

### Resource Prospector (RP)

Mission Overview and Current Activities

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http://www.nasa.gov/resource-prospector @NASAexplores

### **RP Storyboard**













### **EVOLVABLE MARS CAMPAIGN**

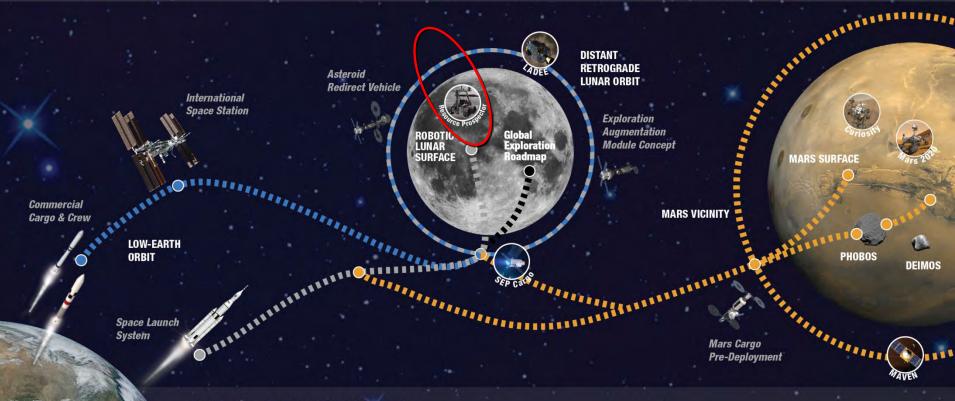
A Pioneering Approach to Exploration



**EARTH RELIANT** 

PROVING GROUND

**EARTH INDEPENDENT** 



### THE TRADE SPACE

**Across the** | Solar Electric Propulsion • In-Situ Resource Utilization (ISRU) • Robotic Precursors • Board | Human/Robotic Interactions • Partnership Coordination • Exploration and Science Activities

**Trades** 

- **Cis-lunar** | Deep-space testing and autonomous operations
  - Extensibility to Mars
  - Mars system staging/refurbishment point and trajectory analyses

**Trades** 

- Mars Vicinity | Split versus monolithic habitat
  - Cargo pre-deployment
  - · Mars Phobos/Deimos activities
  - . Entry descent and landing concepts
  - Transportation technologies/trajectory analyses

#### 2015 Activities

2015



#### RP pursued three simultaneous tracks in FY15!

NASA-International partnership possibilities

NASA-JAXA & NASA-Taiwan

"Full-up" RP20 with ~300kg Prospecting & ISRU Payload and Rover system

~2020

#### NASA-Commercial partnership possibilities

2017/2018

Performed multi-month "Market Research" to see technical and economic feasibility of NewSpace commercial options for 2020

RP15

Build a "RP15" prototype rover/payload system ("Surface Segment") to enable testing & risk reduction (HW, SW, and Distributed Ops)

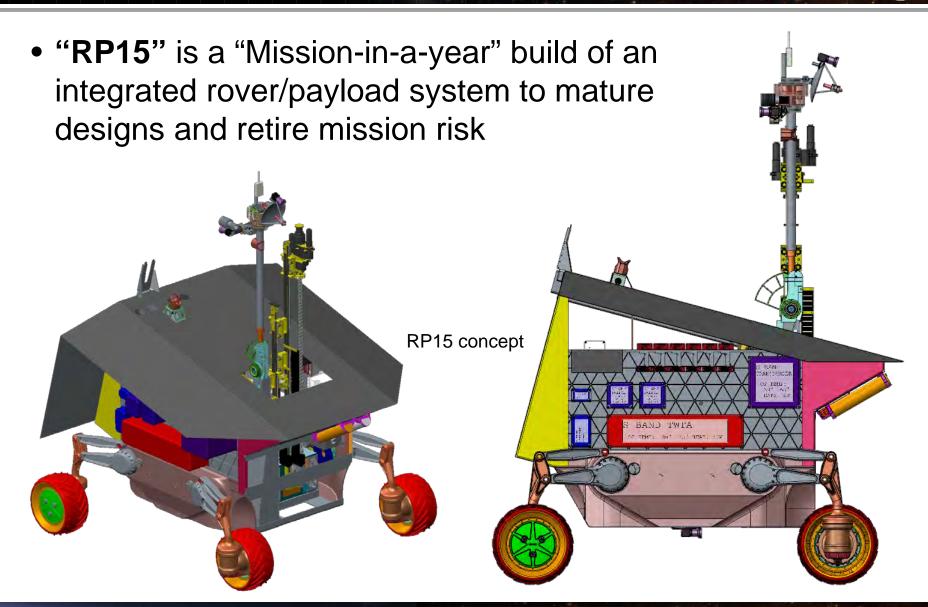
JAXA President Okumura driving the KREX rover at NASA-ARC (2014-10)



NASA delegation to Taiwan (2015-07)

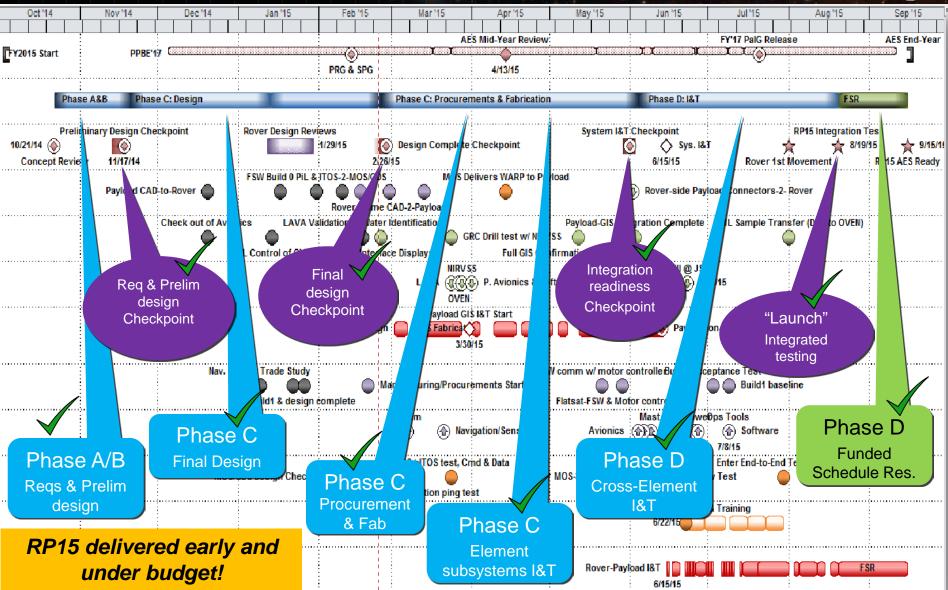






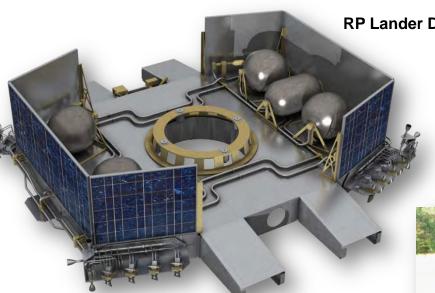
### RP15 "Mission in a year"





### **RP Partnering Lander Concept** 2014-05





**RP Lander Design** 

- Prototyped a cost-efficient lander
  - Novel aluminum riveted structure concept reduces complexity and cost
  - NASA looking for international partner to provide the lander

#### **Lander Prototype & Propulsion testbed**



## RP Neutron Spectrometer (NSS) & NIR Spectrometer (NIRVSS) field tests (2014-08)







#### NSS in the NASA-ARC Roverscape

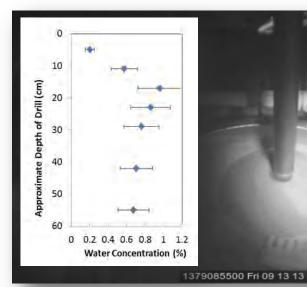
- The NSS is located on the rover and in front of that is a neutron source holder for Earth testing only (simulating lunar radiation activity)
- The team has driven across rock patches and an ice proxy for testing

#### NIRVSS in the NASA-ARC overscape

 The team drove across rock patches and an ice proxy for testing

## RP Drill & NIRVSS testing 2013-09 & 2015-07



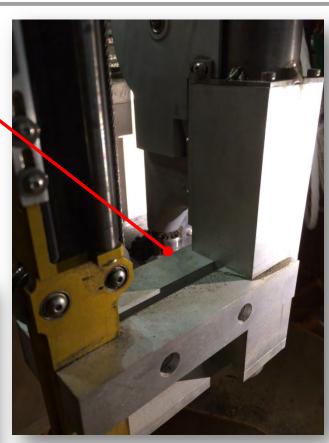


OVEN Crucible







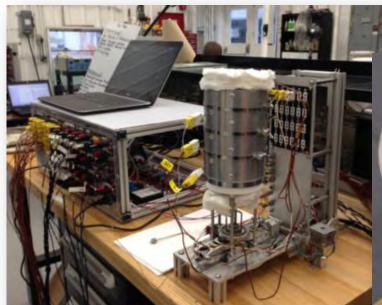


RP15 Rover-hosted Drill testing in doped simulant tube at NASA-JSC

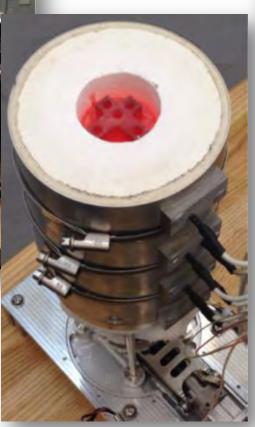
## RP OVEN ETU testing 2014-04



- RESOLVE ISRU payload systems undergoing engineering test
  - Subsystem TVAC and vibe testing, drilling in relevant environment, etc



**OVEN Reactor Checkout Testing** 





OVEN Reactor Mechanical Assembly

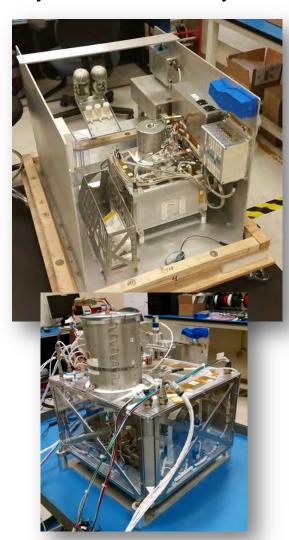
OVEN Reactor Heater at 700+°C

## RP15 Payload Activities 2015-05



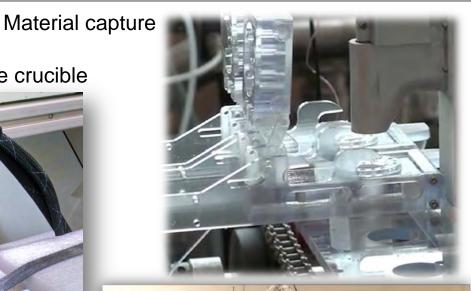


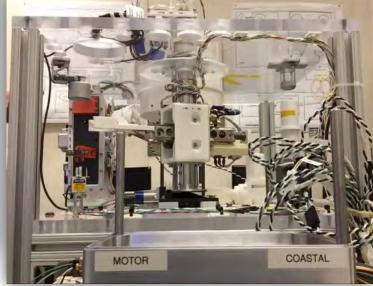
Payload & Drill subsystem





Crucible processing





## RP15 Rover Activities 2015-06



### Rover Suspension/Drive Subsystem







Suspension assembly







1g wheels

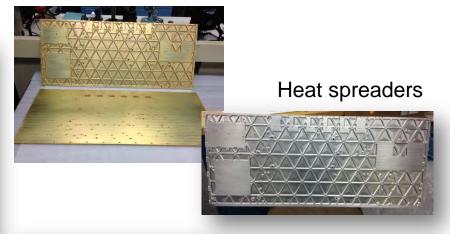
## RP15 Rover Activities 2015-06



#### Rover Frame/Chassis







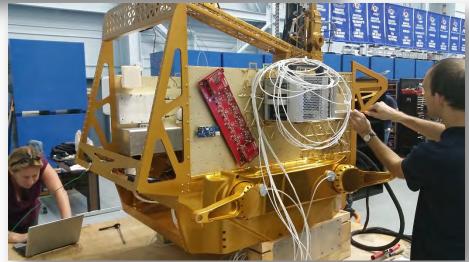


## RP15 Rover/Payload integration 2015-07





Rover Assembly





## RP15 Assembly Time-Lapse 2015-07







Rover Assembly

## RP15 In the Dirt 2015-08-15



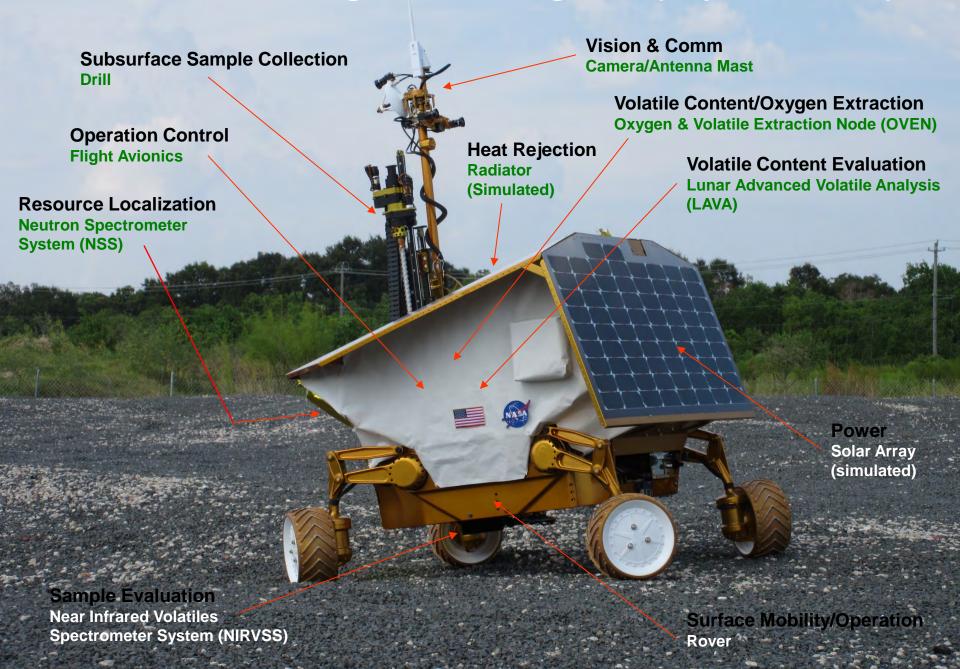


## RP15 In the Dirt 2015-08-15





### RP15 Field Testing: Surface Segment (Payload/Rover)



### RP15 Drilling on a slope in the Field

2015-08-24







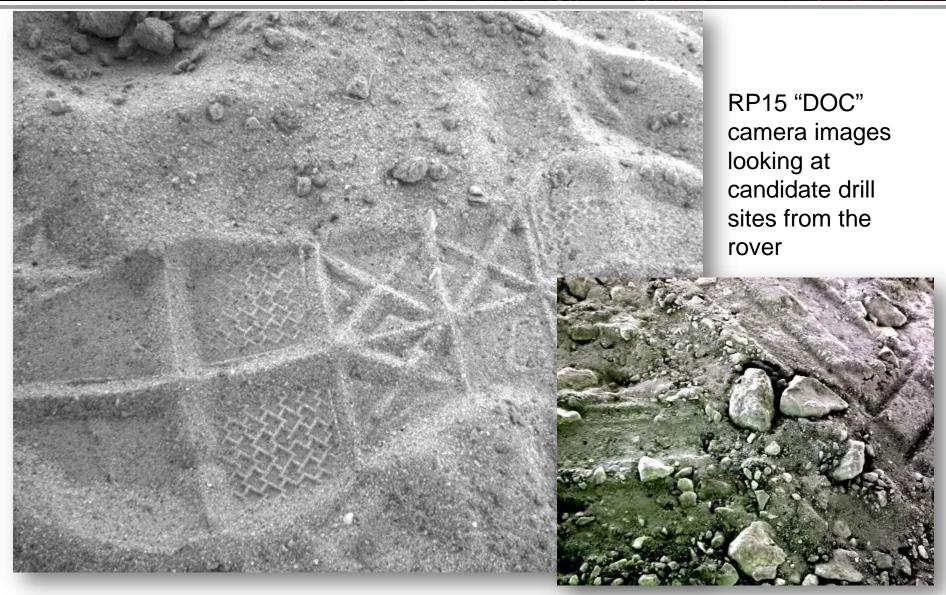


Sand Captured in Drill Brush Housing & Flutes

Sloped Drilling at JSC

## RP15 Initial Terrestrial Images 2015-08-11





### **RP15 Distributed Operations Test testing**

2015-08-21





NASA-ARC Mission Control room driving RP15 rover @ NASA-JSC

> NASA-JSC Rock Yard from the rover (left) stereo camera



3-D Image Viewing of NIRVSS Camera Images During DOT



NASA-KSC Payload Control room

## RP15 Rocky Weather in Houston 2015-08-18





Mother Nature rebelling. Building sand barriers to flowing water

Heading back to the highbay to do a systems check (all ok)







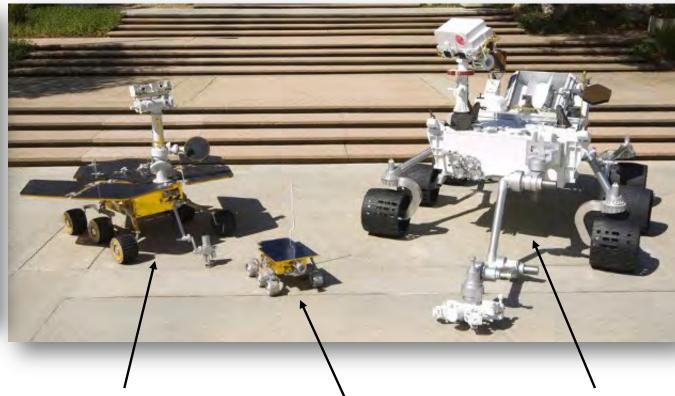
### Rover Dimensional Comparison (approx.)







- 1.5m x 1.5m x 2.0m (LxWxH)
- Weighs about 300kg



#### Spirit/Opportunity (2004):

- 1.6m x 2.3m x 1.5m (LxWxH)
- Weighs about 180kg

#### Sojourner (1996):

- 0.6m x 0.5m x 0.3m (LxWxH)
- Weighs about 11kg

#### Curiosity (1996):

- 3.0m x 2.8m x 2.1m (LxWxH)
- Weighs about 900kg

### **RP's Impressive Social Media penetration**



Rep Mike Honda's Chief staffer requested an RP briefing @ NASA-ARC because, "the techie staffers read about it on Twitter"





### Evolvable Lunar Architecture Press Conference 2015-07-20





The Top Strategic Risk:
"We don't know exactly
how much water is in the
moon or how deep, or
how plentiful it is. This is
a key strategic issue we
need to understand... and
if there is one thing we
should do soon, it is to
send soon a resource
prospector to the moon".

Charles Miller - Study PI & President of NexGen Space LLC



Press conference by National Space Society (NSS) and Space Frontier Foundation (SFF) announcing their support for NASA's funding of the newly released NexGen Space study. Study: "Economic Assessment and Systems Analysis of an Evolvable Lunar Architecture that Leverages Commercial Space Capabilities and Public - Private - Partnerships"; NASA funded the \$100K study; Independent review of the study occurred 2015-03



### Resource Prospector (RP) Overview



#### Mission:

- Characterize the nature and distribution of water/volatiles in lunar polar sub-surface materials
- Demonstrate ISRU processing of lunar regolith

#### **RP20 Specs:**

- Mission Life: 6-14 earth days (extended missions being studied)
- Rover + Payload Mass: 300 kg
- Total system wet mass (on LV): 5000 kg
- Rover Dimensions: 1.4m x 1.4m x 2m
- Rover Power (nom): 300W
- Customer: HEOMD/AES
- Cost: <\$250M (excl LV & Lander)</li>
- Mission Class: D-Cat3
- Launch Vehicle: Falcon 9 v1.1

#### **Project Timeline:**

- ✓ FY13: Pre-Phase A: MCR (Pre-Formulation)
- √ FY14: Phase A (Formulation)
- FY15: Phase A (Demonstration: RP15)
- FY16: Phase B prep -> SRR/MDR
- FY17: PDR (Implementation)
- FY18: CDR (Critical design)
- FY19: I&T
- FY20: RP launch



### RP15 Activities 2015-06



#### **Rover Avionics**





3-axis mobility controller testbed

Motor Controllers with Single wheel testbed

