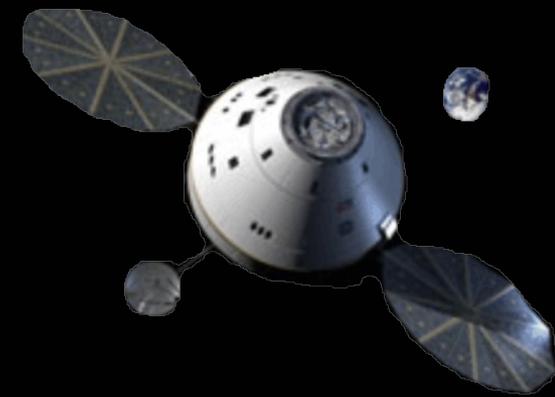


# ORION/MOONRISE: JOINT HUMAN-ROBOTIC LUNAR SAMPLE RETURN MISSION CONCEPT



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LEAG Meeting, 2012  
October 22-25, 2012, GSFC

# Thank you

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- Co-authors of this paper
- John Baker and Gary Burdick, JPL Human Exploration Program Office
- Brad Jolliff and Chip Shearer
- To the LEAG community for your attention

# Orion/MoonRise Mission Concept: Introduction & Motivation

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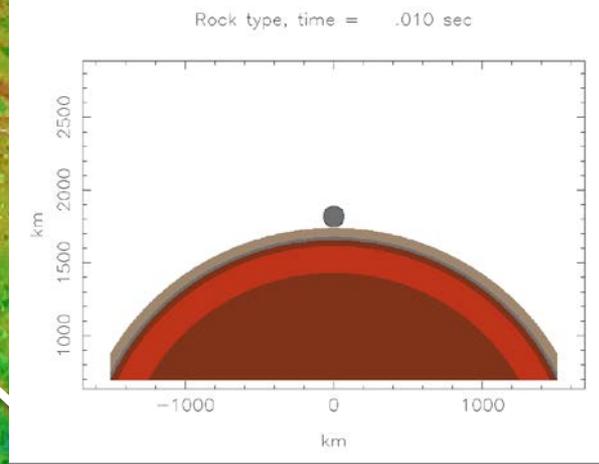
- An opportunity for significant collaboration between SMD and HEOMD.
- Conduct an exciting and bold joint human-robotic mission in cis-Lunar space as a precursor to future Mars exploration by combining the mature MoonRise lander design with the HEOMD architecture.
- Accomplish high national priority Decadal Survey Science with the first sample return from the lunar farside; the key to understanding the formation of our Solar System and early evolution of the Earth-Moon System at a time when life originated on Earth.

South Pole –  
Aitken Basin

Equator

Aitken Crater

South Pole

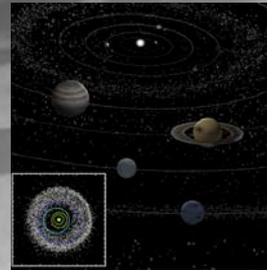


LRO LOLA data on LROC  
WAC context mosaic

# MoonRise sample return addresses key Solar System Science as endorsed by the NRC!

*Addresses key objectives for Planetary Science.*

*Advances scientific knowledge of Solar System history and processes.*



Dynamics of the Outer Solar System



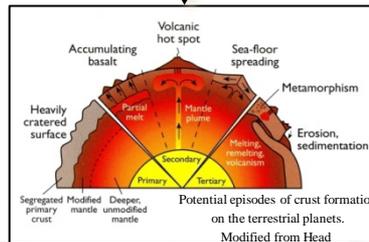
Impact Cataclysm



Effects of Giant Impacts on Planetary Evolution



Origin of the Earth-Moon system



Differentiation and Thermal History of the Terrestrial Planets



Planetary Environments for the Origin and Evolution of Life

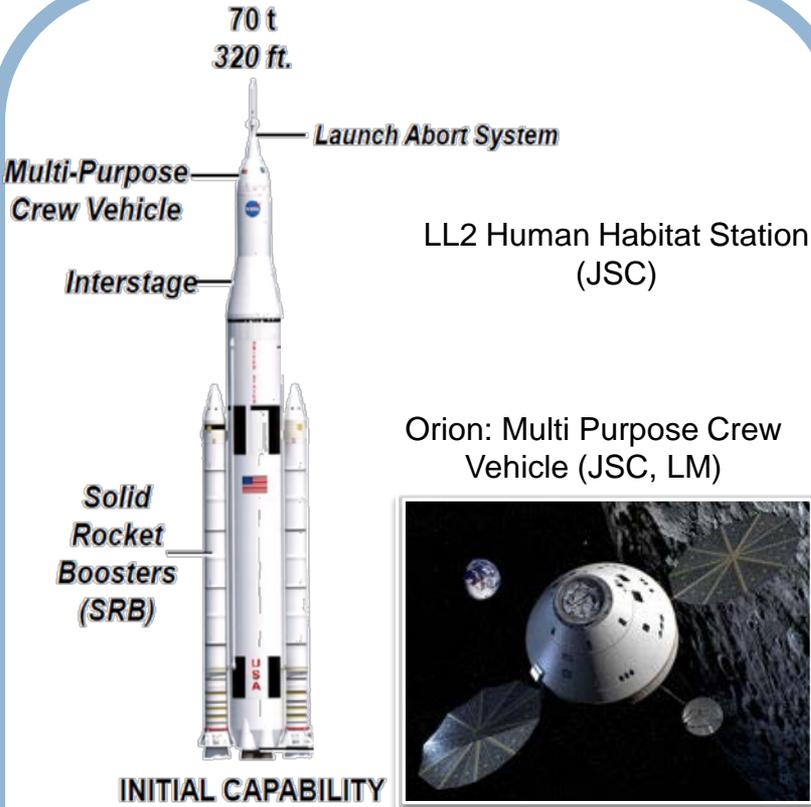
*How the Solar System evolved to its current, diverse state.*

*Implications for the history of Earth at a critical time in the development of its habitable environments and the origin and survival of Earth's early life.*

## Architectural Elements of the Study

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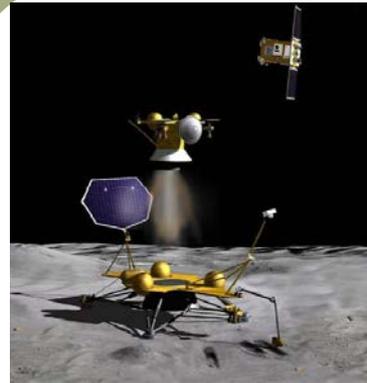
### Human Architectural Elements



SLS: Space Launch System  
(JSC, MSFC, KSC)



### Robotic Architectural Elements



MoonRise New Frontiers Phase A Study (JPL, LM)



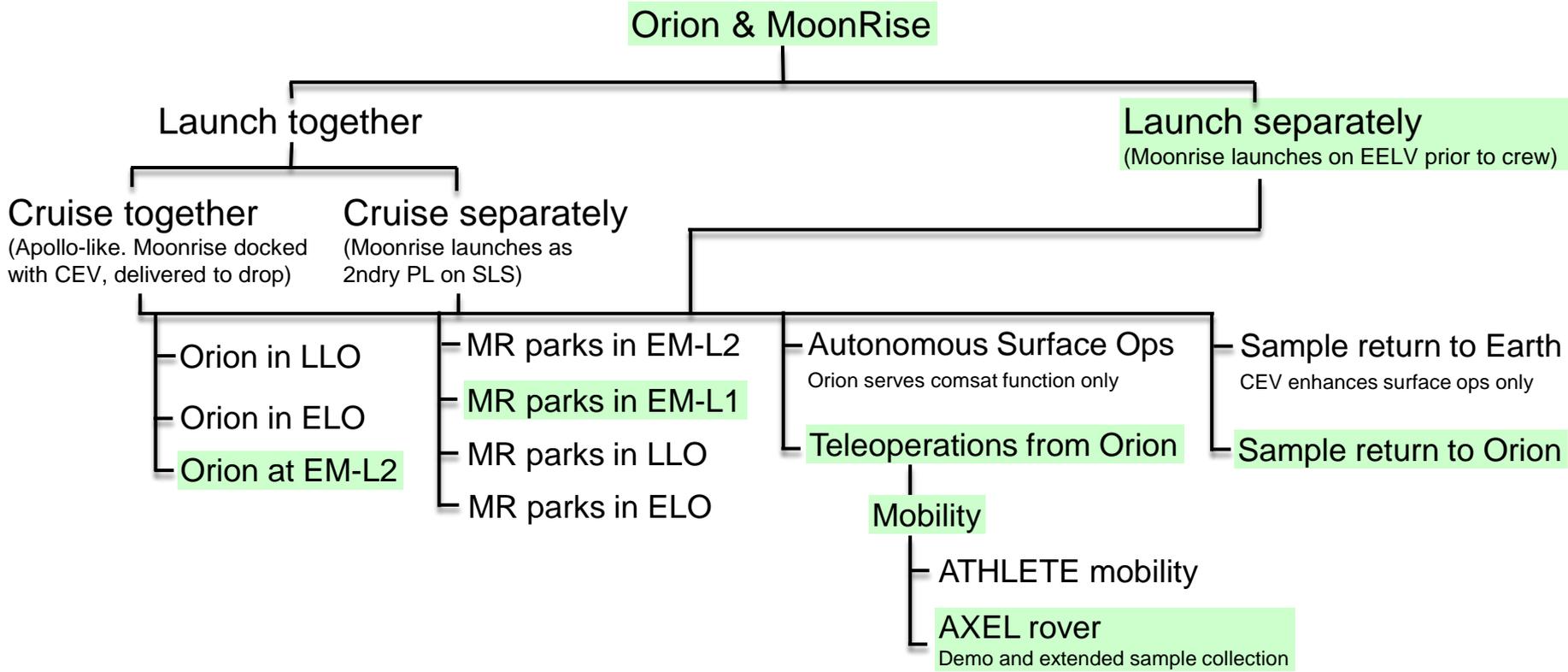
ALHAT: Autonomous Landing and Hazard Avoidance Technology (JSC, LaRC, JPL, APL, GRC)



Axel: Scalable low mass tethered rover for very steep terrain access & sample collection (JPL)

## sample return from the South Pole - Aitken Basin

Planning and discussion  
Purposes  
Only



# Orion/MoonRise: Mission Concept Outline:

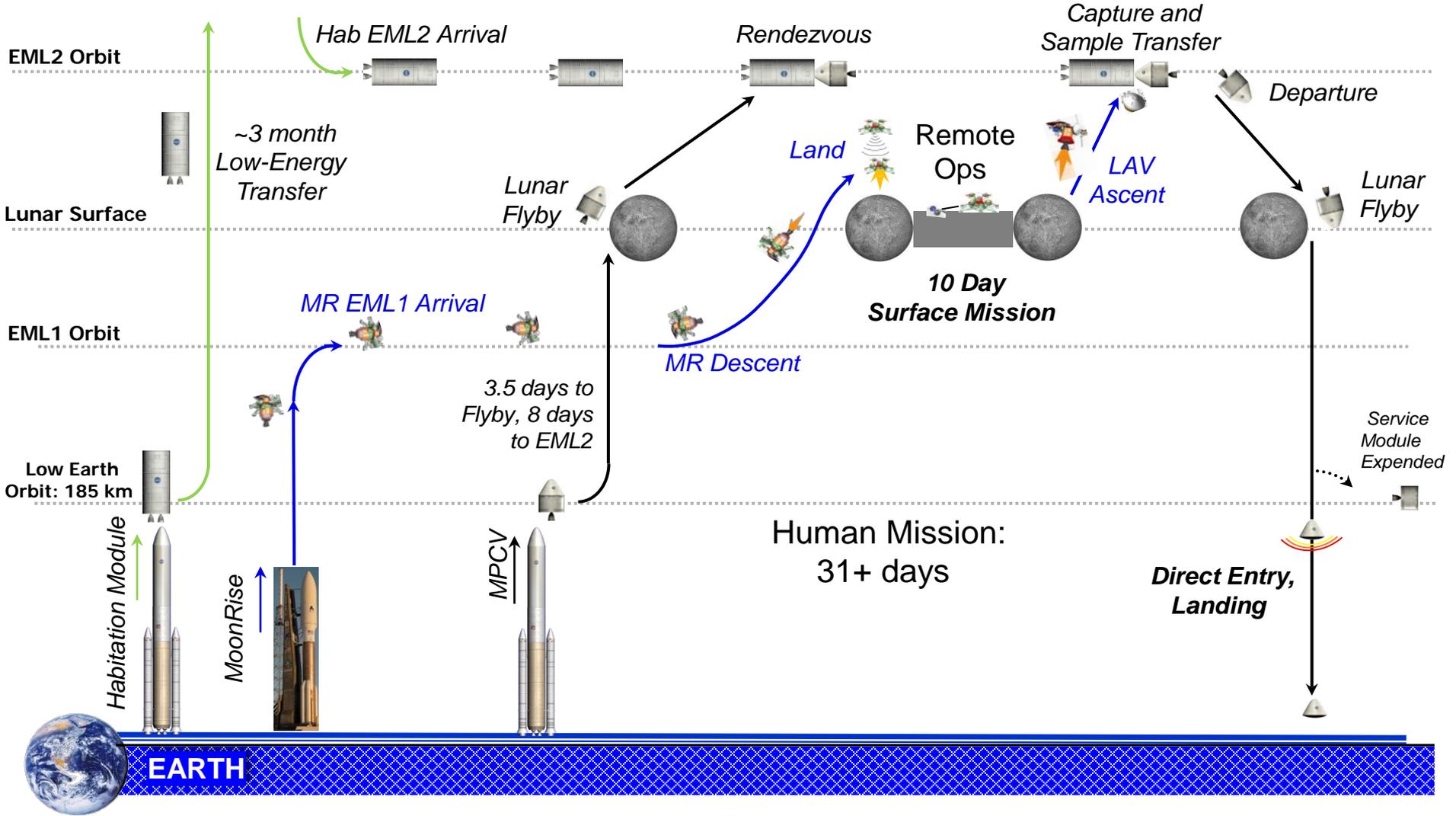
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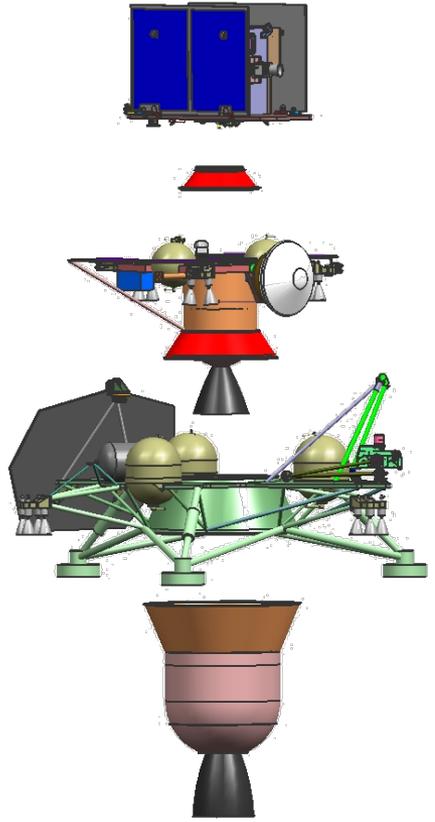
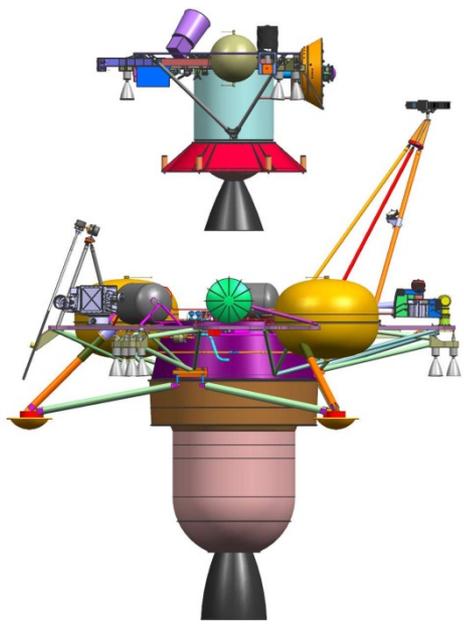
8

- Assume human habitat module is launched on SLS and is established at or around EM-L2.
- The MoonRise robotic sample return vehicle (SRV) is launched.
- After the SRV has successfully arrived at its staging orbit (EM-L1 or EM-L2), Orion is launched with astronauts to EM-L2 using the crew version of SLS.
- Once Orion is ready at EM-L2, the SRV lander lands at the South Pole-Aitken Basin with Orion providing relay critical coverage during descent.
- Upon landing, the lander, tele-operated by astronauts from Orion, uses advanced robotics and mobility systems to sample and retrieve precious scientific samples and store them in a container in the Lunar Ascent Vehicle.
- The Ascent Vehicle with as much as **10 - 30 kg** of samples ascends to EM-L2 station.
- Astronauts in Orion capture sample canister at EM-L2 and return samples back to Earth.
- This mission demonstrates human/robotic sample return for future Mars missions and brings high science value payload to the science community.
- Excellent opportunity for public engagement and outreach!

# Orion/MoonRise Mission Architecture



## Small updates to the MoonRise 2010 Architecture

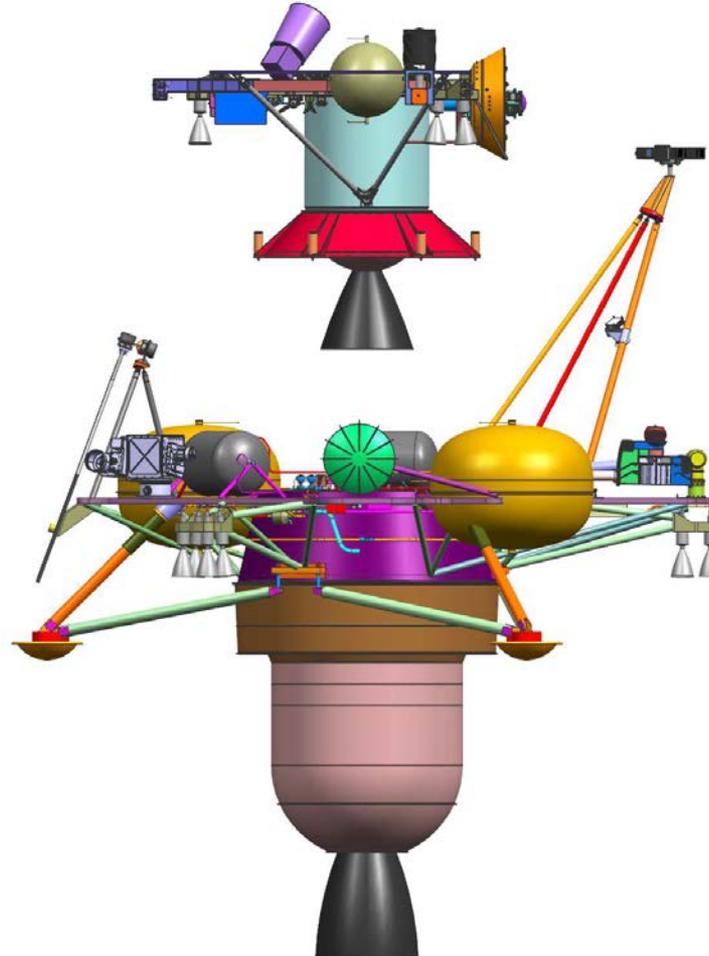
| MoonRise 2010   | Implementation Approach   | Orion/MoonRise Lander   |
|---|---|---|
|  | <p><u>Com Sat</u></p> <p><u>LAV &amp; SRC</u></p> <p><u>LSM</u></p> <p><u>LBM</u></p> | <p>Orion</p>   |

# Orion/MoonRise: modified SRV

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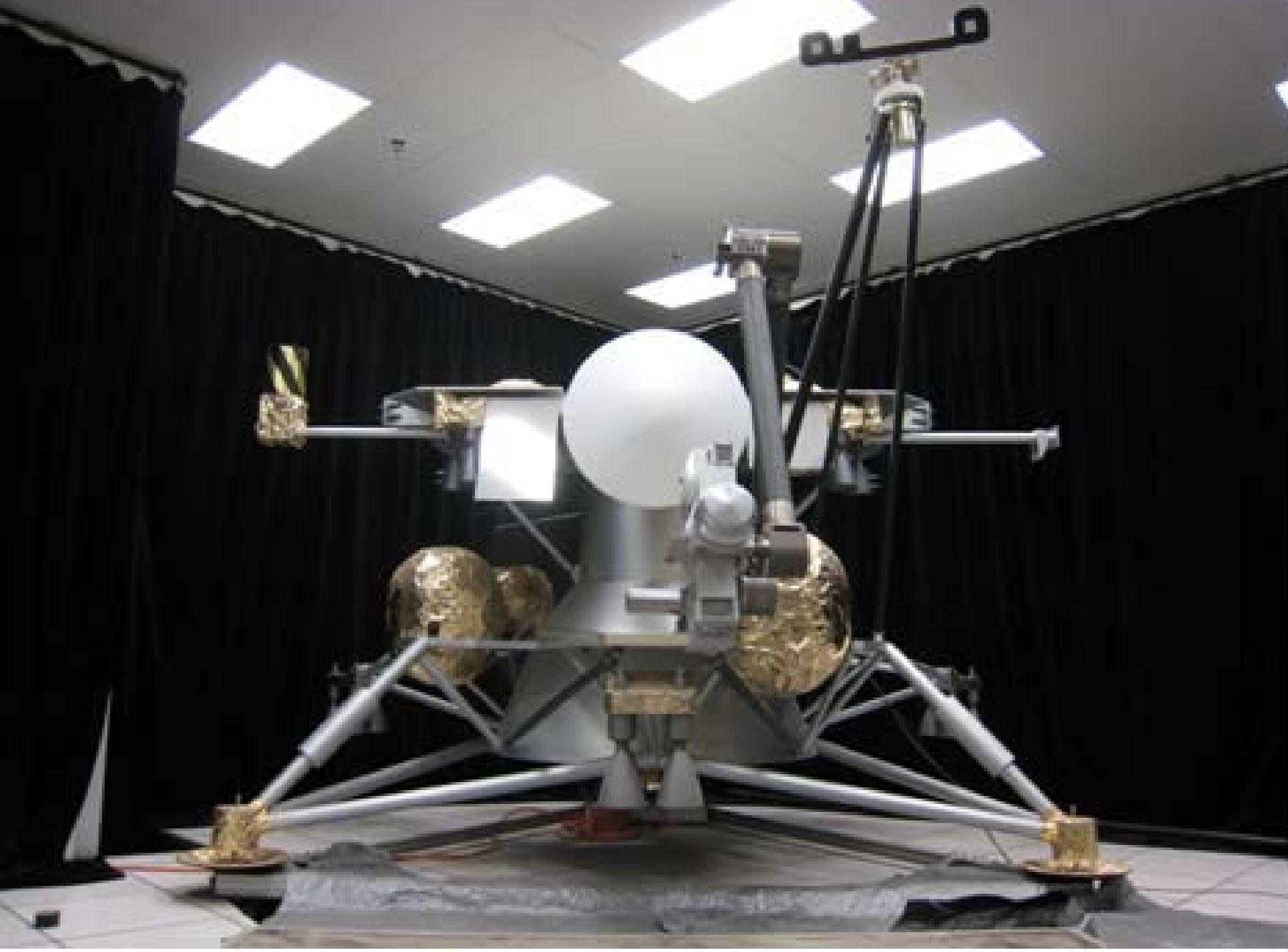
2x ATK/PSI 80512 Tanks  
49 kg  $N_2H_4$   
Off-the-shelf

2x ATK/PSI 80407 Tanks  
462 kg  $N_2H_4$   
Off-the-shelf

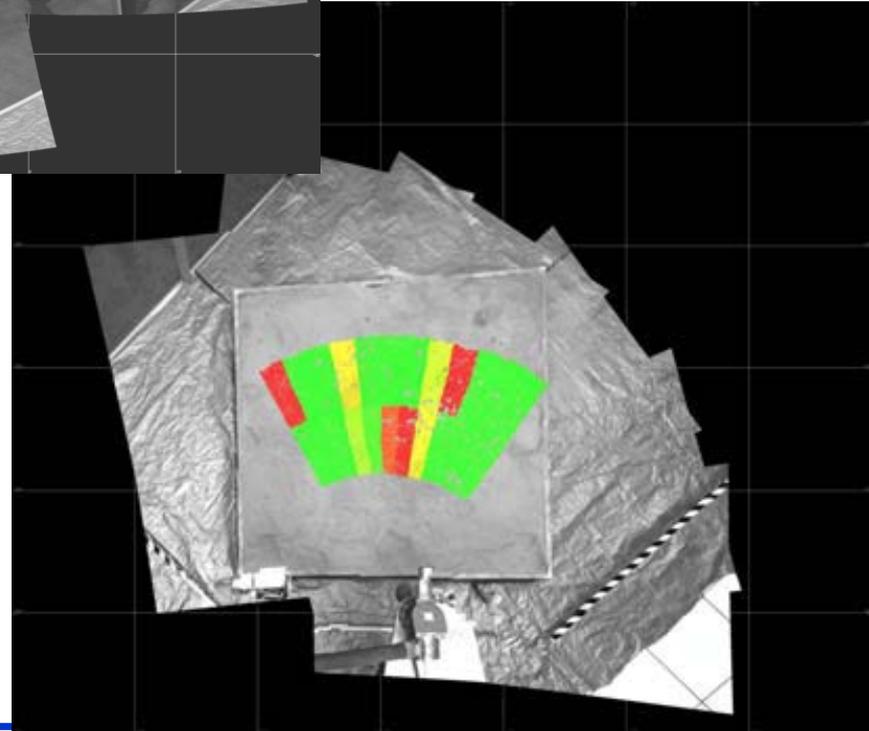


STAR 30 C/BP  
Fully loaded  
Off-the-shelf

STAR 48AX 7.5%  
uploaded vs  
MoonRise 2010

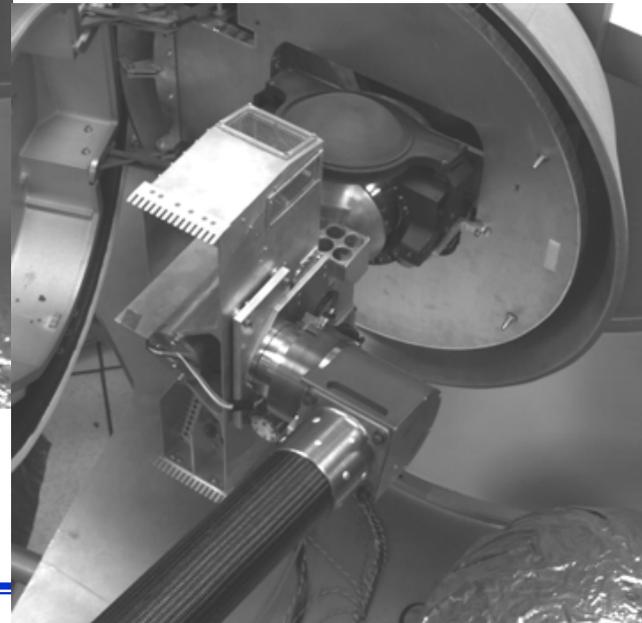
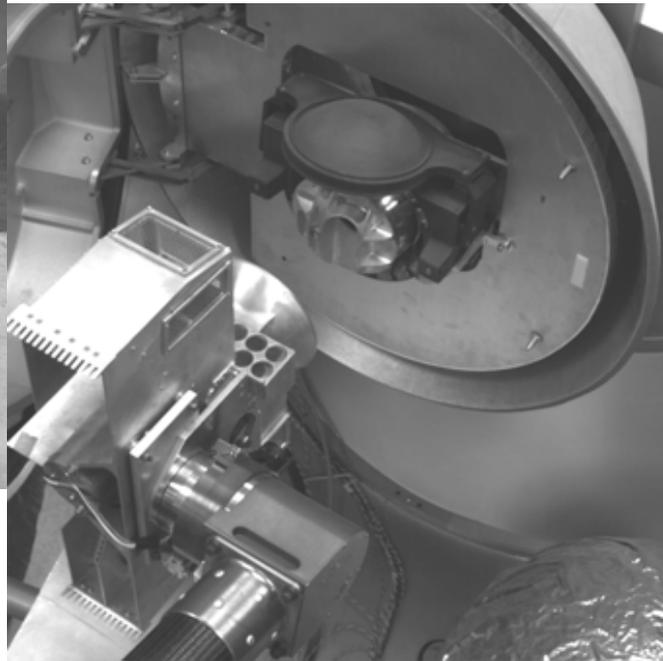
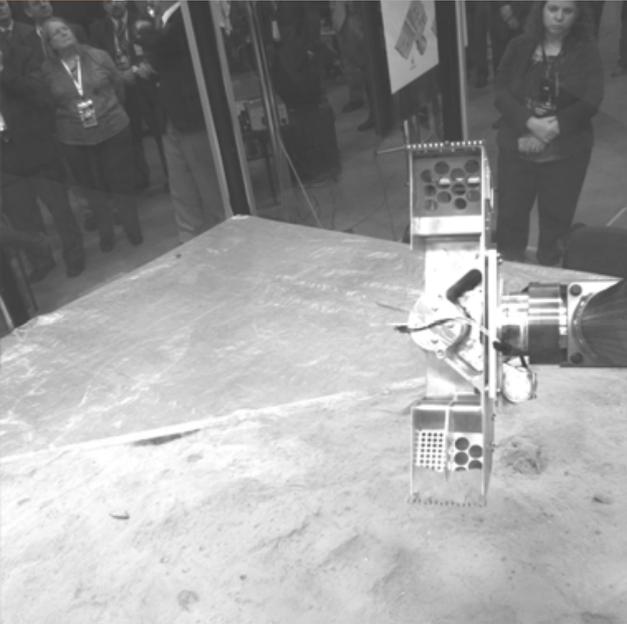


# MoonRise Lander: Workspace characterization



# MoonRise Lander: Sample Acquisition and Transfer System

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11/1/2012

# Orion/MoonRise Mission Design: *SRV Staging at EM-L1, Ascent to EM-L2*

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## Scenario

- ❑ Launch well before humans; take a low-energy transfer to the Moon; pass through the EM-L2 vicinity and arrive at a halo orbit about EM-L1.
- ❑ Remain at EM-L1 until humans launch; then proceed with descent to surface.
- ❑ Land via shallow flight path angle; remain on the surface for up to 10 days.
- ❑ Ascend via a high flight path angle on a direct return path to the EM-L2 orbits where humans will be stationed.
- ❑ Humans then rendezvous and pick up samples at EM-L2 for return to Earth.

## Comments

- ❑ This option is almost identical to the MoonRise New Frontiers Proposal.
-

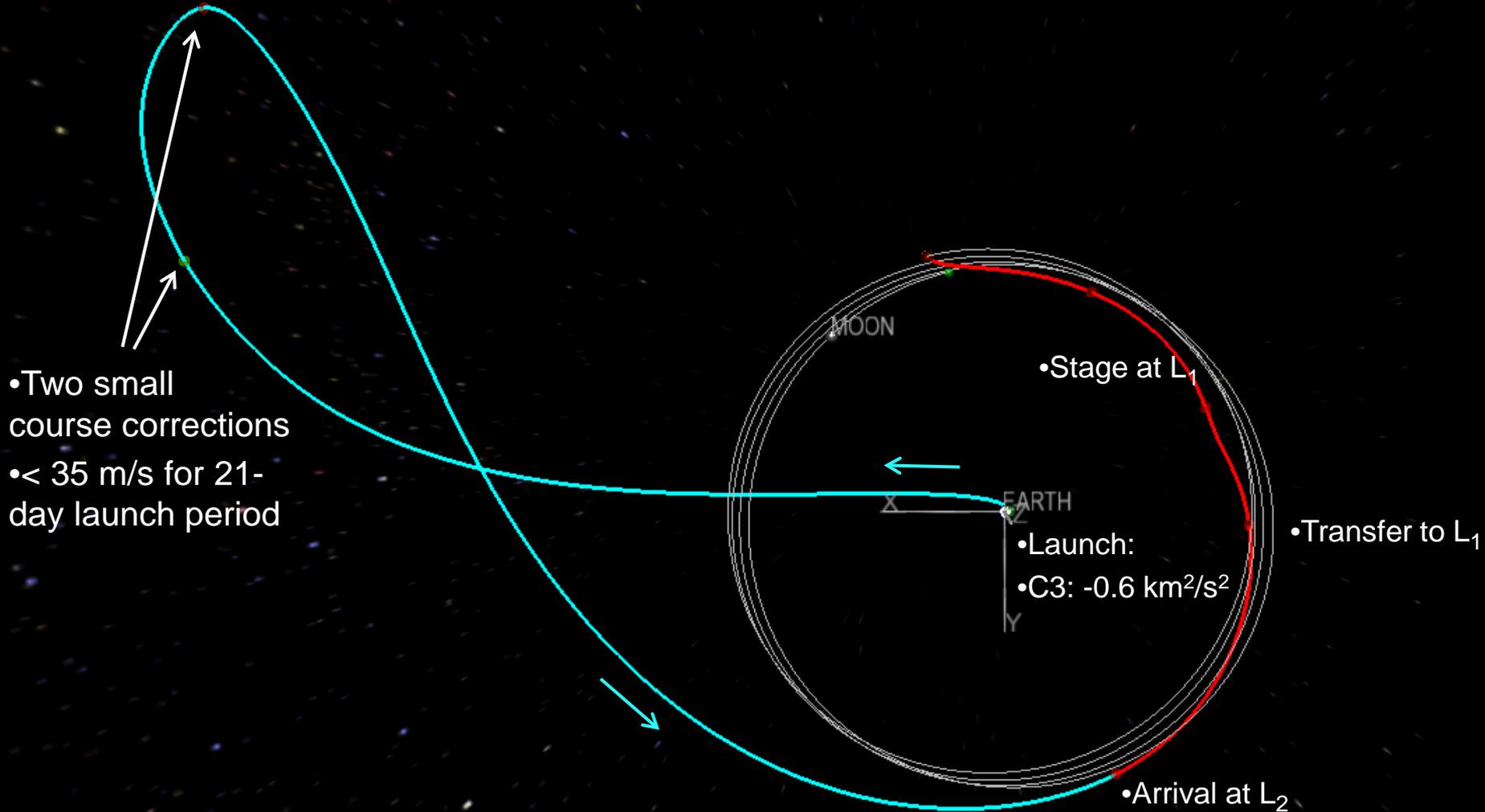
# SAMPLE RETURN VEHICLE: LAUNCH, TLC

11/1/2012

LEAG 2012: Orion/MoonRise

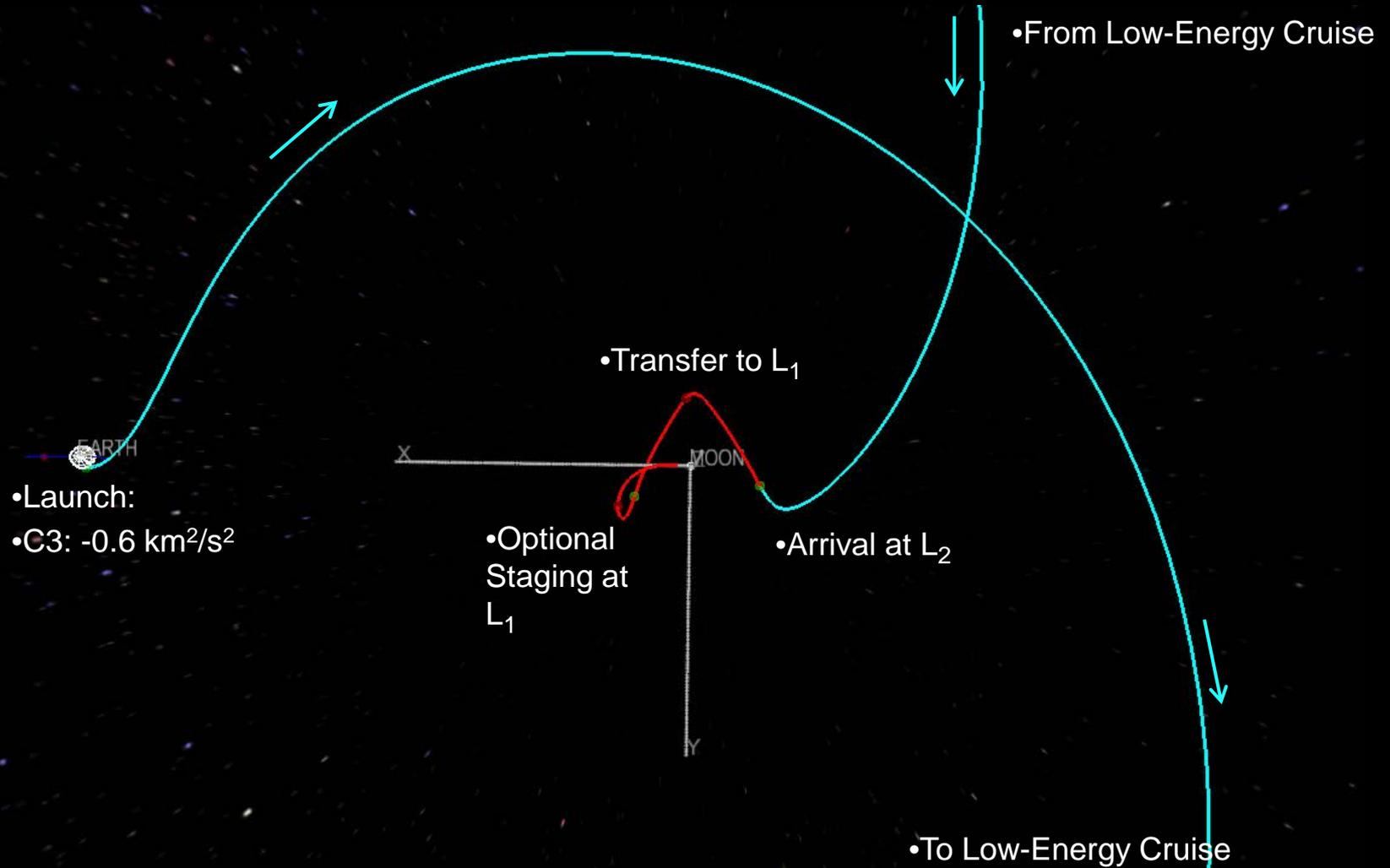
- 3 month low-energy transfer to the Moon
- Staging at  $L_1$  or  $L_2$
- 7.5 day descent, which may begin before humans arrive at  $L_2$
- 10.6 days on the surface
- 4.5 day ascent from surface to halo

- Human MoonRise Mission
- Sun-Earth Rotating Frame
- Viewed from Above



- 3 month low-energy transfer to the Moon
- Staging at  $L_1$  or  $L_2$
- 7.5 day descent, which may begin before humans arrive at  $L_2$

- Human MoonRise Mission
- Earth-Moon Rotating Frame
- Viewed from Above



- 3 month low-energy transfer to the Moon
- Staging at  $L_1$  or  $L_2$
- 7.5 day descent, which may begin before humans arrive at  $L_2$

- Human MoonRise Mission
- Earth-Moon Rotating Frame
- Viewed from Above

• Optional Staging at  $L_1$

• From Low-Energy Cruise

• Transfer to  $L_1$

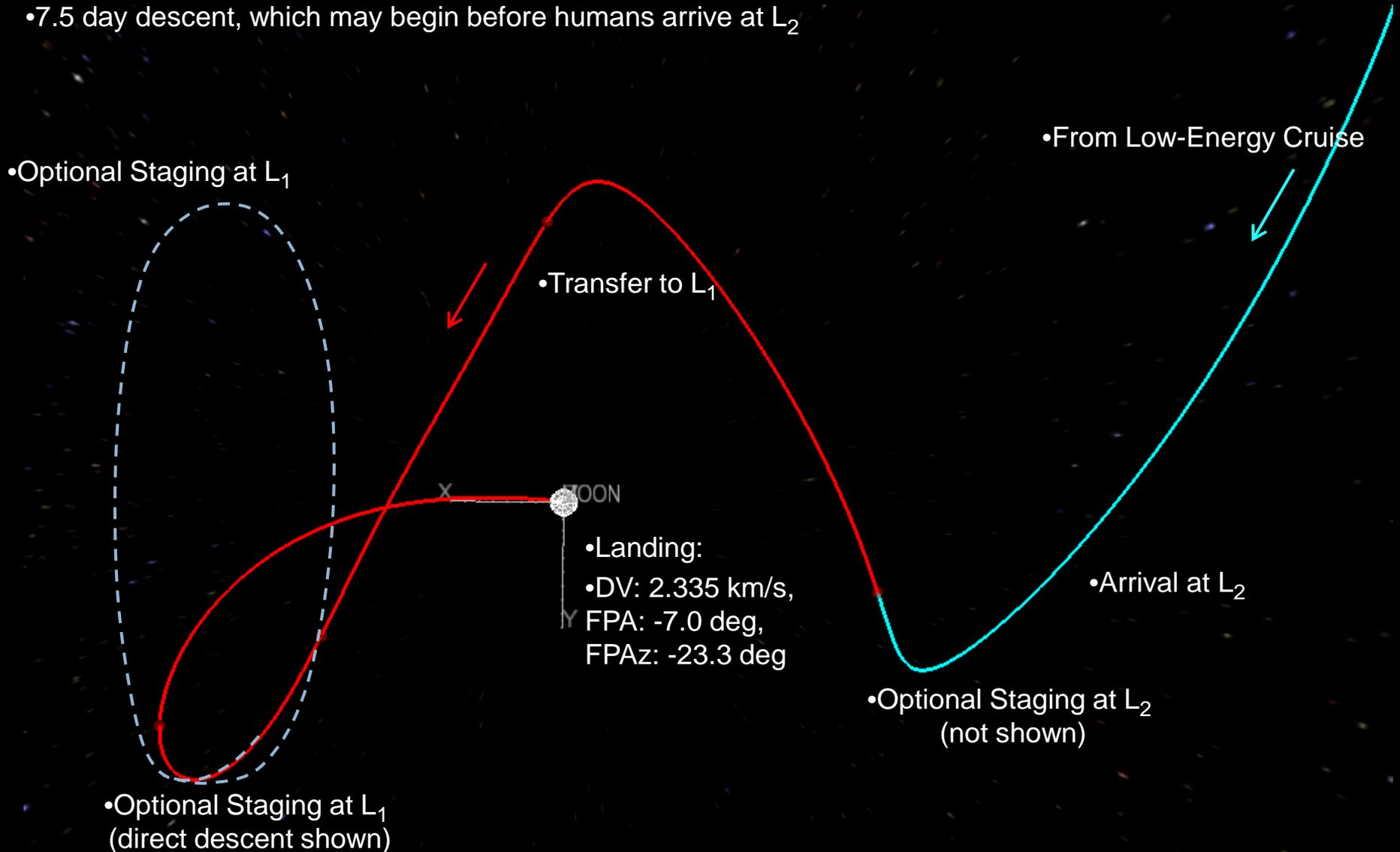
X MOON

- Landing:
- DV: 2.335 km/s,
- FPA: -7.0 deg,
- FPAz: -23.3 deg

• Arrival at  $L_2$

• Optional Staging at  $L_2$   
(not shown)

• Optional Staging at  $L_1$   
(direct descent shown)



# SAMPLE RETURN VEHICLE: DESCENT

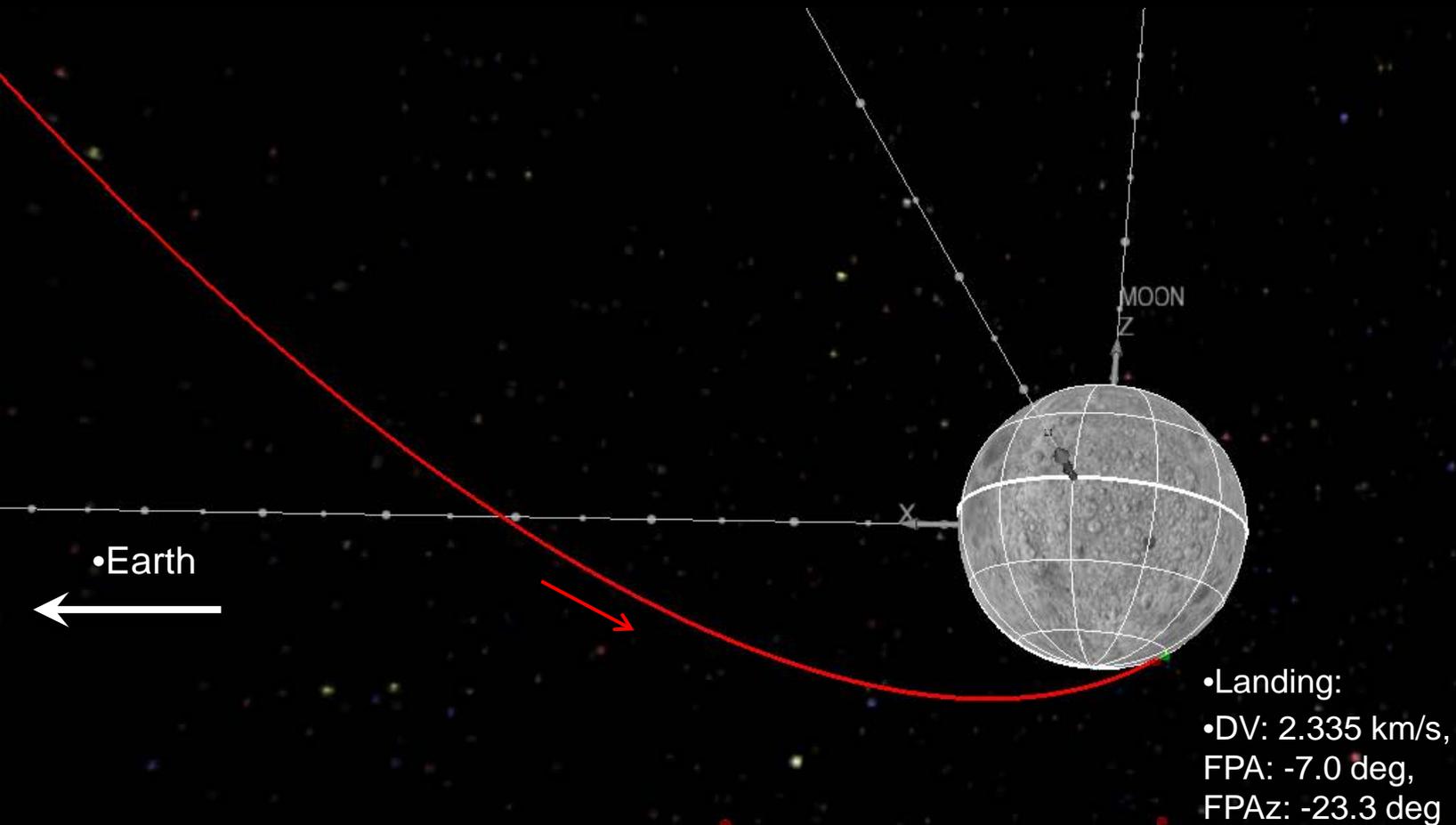
11/1/2012

LEAG 2012: Orion/MoonRise

- Human MoonRise Mission

- Moon-centered  
Viewed from the Side

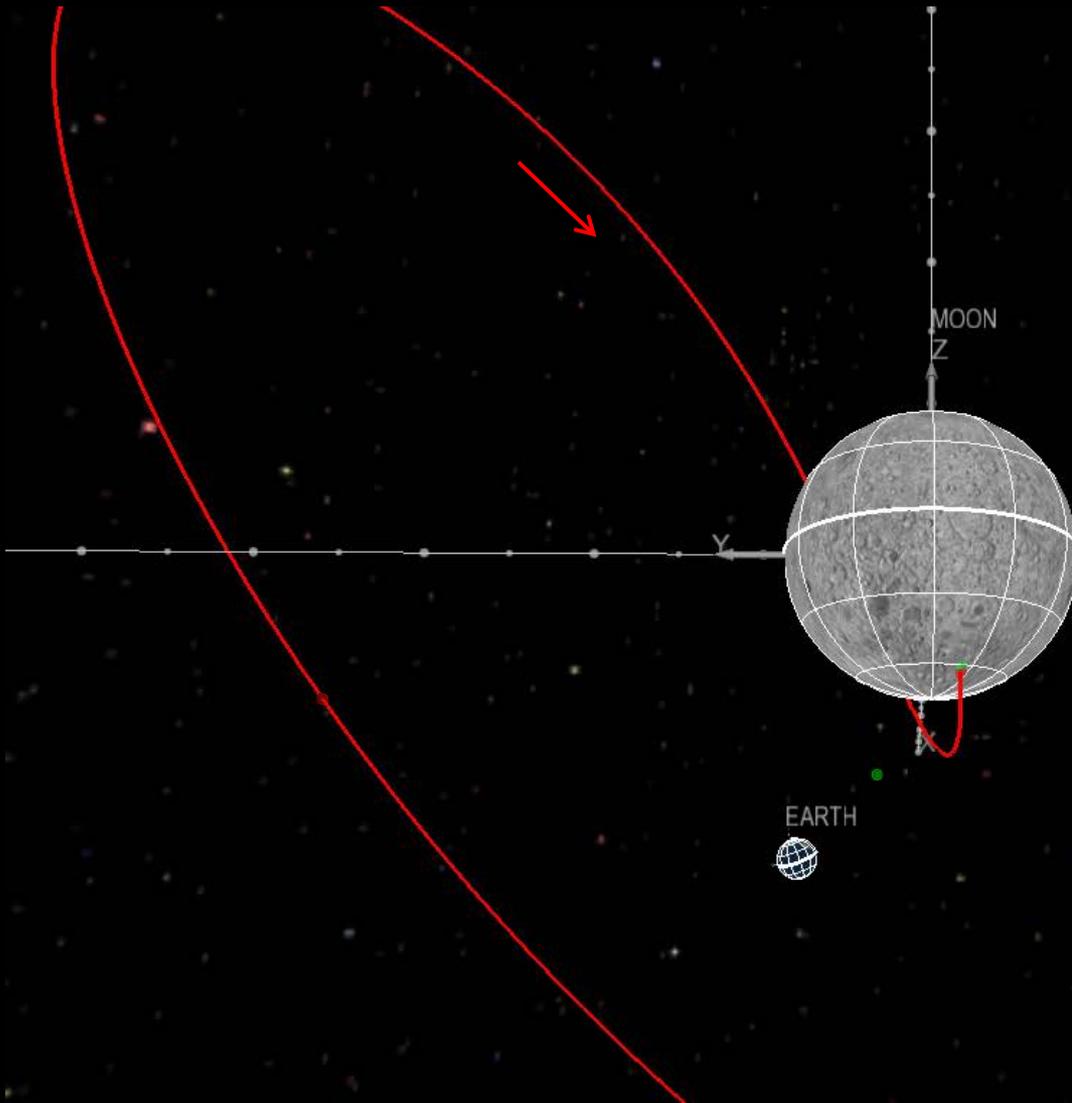
- 3 month low-energy transfer to the Moon
- Staging at  $L_1$  or  $L_2$
- 7.5 day descent, which may begin before humans arrive at  $L_2$



- Human MoonRise Mission

- Moon-centered  
Viewed from the Back

- 3 month low-energy transfer to the Moon
- Staging at  $L_1$  or  $L_2$
- 7.5 day descent, which may begin before humans arrive at  $L_2$



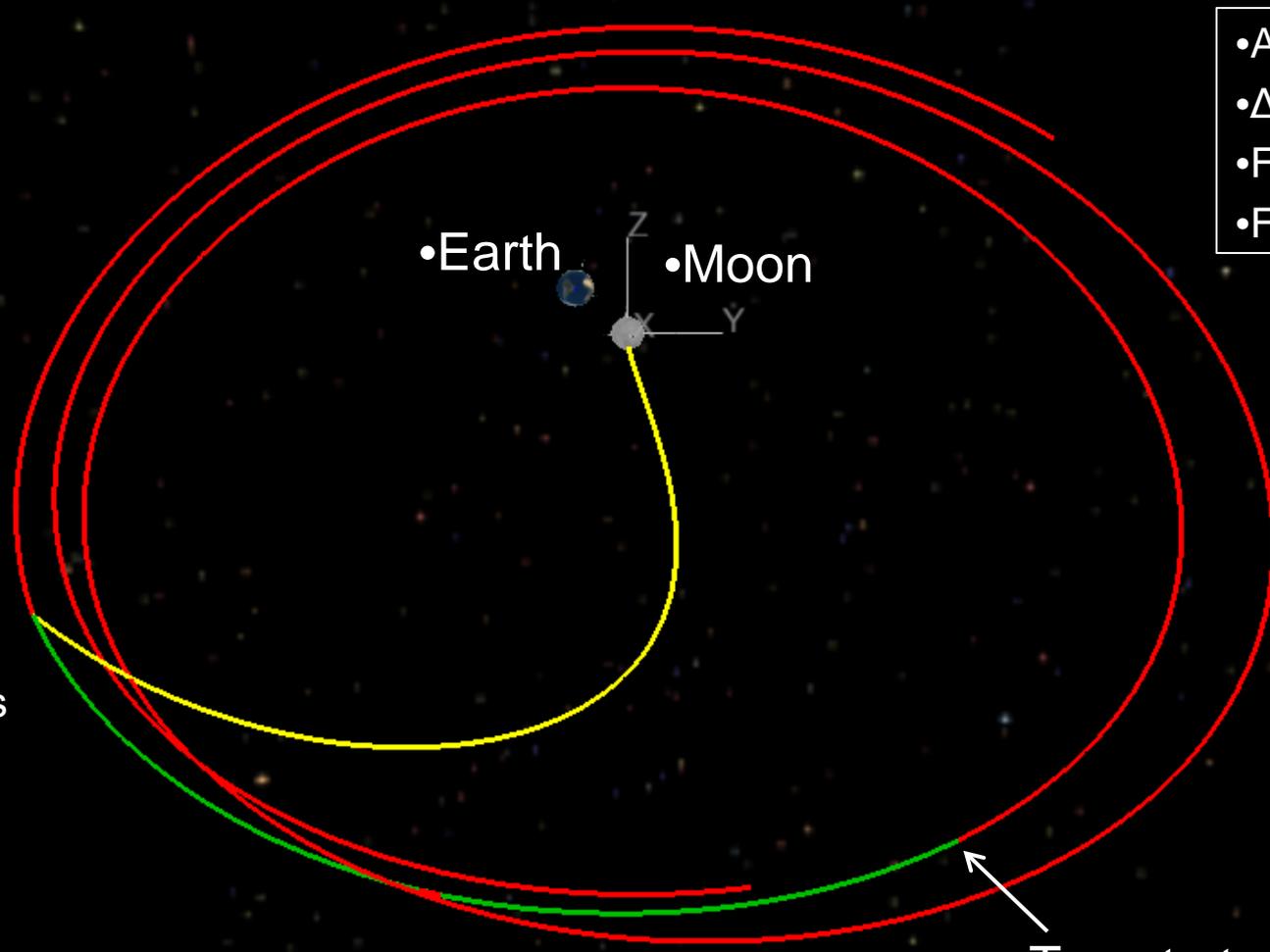
- Landing:
  - DV: 2.335 km/s,
  - FPA: -7.0 deg,
  - FPAz: -23.3 deg

# LUNAR ASCENT VEHICLE: ASCENT

11/1/2012

LEAG 2012: Orion/MoonRise

•View from Behind Halo

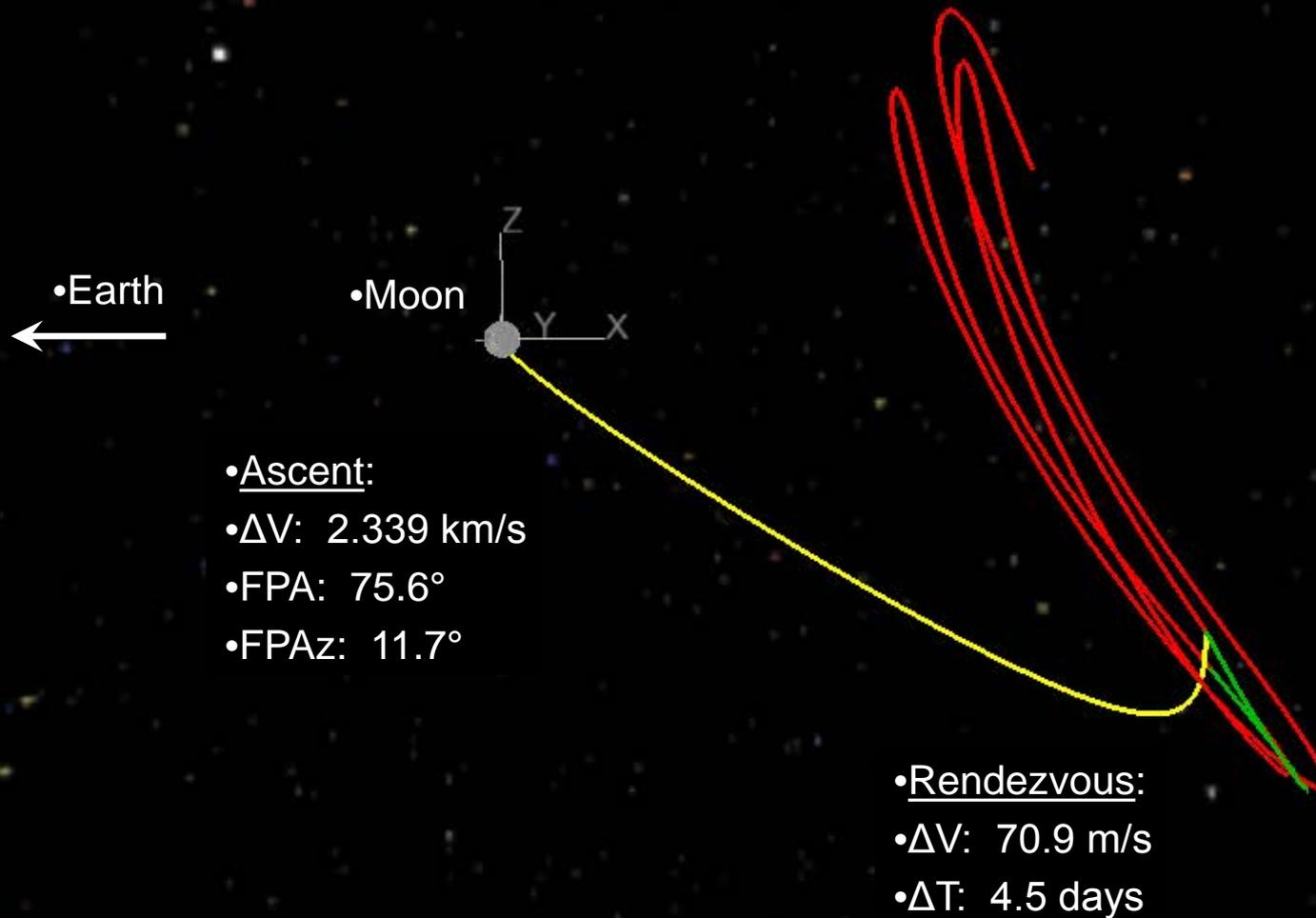


- Ascent:
- $\Delta V$ : 2.339 km/s
- FPA: 75.6°
- FPAz: 11.7°

- Rendezvous:
- $\Delta V$ : 70.9 m/s
- $\Delta T$ : 4.5 days

•Target at Ascent Time

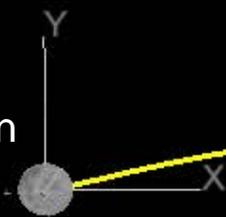
# •View from the Side



•View from Above

•Earth  
←

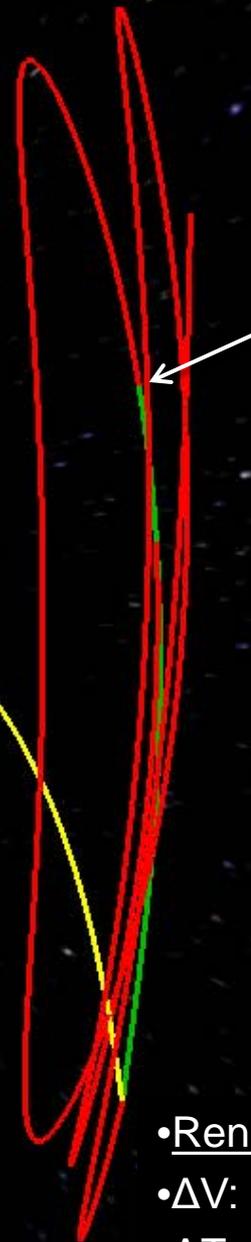
•Moon



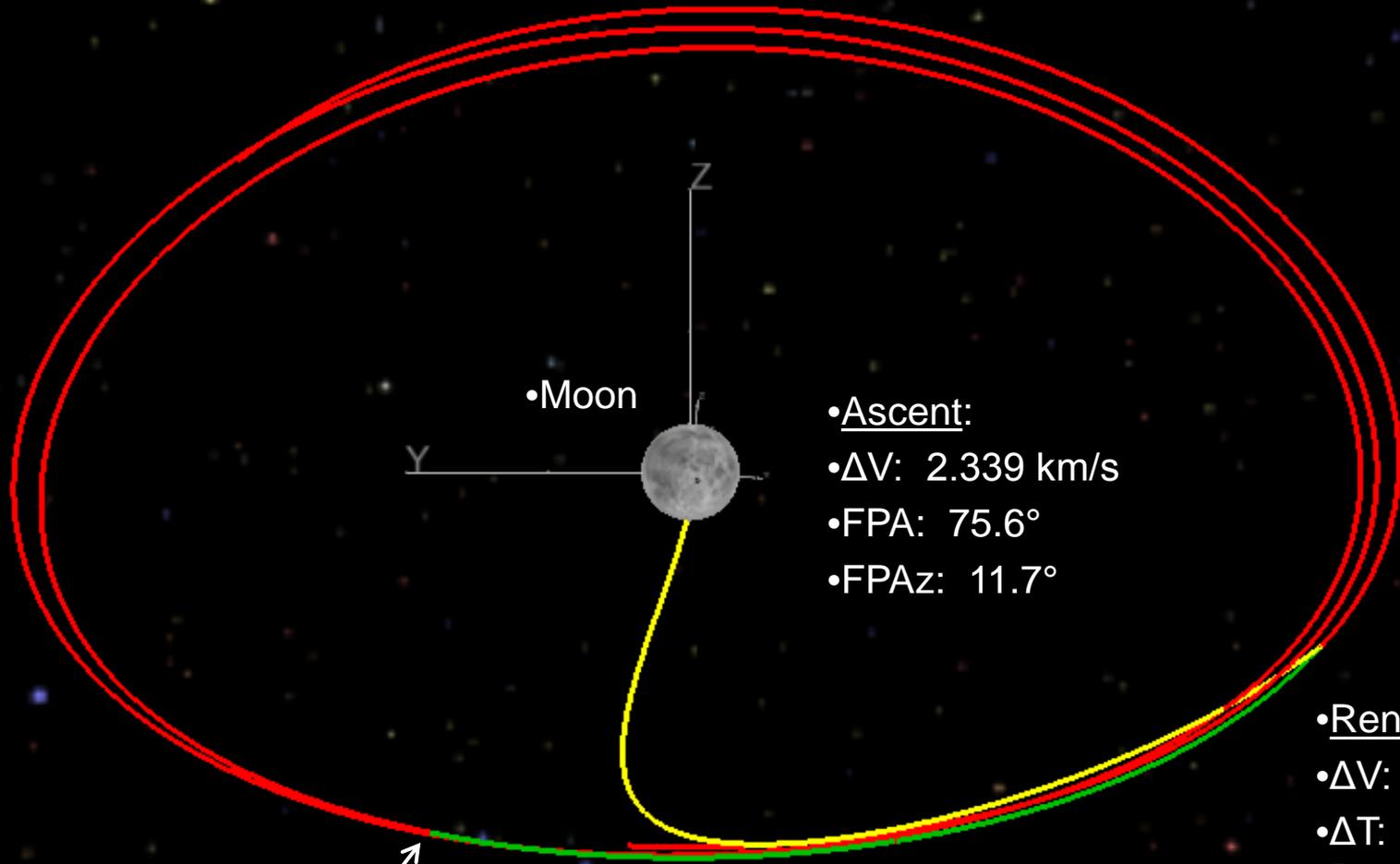
- Ascent:
- $\Delta V$ : 2.339 km/s
- FPA: 75.6°
- FPAz: 11.7°

•Target at  
Ascent Time

- Rendezvous:
- $\Delta V$ : 70.9 m/s
- $\Delta T$ : 4.5 days



- View from Earth



- Ascent:
- $\Delta V$ : 2.339 km/s
- FPA: 75.6°
- FPAz: 11.7°

- Rendezvous:
- $\Delta V$ : 70.9 m/s
- $\Delta T$ : 4.5 days

•Target at  
Ascent Time



# Orion/MoonRise delta-V: Staging at EM-L1 (descent); Ascent to EM-L2

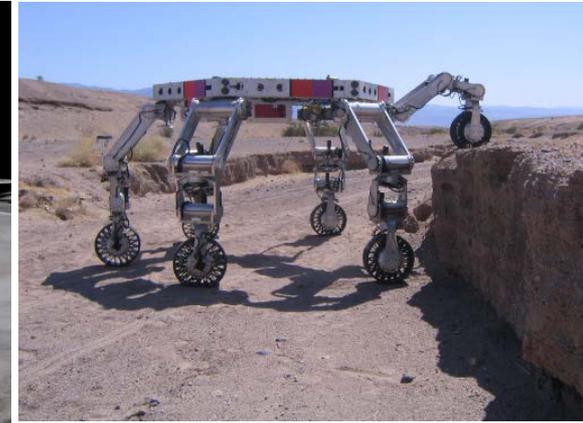


| Mission Phase             | Mission Element              | $\Delta V$ (m/s) | Comments   |
|---------------------------|------------------------------|------------------|--|
| <b>Trans-Lunar Cruise</b> |                              |                  |  |
|                           | Deterministic $\Delta V$     | 40               | May be less, but it's good to carry a little extra here.   |
|                           | Statistical                  | 20               | Added 12 m/s for a year of station keeping   |
|                           | ACS                          | -                | Propellant usage   |
|                           | L1 Departure, Targeting      | 48               | 1-2 Additional maneuvers (not fully studied). This could be small (20?) or maybe even a little higher (50?), but probably around 30. |
| <b>Landing</b>            |                              |                  |  |
|                           | BB SRM + attitude control    | 2232.34          | See MR Proposal  |
|                           | Velocity Cleanup             | 167.64           |  |
|                           | Terminal Descent and Landing | 172.48           |  |
|                           | Configuration Change         | -                | Leave lander, gain sample  |
| <b>Ascent</b>             |                              |                  |  |
|                           | Pop-up                       | 12.45            |  |
|                           | AB SRM + attitude control    | 2351             | We have a smaller velocity target than MR, so this is probably conservative.   |
|                           | Clean-up                     | 63.5             |  |
|                           | Rendezvous                   | 71               | This may be smaller for longer-duration ascents, or larger for smaller-duration ascents.   |
|                           | Statistical                  | 28               | Introduction of a rendezvous clean-up maneuver.  |
|                           | ACS                          | -                | Propellant usage   |
|                           | Margin                       | 50               | I would recommend a large Margin since we haven't fully explored everything. 50 seems okay.  |

# Orion/MoonRise Lander: Mobility Asset & Sample collection

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- The MoonRise arm provides a heritage design for the primary sample return
- AXEL rover is a scalable (20-50kg) tethered rover
- Tech demo that could provide samples from outside the landing zone
  - ▣ Pictures of the Lander and launch



## Science Return

- Returning ~10-40 kg of samples
- Examine a unique record of the early solar system
- Analysis of the preserved rock fragments in the South Pole-Aitken basin
- Sample return from this area has consistently been a priority of the Decadal Survey

## Technical Return

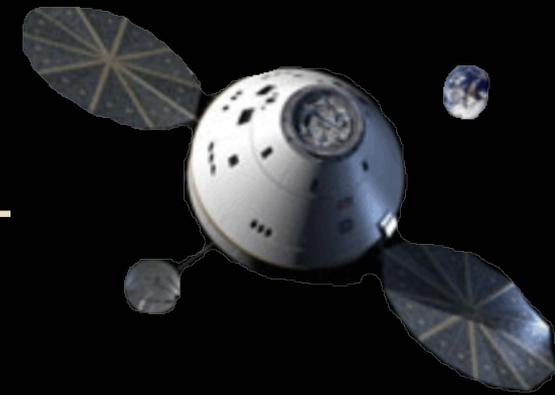
- Demonstration of human robotic sample return mission
- Demonstration of human robotic operations:
  - ▣ Feed forward to future Mars Missions
  - ▣ Critical relay coverage
  - ▣ Tele-robotics
- Demonstrates the flexibility of the EM-L2 as a destination, use of the Orion vehicle, surface assets
- Demonstration of Axel Mobility System

## Public Engagement

- Pictures of Lander and launch from the surface of the Moon
- Exciting demonstration of human robotic exploration
- Sample capture at EM-L2
- First samples from another planetary body since the 1970s
- First ever samples from the SPAB

- There is an integrated architecture that allows us to draw on our knowledge of planetary landers to demonstrate planetary sample return and human robotic interaction around a planetary body.
- Combining the Science return from a MoonRise style mission with the human assets provides a clear opportunity for significant technical and scientific return.
- Orion/MoonRise mission concept provides clear feed-forward to Mars sample return and Mars human exploration.

# ORION/MOONRISE: JOINT HUMAN-ROBOTIC LUNAR SAMPLE RETURN MISSION CONCEPT



Thank you for your attention.  
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# Executive Summary

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- Using the MoonRise approach with minor design modifications, retrievable rock sample mass can be significantly increased from 1 kg to **38 kg, and a micro-rover be deployed** using the human way-point scenario at L2.
    - Lander mass will increase over MoonRise 2010 by approx. 400 -500 kg depending on landing scenario, yet launch injected mass is still lower than MoonRise 2010 by 200-300 kg due to elimination of comsat and comsat adapter.
    - If 1 kg and no rover deployment goal of MoonRise 2010 is maintained, Orion/MoonRise lander mass will decrease or increase slightly over MoonRise 2010 lander mass depending on landing scenario due to higher delta-v requirements, offset by lighter SRC mass for the LAM. Launch injected mass will drop by 600-700 kg over MoonRise 2010.
  - Both Trans-L1 and L2-Direct mission scenarios are workable maintaining the MoonRise approach, with the L2-Direct landing scenario requiring higher terminal decent and landing delta-v resulting in higher S/C masses over the trans-L1 case by up to 100 kg depending on sample mass.
  - The L2-orbit landing scenario requires too high a liquid delta-v for orbit insertion and cannot be accommodated using the MoonRise approach.
  - Minor MoonRise design modifications are required to facilitate the Trans-L1 and L2-Direct landing scenarios:
    - Change from 3 MSL tanks on the LSM to 2 LCROSS tanks. Lower tank pressure rating reduces thruster feed pressure and Isp, taken into account. This affords approx. 50% propellant margin. Customized tank can reduce mass.
    - Stretch the MoonRise STAR 48AX design further by 7.4% (Trans-L1) and 12% (L2-Direct) to return 38 kg of lunar rock sample. Stretches can be reduced by reducing returned rock sample mass.
    - Use a fully loaded STAR 30 C/BP for ascent, rather than a 6% downloaded version for MoonRise to maximize rock sample return. A 1-kg sample return will allow for greater offload than for MoonRise 2010 due to lower SRC mass.
-