	0.00	0.00	180.00	3.60	7.30	1560.0
11	0+45	5.30	5.30	180.00	2.70	7.30	1290.0
12	0+45	0.35	5.20	180.00	2.70	7.30	1290.0
13	0+10	0.65	4.70	180.00	2.70	7.30	1290.0
14	0+30	0.85	4.40	180.00	2.70	7.30	1290.0
15	0+10	1.35	3.40	180.00	3.60	7.30	1560.0
17	0+23	1.65	2.25	180.00	3.60	7.30	1560.0
LM	0+55	2.25	0.00	180.00	3.60	7.30	1560.0

MET RATE	MET RATE	MET RATE	MET RATE	LEAK	EVA	EVA
ALSEP	RIDING	STATION	LM D/H	RATE 02	START	START
(BTUZHR)	(BTU/HR)	(BTUZHR)	(BTUZHR)	(LB/HR)	(FZW-LB)	(02-LB)
1050.00	550.00	950.00	1050.00	0.035	11.64	1.353

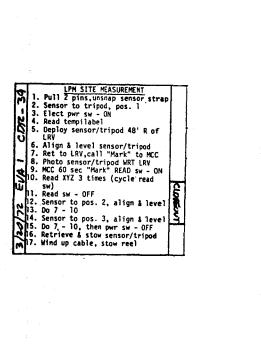
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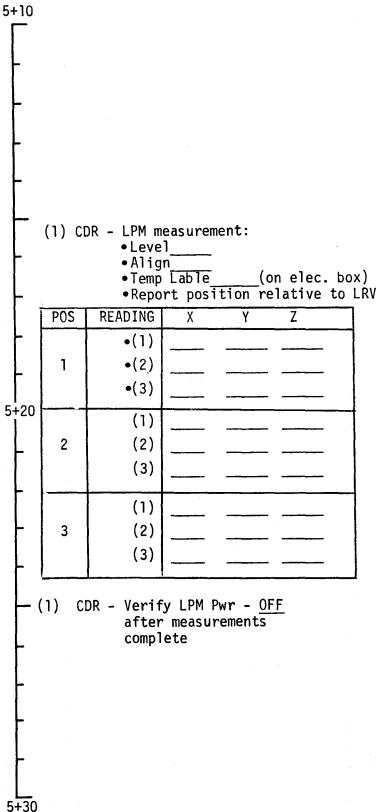
The following pages are referred to in instruction 4 of the preface to this supplement.

MISSION: APOLLO 16 EVA: 1

DATE: MARCH 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES	SE C C A	TASI FUNC L M	CTION C D
	4+50		M.	Р	R
Stow ext. handle/scoop on HTC	+150	Stow gnomon in LRV bag		GY STATION 1 (CONT'D)	GY STATION 1 (CONT'D)
<ul><li>Verify HTC is secure</li><li>Mount LRV</li></ul>	+	LCRU mode sw-1; pos. TV horiz, CC Mount LRV	¥	GEOLOGY	GEOLOGY
· •	1	Configure LRV per decal  TRAVERSE TO STATION 2			
TRAVERSE TO STATION 2  Drive to Station 2	+	Drive to Station 2		STAT. 2	STAT. 2
<del></del>	5+00   			TO GEO.	. TO GEO.
SPOOK CRATER  GEOLOGY STATION 2	+	SPOOK CRATER  GEOLOGY STATION 2  Park I BY a Honding and 1998		TRAV.	TRAV
Read LRV displays  Dismount LRV Take photo pan  Describe surrounding area	+	Park LRV; Heading = 180°  Set brake  ± 15 VDC Sw - OFF  Dismount LRV  LCRU mode Sw - 2  Align HGA to earth  Dust GCTA, LCRU & TV lens  Describe surrounding area		GEOLOGY STATION 2	GEOLOGY STATION 2
Take 500 mm cam. photos	5+10	Perform LPM site measurement  ● Sensor position #1,#2,#3			



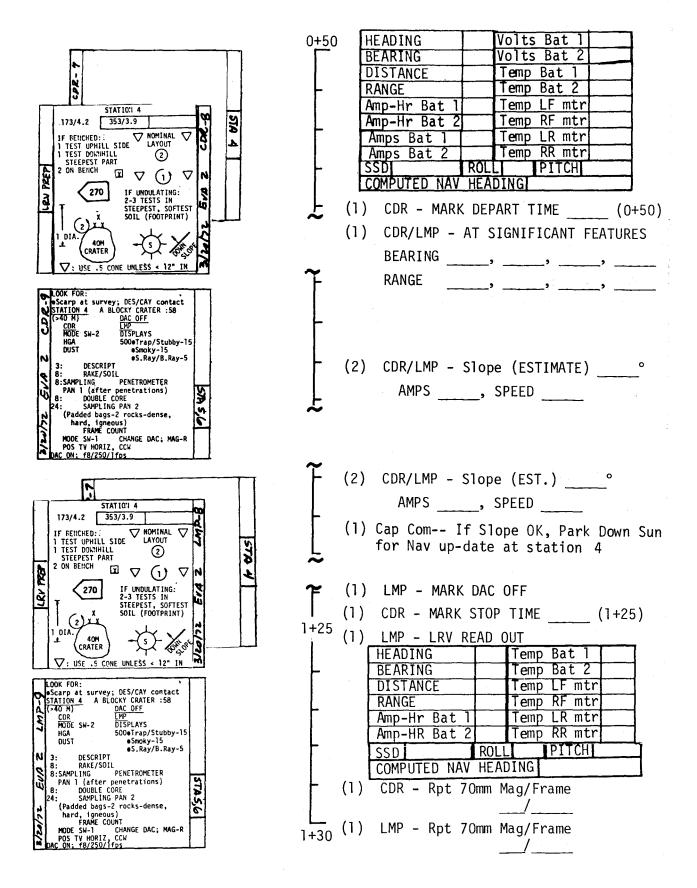


f4/250/1 fps

DATE: MARCH 1972 EVA: 2 TASK FUNCTION EVA LMP ACTIVITIES CDR ACTIVITIES TIME •Core tubes - 1U, 1L 0+30 Place 2-70mm mags D & I 0 2-20 bag dispensers under seat ol-core tube cap assy Place 2-16mm mags R & S under seat <u>a</u> (CONT'D) Put SCB 3(or 4) on R floor board (CONT Return ETB to table on MESA PREP EQUIPMENT PREP Put 16mm mag Q on DAC - check DAC out (ensure green light) EQUIPMENT Tidy MESA blankets Place maps in holder PLSS LOADUP 0+40 PLSS LOADUP Hold still Get extra SCB (No's 5-8) from pallet, place on LMP CAM UP/PAN Get Core tube cap assy & place LOAD UP/UV on LMP Put SCB 2 on CDR Put hammer in pocket - hold LOAD still PAN RESET FAR UV CAMERA Don CDR HEDC, move to Quad III Punch "reset" verify new target PLSS Pan 20' off Quad III, 7' vertical (6) with MCC PLSS pan Cosmic Ray Experiment Enter new azimuth, elevation Replace CDR HEDC on L seat LRV PREP LRV PREP Switch LCRU Mode - 1 Don LMP HEDC & 20 DSBD Position TV horizontal and Put SCB 3(or 4) under R seat CCW to stop PREP Don HEDC & 20 DSBD Mount LRV Mount LRV LRV LRV As move out, turn on DAC

Power up

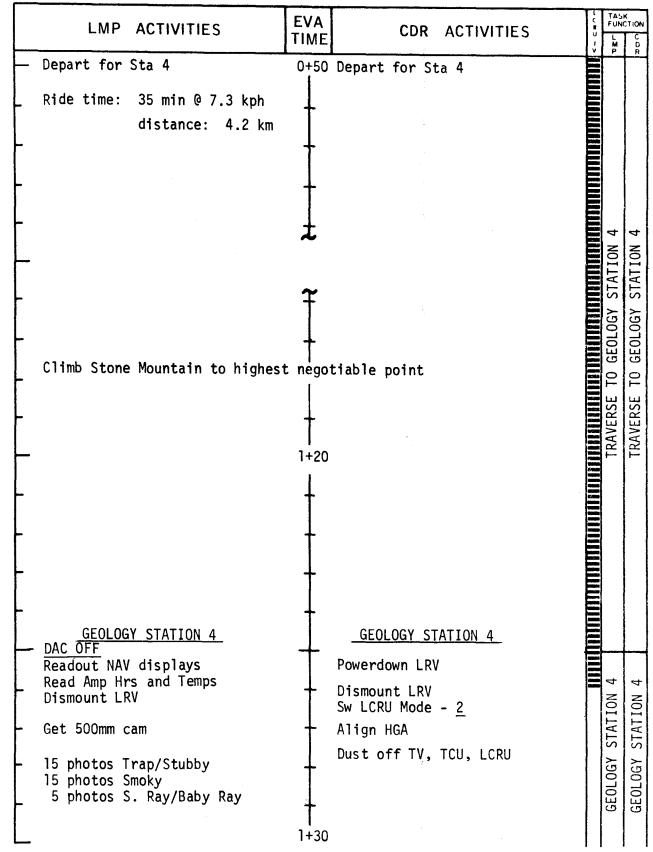
0+50 Initialize NAV System

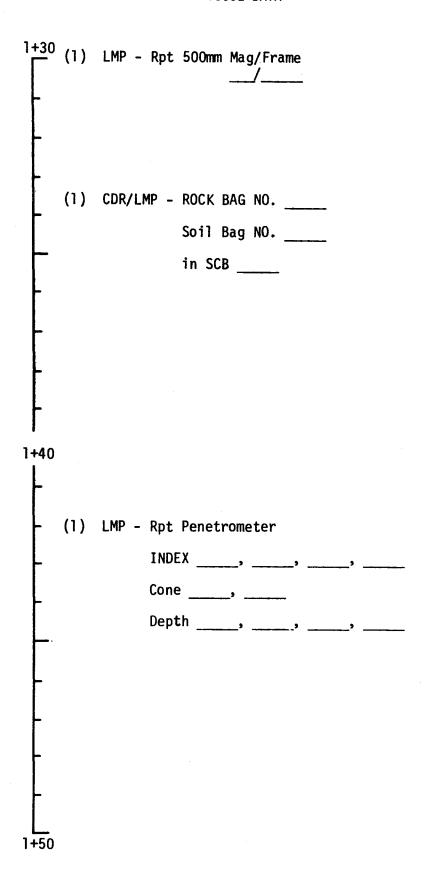


MISSION: APOLLO 16

EVA: 2

DATE: MARCH 1972



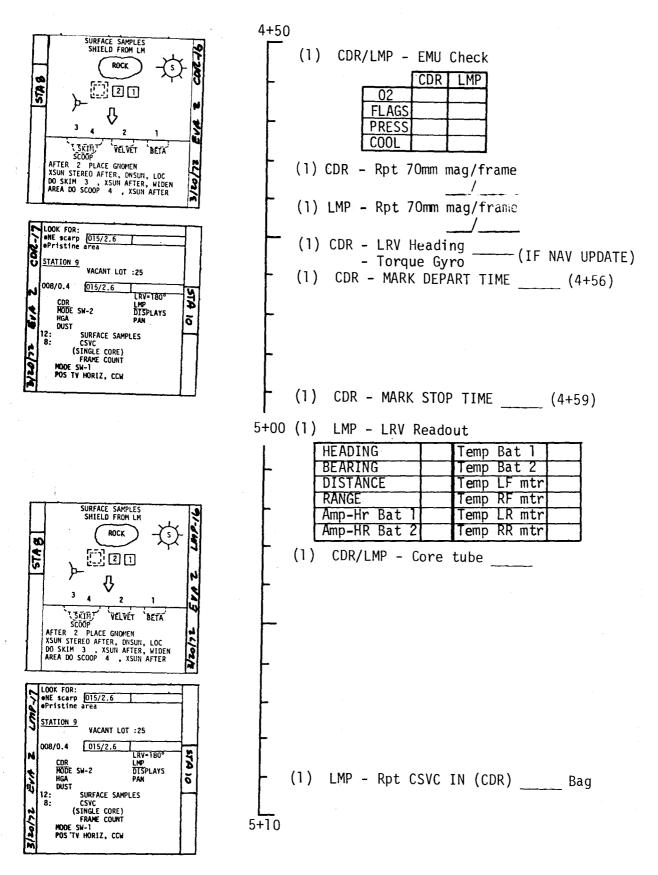


MISSION: APOLLO 16

EVA: 2

DATE: MARCH 1972

LMP ACTIVITIES	EVA TIME	CDR ACTIVITIES		ASK UNCTION C M D R
Sampling	4+30		8 (CONT'D)	8 (CONT'D)
	4+40		GEOLOGY STATTON	GEOLOGY STA



EMU CLEANUP

Clean EMU's

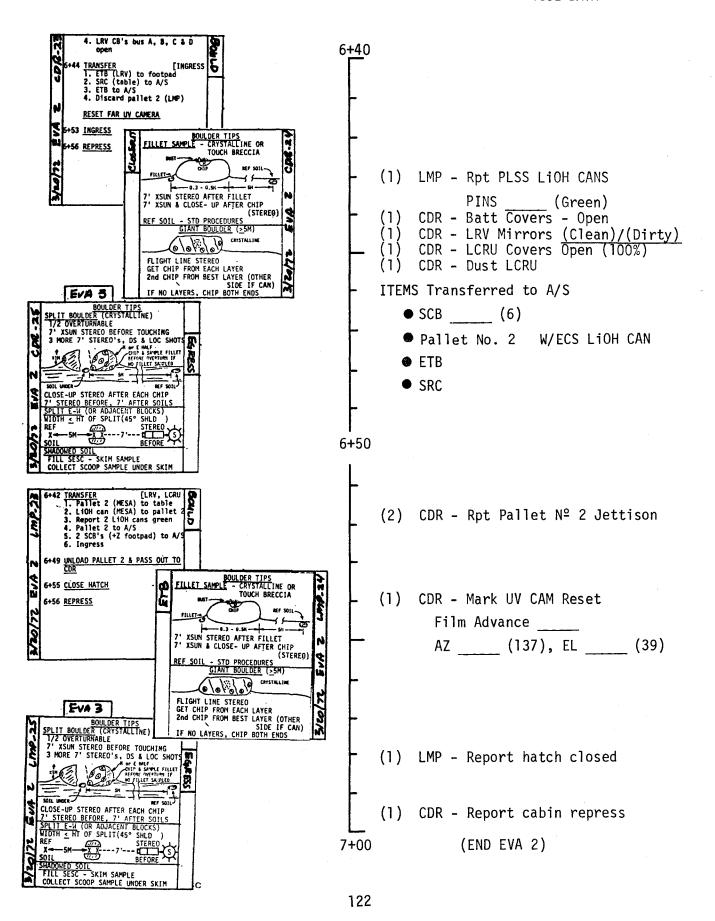
MISSION: APOLLO 16 DATE: MARCH 1972 EVA: 2 TASK FUNCTION EVA LMP ACTIVITIES CDR ACTIVITIES TIME ARRIVE AT LM 6+20 ARRIVE AT LM Readout all LRV Displays Park LRV at MESA in sun x sun (heading 351°) Dismount LRV Power down LRV (+ 15 VDC Sw -T۷ OFF) Switch LCRU Mode - 3 Dismount LRV Align HGA RESET FAR UV CAMERA Dust TV, TCU, LCRU Punch "reset", verify target (7) with MCC Put HEDC on L seat Enter new azimuth, elevation UNLOAD PLSS UNLOAD PLSS Hold Still Take SCB off LMP, place on +Z foot pad Throw away core cap dispenser Stow core rammer on HTC CLOSEOUT CLOSEOUT Put hammer, tongs on HTC Take SCB 2 off CDR, put on HTC Stow LMP antenna Put tongs on HTC 6+30 Hold Still EVA Stow CDR antenna PACK SRC 2 PACK ETB Get SCB 2 from HTC Bring ETB to L floor board Place SCB pouches up in SRC 2 Place in ETB: 2 - HEDC's (with mags) Remove skirt & seal protector 2 - 70mm mags 2 - 16mm mags Close & seal SRC 2 2 - Padded Bags 1 - mag from 500mm cam Place SRC 2 by ladder on pad restow cam under seat Take ETB to R floor board Pack: Put any large rocks collected 1 - mag from DAC - turn DAC battery to sun during EVA 2 on +Z pad 1 - set of maps

6+40

EMU CLEANUP

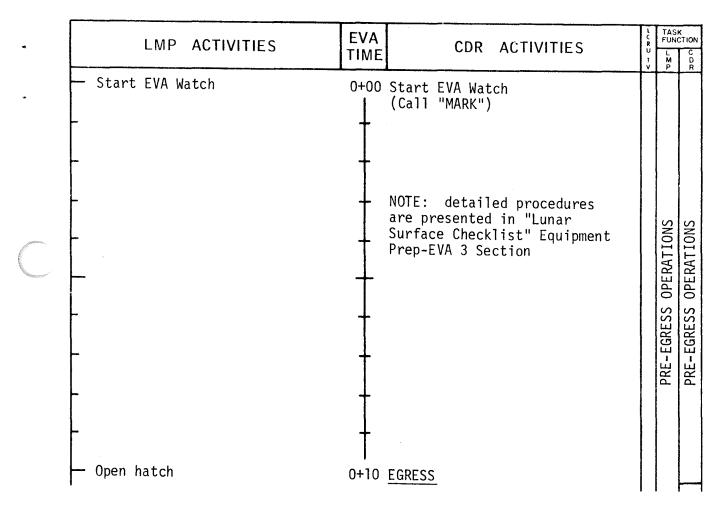
clean EMU's

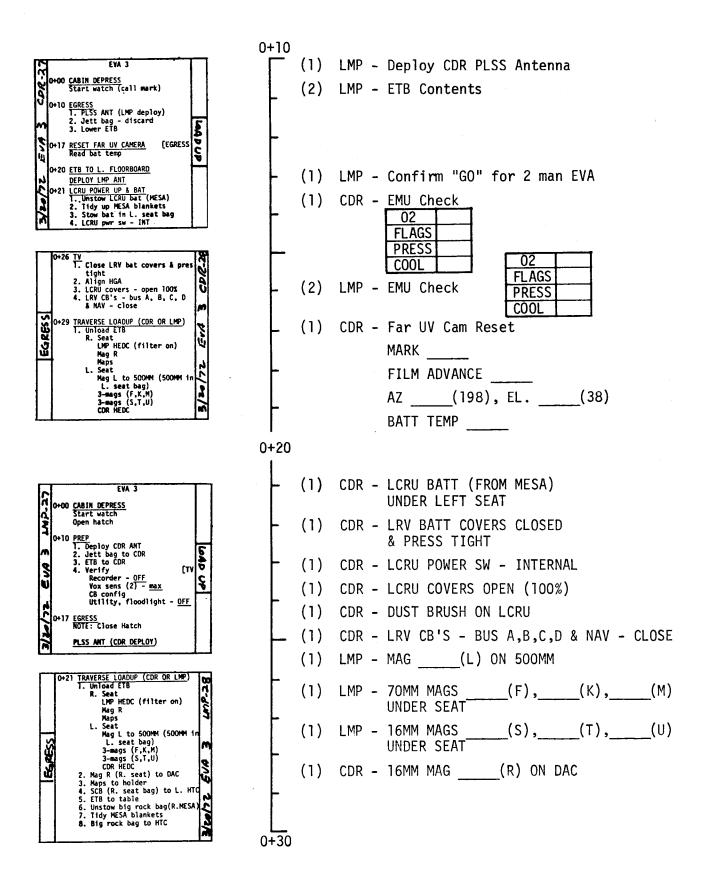
Get brush off LCRU -



## NOMINAL TIMELINE

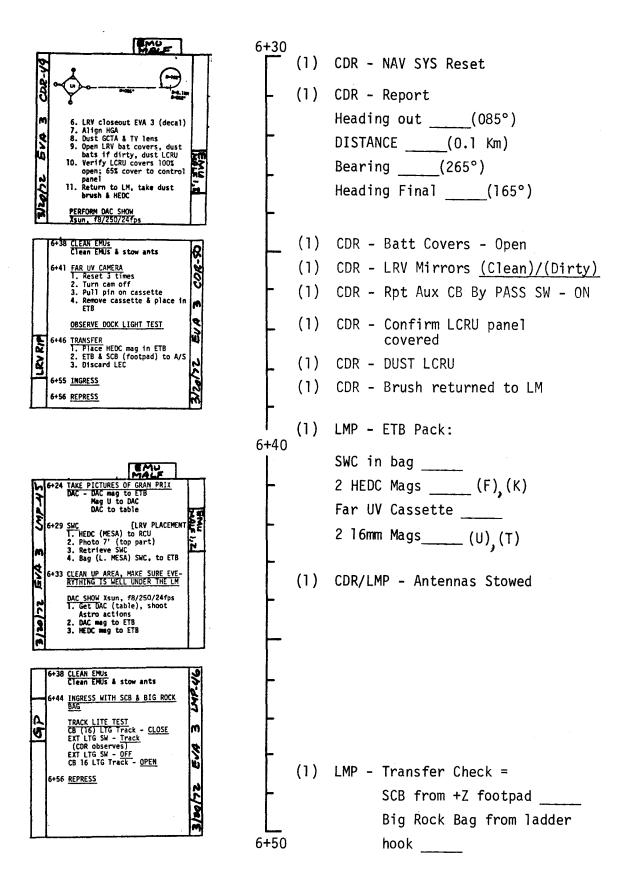
MARCH 1972





DATE: MARCH 1972

LMP ACTIVITIES	EVA CDR ACTIVITIES		e c	TASK FUNCTIO	
	TIME	9	i. p	CDR	
UNLOAD PLSS Hold still  Put CDR SCB on foot pad (+Z) Quick release PLSS tool carrier PACK ETB  Get ETB, place on L floor board Pack in ETB: 500 mm cam mag 3 HEDC mags Mag R (16 mm)  Put 16 mm mags T, U on R Seat Transfer ETB to R Side Put DAC mag in ETB Put Mag T on DAC Take mag U & DAC to SRC table  Assist CDR with CRE if req'd Return to LRV Place maps in ETB Remove drum from penetrometer  Bag (DSB) and place drum in ETB  Take ETB to SRC table - hang it  Put CRE bag in ETB Get HEDC (R Seat) place on MESA  Ready DAC for Gran Prix Photo Gran Prix	6+20 up	UNLOAD PLSS Put LMP SCB on footpad (+Z)  Quick release PLSS tool carrier (optional)  Hold still  COSMIC RAY Pull white ring & pin, take Cosmic Ray experiment & Case to SRC Table  Pull blue ring & slide cosmic ray panels out of CRE case  Report Temp labels as they come up  Fold panels and place in bag - leave bag on table		EVA CLOSEOUT (CONT'D)	CLOSCOLT



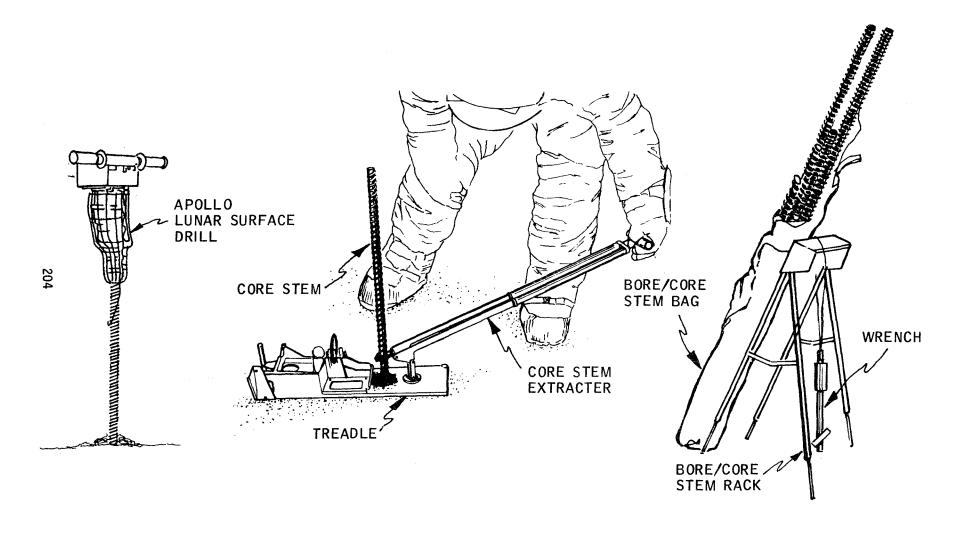


Figure 3.5-4 LUNAR SURFACE BORING & CORING HARDWARE

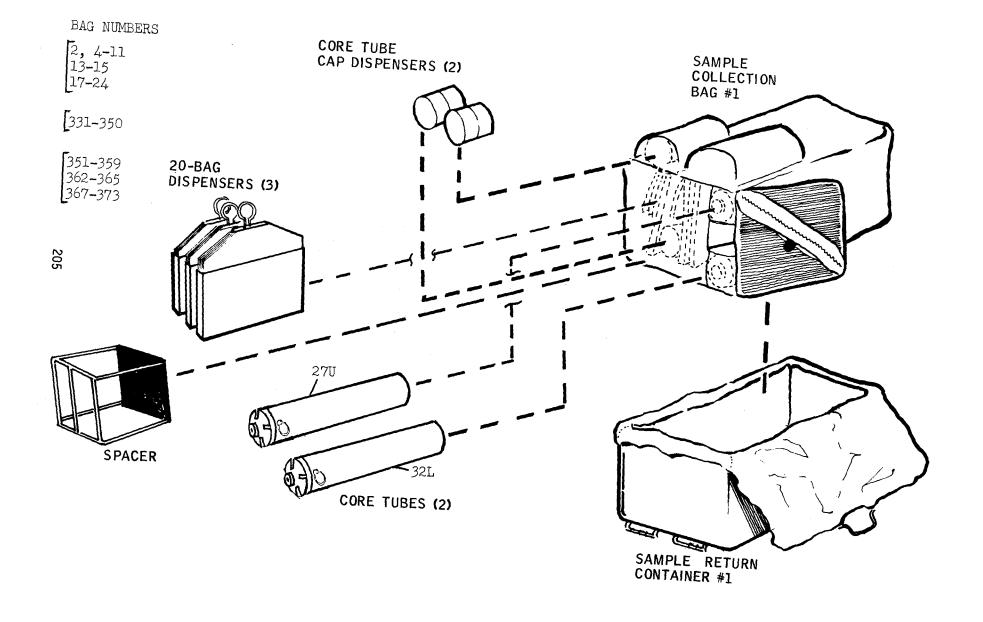


Figure 3.5-5a GEOLOGY SAMPLING ITEMS STOWED IN SRC # 1

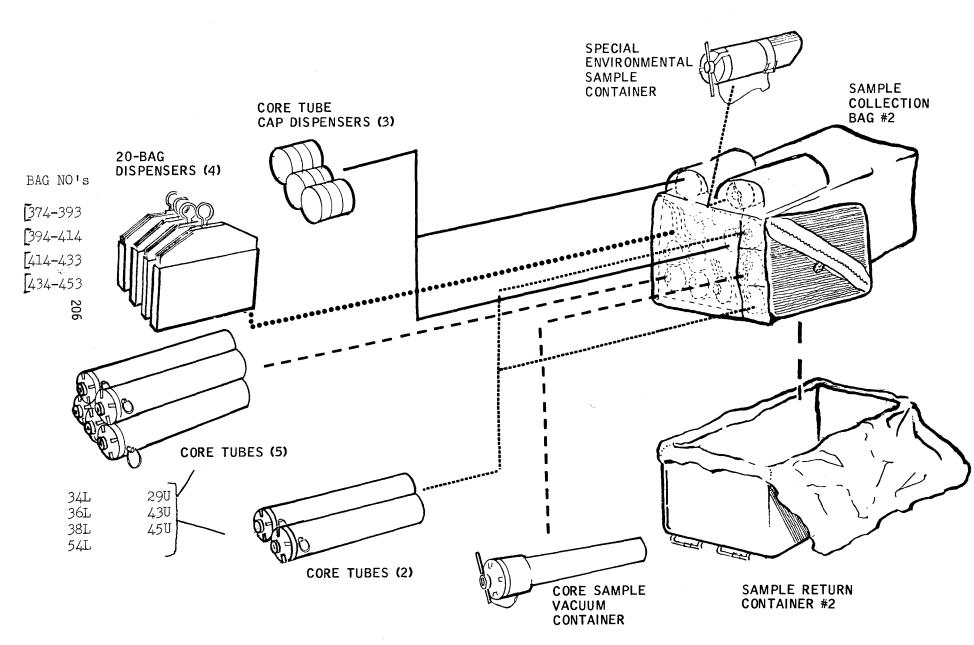


Figure 3.5-5b GEOLOGY SAMPLING ITEMS STOWED IN SRC # 2

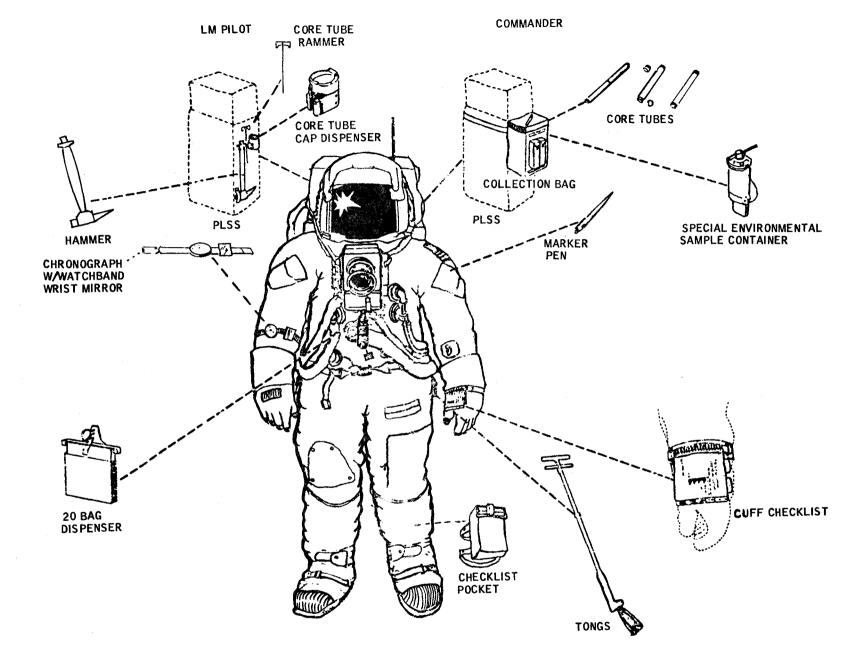
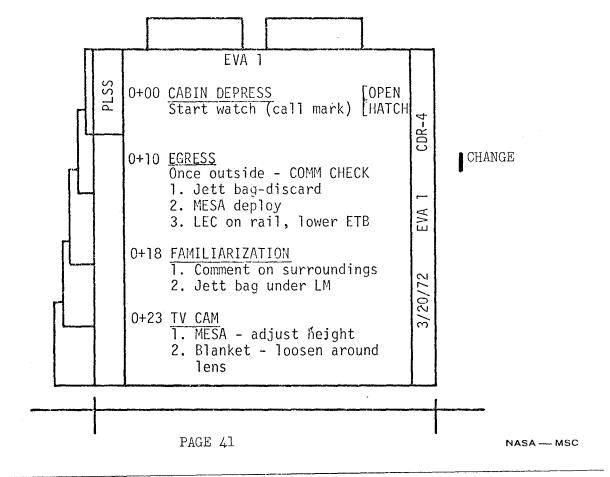
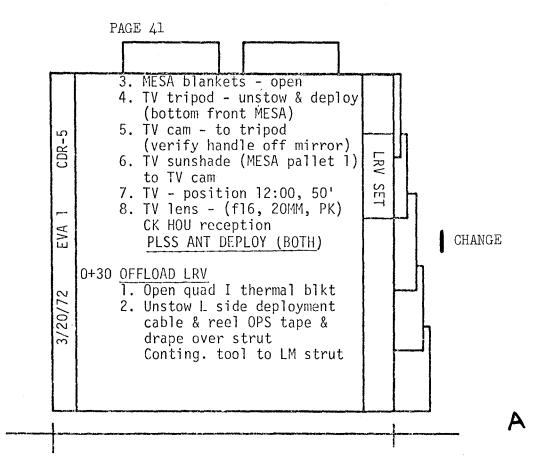
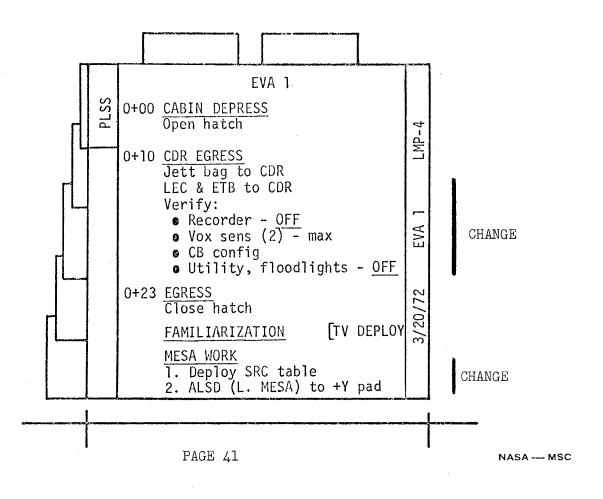


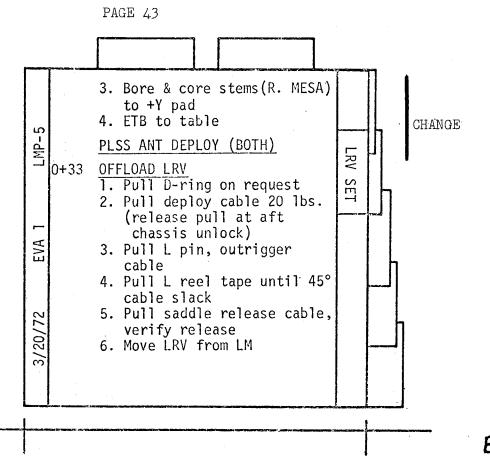
Figure 3.5-6 LUNAR SURFACE EQUIPMENT STOWED ON EMU

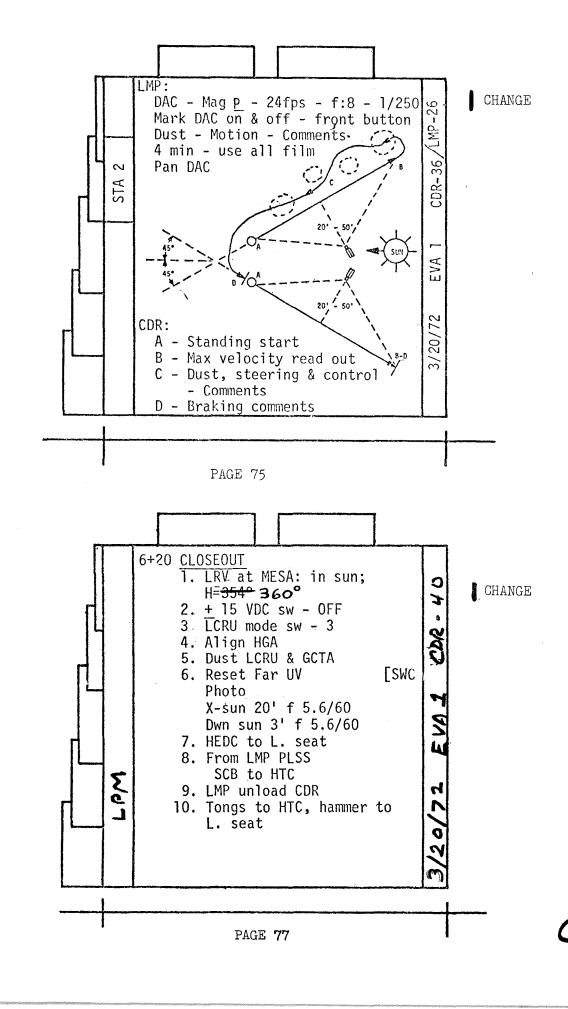
The following pages are referred to in instruction 6 of the preface to this supplement.

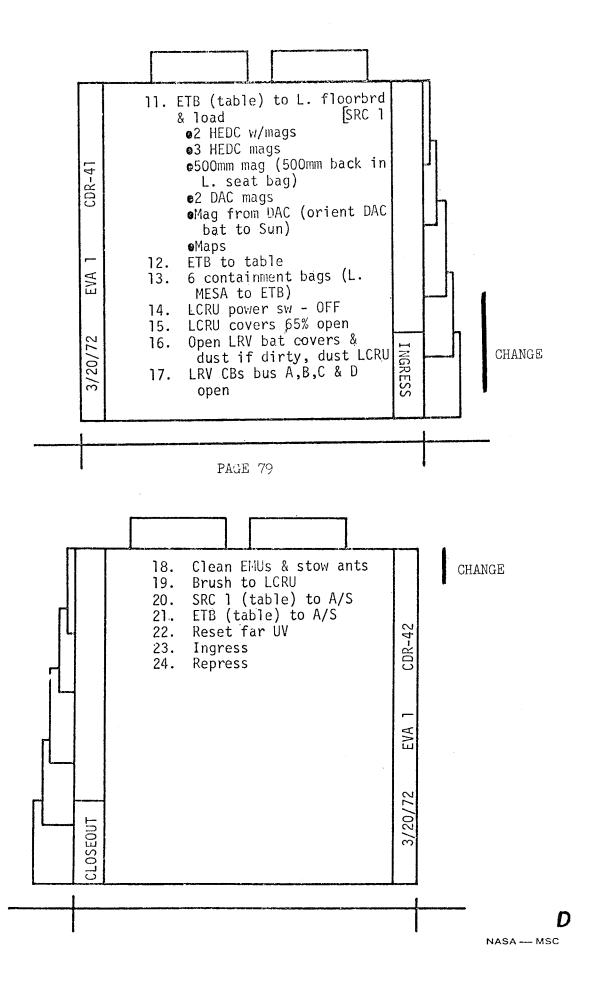


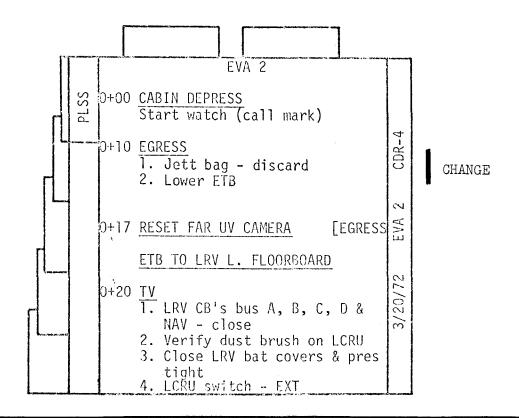


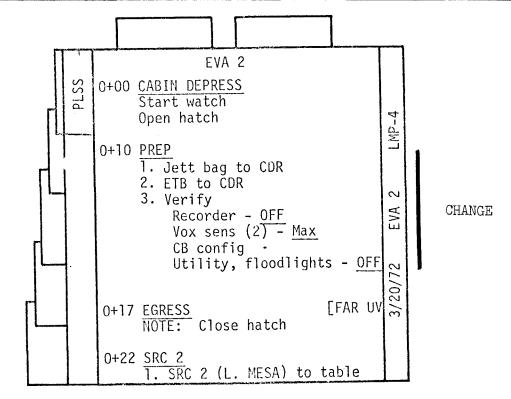


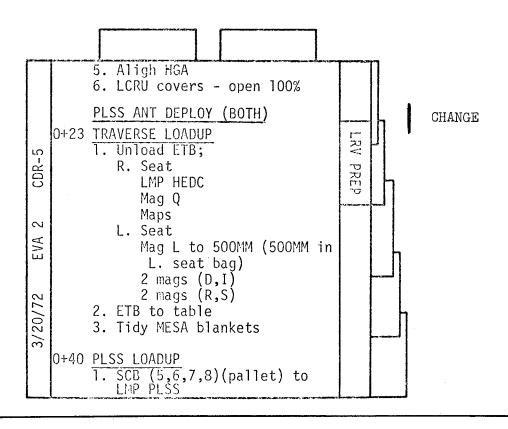


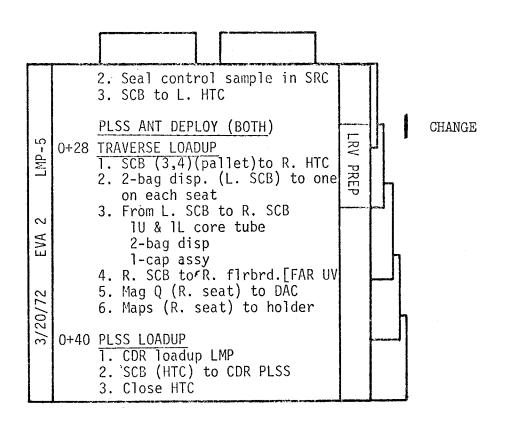


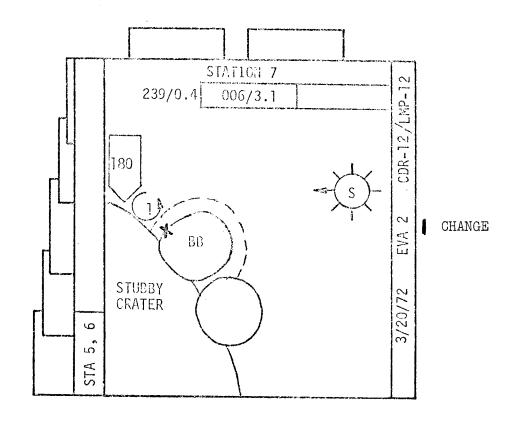


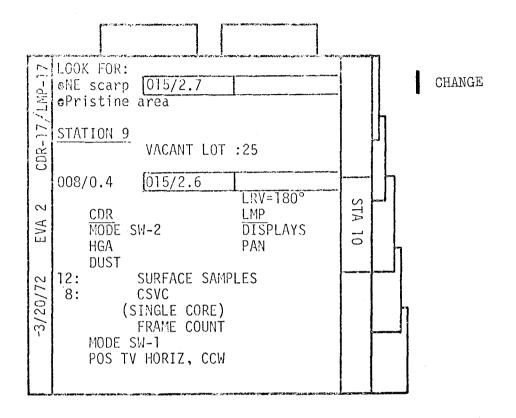


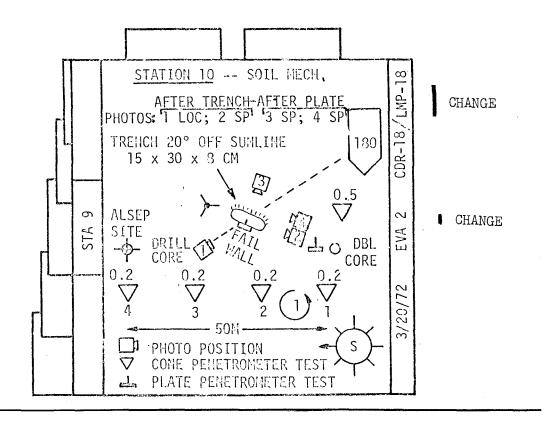


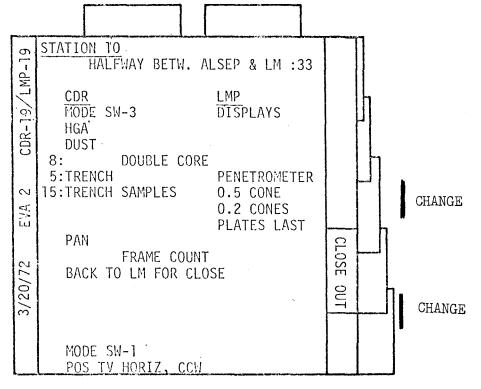


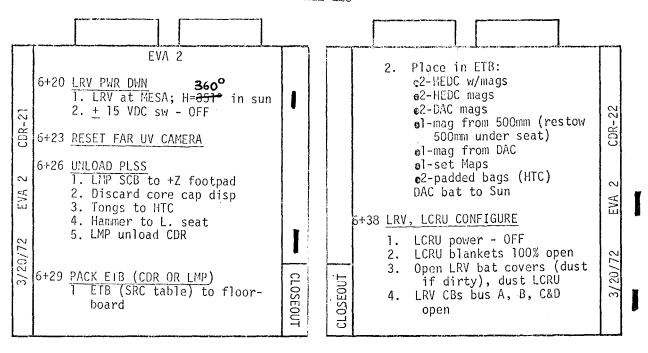


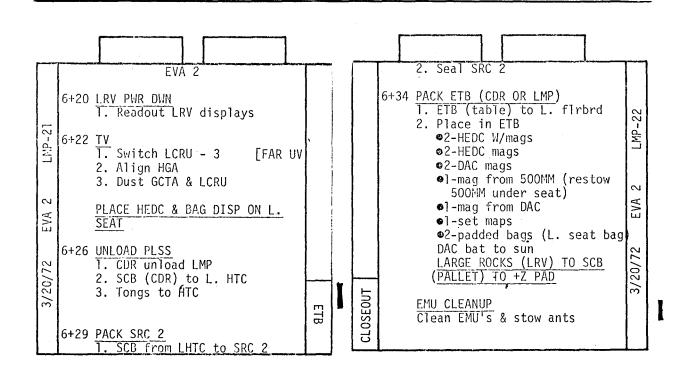


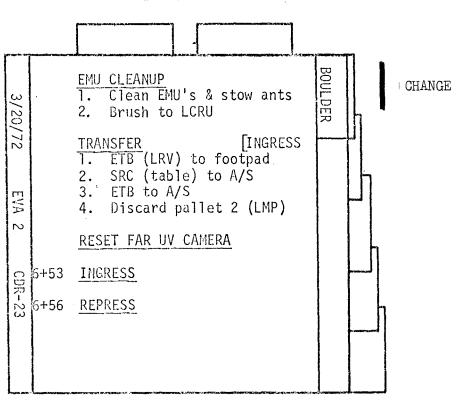


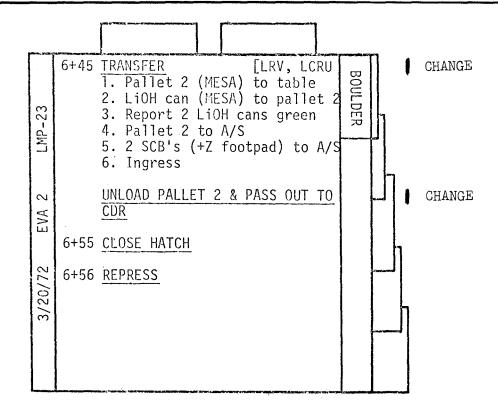


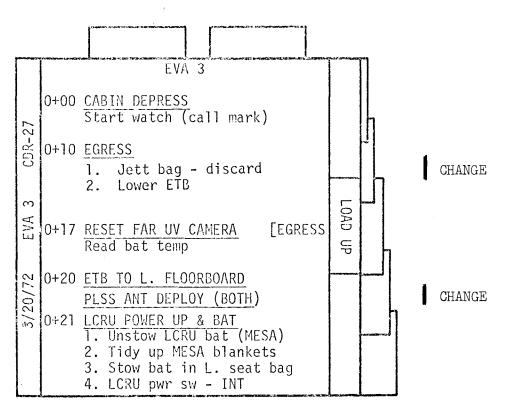


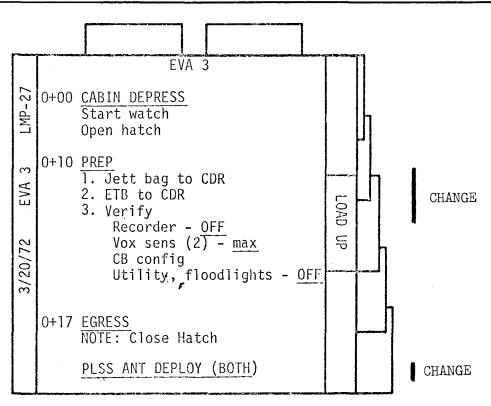


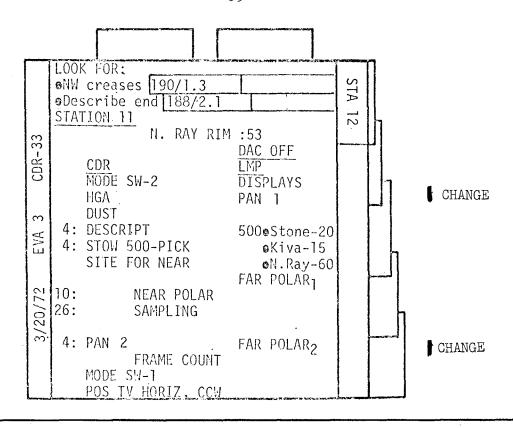


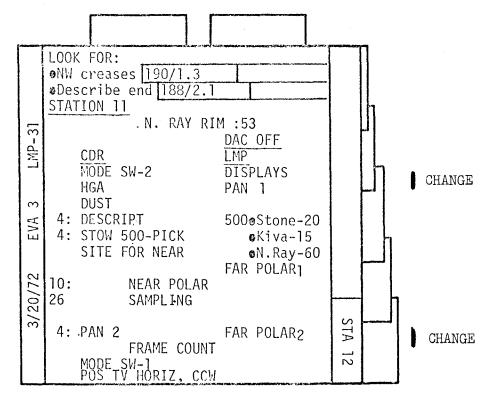




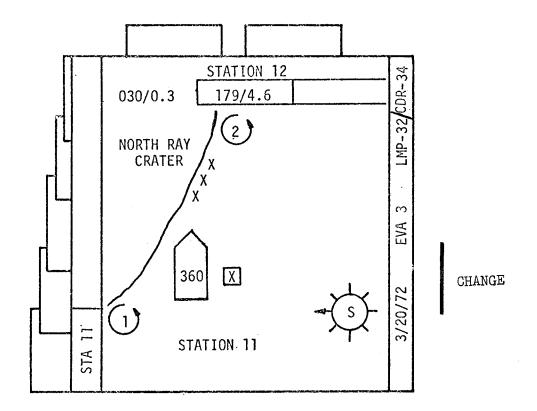


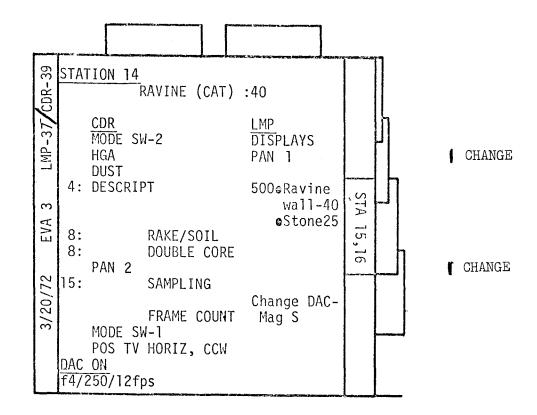






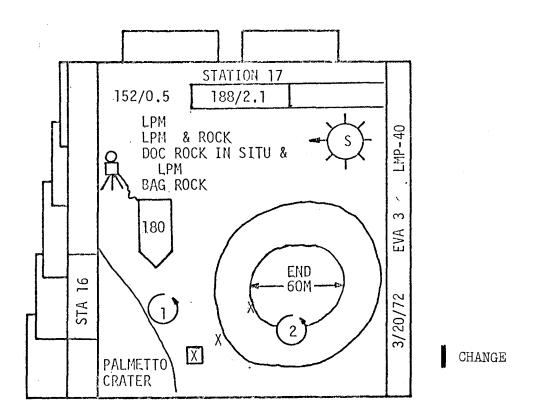
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